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Evaluation of Damping Loss Factor of Flat Laminates by Sound Transmission

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Abstract

A novel approach to investigate and evaluate the damping loss factor of a planar multilayered structure is presented. A statistical analysis reveals the connection between the damping properties of the structure and the transmission of sound through the thickness of its laterally infinite counterpart. The obtained expression for the panel loss factor involves all the derivatives of the transmission and reflection coefficients of the layered structure with respect each layer damping. The properties of the fluid for which the sound transmission is evaluated are chosen to fulfil the hypotheses on the basis of the statistical formulation. A transfer matrix approach is used to compute the required transmission and reflection coefficients, making it possible to deal with structures having arbitrary stratifications of different layers and also granting high efficiency in a wide frequency range. Comparison with alternative formulations and measurements demonstrates the effectiveness of the proposed methodology.

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1 1. Introduction

Passive damping treatments are widely used in engineering applications to reduce noise radiation, the amplitude of vibrations and the risk of fatigue failure. In particular, viscoelastic laminates have found application in many areas of structural acoustics due to the high damping levels that can be attained when the cross-sectional properties of the laminate are appropriately chosen. A key requirement for determining the optimal cross-sectional properties of a given laminate is an accurate model of its dynamics.

Typically, at low frequencies, a finite element (FE) model provides a good 9 description of the structural-acoustic behavior of the laminate. A Modal 10 Strain Energy (MSE) analysis on the FE model can provide the loss factor of 11 the structure in terms of the strain energy field of each mode [1]. At higher 12 frequencies, the wavelengths of interest become small with respect to the lat-13 eral dimensions of the laminate and then the FE approach becomes impracti-14 cal. Indeed, Statistical Energy Analysis (SEA) [2] is a more suitable method 15 for estimating the high-frequency responses of a structure under acoustic or 16 mechanical excitation. In order to model a subsystem in SEA, it is necessary 17 to determine the dispersion properties and the Damping Loss Factor (DLF) 18 of each propagating wave type of the subsystem. An approach for evaluating 19 the DLF of a structure is to simplify a real world component down to an 20 equivalent 3-layer beam or plate system. This was first suggested by Ross, 21 Kerwin, Ungar (RKU) [3, 4, 5], involving a fourth order differential equation

for a uniform beam under free-wave propagation with the sandwich construc-23 tion of the 3-layer laminate system represented as an equivalent, frequency 24 dependent, complex stiffness. Several authors have described extensions to 25 RKU analysis by involving different displacement fields to characterize the 26 response of more general laminates [6, 7]. Typically, the assumption of a 27 low-order displacement field is required in order to reduce analytical com-28 plexity. While simplified analytical models can provide physical insights 29 into the behavior of certain laminates, the assumed displacement fields can 30 often restrict the types of laminates that can be modeled. Numerical meth-31 ods to investigate the damping of laminated panels have been developed by 32 several authors [8, 9, 10, 11, 12, 13]. By exploiting a plane wave expansion, 33 the power dissipated by an isotropic poroelastic media within semi-infinite 34 multilayered systems under arbitrary excitation has also been assessed [14]. 35 The loss factor of more general laminates can be explored by involving a one-36 dimensional FE mesh to describe the cross sectional deformation of a linear 37 viscoelastic laminate, also including a three-dimensional displacement field 38 within the laminate [15]. However, the model is computationally expensive 39 due to the inversion of large matrices as a result of an increasing number of 40 elements in the cross sectional thickness. Regardless of the model adopted 41 to describe the cross sectional deformation, a dispersion problem must be 42 solved by determining, at a specific frequency, ω , and for a specific direction 43 of propagation, a finite number of complex wavenumbers, k, related to the 44 free waves traveling in the structure. The solution of the dispersion prob-45 lem at discrete frequencies for a specific direction of propagation leads to a $k - \omega$ dispersion diagram where dispersion curves must be identified. Then,

the damping loss factor, η_i , for the *i*-th curve can be evaluated by means of 48 the related eigenvectors. However, the number of curves and their intersec-49 tions rapidly grow with the frequency, making it more difficult to identify 50 the curves. An alternative approach is to use an exact description of the 51 through-thickness deformation of a laminate by means of a Transfer Matrix 52 Method (TMM) [16]. The characteristic equation that describes free-wave 53 propagation in a laminate can take the form of a nonlinear transcendental 54 eigenvalue problem [17]. However, the computational burden and robustness 55 of the root-tracking algorithms employed to determine dispersion solutions 56 limit the usefulness of the approach. 57

The scope of this work consists in defining the DLF of a planar structure, 58 averaged among all dispersion curves, by avoiding both the solution of the 59 dispersion problem and the modal approach. We are avoiding the solution of 60 a dispersion problem because i) identify dispersion curves at high frequency 61 could be prohibitive and ii) take into account the damping of all the prop-62 agating waves may be impractical. On the other hand, we are discarding 63 the modal approach because i) it could be computationally prohibitive even 64 at relatively low frequencies and ii) materials characterized by frequency de-65 pendent properties cannot be easily taken into account. A theory producing 66 the DLF of a multilayered planar structure and overcoming the limitations of 67 the above discussed approaches is proposed. A statistical analysis reveals the 68 connection between the damping properties of the structure and the trans-69 mission of sound through the thickness of its laterally infinite counterpart. 70 The incident diffuse acoustic field prescribed by the statistical approach to 71 evaluate the sound transmission ensures the excitation of all the propagating ⁷³ waves contributing to the damping of the medium, thus providing a mean
⁷⁴ loss factor for the structure. A TMM is used to evaluate the required trans⁷⁵ mission and reflection coefficients, making it possible to deal efficiently with
⁷⁶ structures having generic stratifications, possibly including in-plane periodic
⁷⁷ layers [18]. The wave approach on the basis of the TMM also avoids the
⁷⁸ need to set a specific kinematic model for the laminate, thus yielding high
⁷⁹ accuracy.

The DLF of a multilayered planar structure is derived in Section 2 by means of a statistical analysis on the sound transmission through the thickness of the structure. A number of applications are then discussed and compared with alternative formulations and measurements.

⁸⁴ 2. Layered Systems

Let us consider a layered structure in which the *i*-th layer is characterized by hysteretic damping through the loss factor $\eta_i(\omega)$. The time-averaged power dissipated by the *i*-th layer, Π_i , when the structure is subjected to harmonic excitation at angular frequency ω , can be expressed as [2]

$$\Pi_i = \omega E_i \eta_i , \qquad (1)$$

where E_i is the time-averaged total energy stored in the layer. The DLF of the layered structure, $\eta_s(\omega)$, concerns the overall time-averaged power dissipated by the structure, Π_{diss} , when a diffuse reverberant field exists within it, and can be expressed as [2]

$$\eta_s(\omega) = \frac{\Pi_{\text{diss}}}{\omega E_s} = \frac{\sum_{i=1}^N E_i \eta_i}{\sum_{i=1}^N E_i} , \qquad (2)$$

where the total dissipated power, Π_{diss} , is the sum of the power dissipated 93 by the N layers in the medium, and the total panel energy, E_s , is the sum 94 of the energies in all layers. We propose to derive the total energy stored in 95 each layer of a planar structure, E_i , by means of the transmission and reflec-96 tion coefficients of the laterally infinite counterpart of the structure. Such a 97 purpose draws legitimacy from the idea that the phenomenon of sound trans-98 mission through the thickness of the structure hides and carries the very same 99 information as the dispersion problem for the medium. Such information are 100 exposed by means of a statistical analysis of the sound transmission through 101 the structure. The adopted statistical approach is here reliable at any fre-102 quency since an infinite extent is considered for the structure. 103

104 2.1. Statistical Approach

Sound transmission through the thickness of a planar structure can be 105 investigated by placing the structure between two rooms. In the context of 106 SEA, two energy paths can be identified between the rooms. The first one 107 links the rooms without involving the resonance of the interposed wall, and 108 depends only on the specific mass of the wall, the so-called non-resonant 109 path. A second path treats the interposed structure as a subsystem, so 110 involving its strain energy, the so-called reverberant path. The non-resonant 111 path is therefore neglected in the following since it is not sensitive to the 112 panel properties we are looking for, *i.e.* the energy field within the panel. 113 The conditions under which such a choice may be effective are investigated 114 afterwards (Section 2.2). 115

116

Focusing on the reverberant path, the power balance of a panel perturbed

 $_{117}~$ by incident acoustic power, $\Pi_{\rm inc},$ can be expressed as

$$\Pi_{\rm tra}(\omega,\eta_1,\ldots,\eta_N) + \Pi_{\rm ref}(\omega,\eta_1,\ldots,\eta_N) + \sum_{i=1}^N \Pi_i(\omega,E_i,\eta_i) = \Pi_{\rm inc} , \qquad (3)$$

where the transmitted power, Π_{tra} , and the reflected power, Π_{ref} , depend on the damping of all layers. Therefore, the power balance for the panel, Eq. (3), can be written in normalized form:

$$\tau_d(\omega,\eta) + r_d(\omega,\eta) + \frac{\omega}{\prod_{\text{inc}}} \sum_{i=1}^N E_i \eta_i = 1 , \qquad (4)$$

where $\tau_d = \Pi_{\text{tra}}/\Pi_{\text{inc}}$ is the power transmission factor, $r_d = \Pi_{\text{ref}}/\Pi_{\text{inc}}$ is the 121 power reflection factor and vector η collects the damping factors. In the 122 following analysis each layer energy, E_i , is evaluated assuming a laminate 123 with null damping. In other words, the dynamics of the structure is evaluated 124 by employing the kinematics related to the undamped counterpart of the 125 structure. This assumption implies that the cross sectional displacement field 126 of a given propagating wave is not significantly sensitive to the damping. It 127 should be noted that this assumption is implicit in previous studies which 128 assume a fixed displacement field for the cross section that is independent 129 of damping, e.g. RKU and MSE. Therefore, by linearizing Eq. (4) around 130 the undamped condition, $\eta = 0$, with respect to each layer damping, η_i , and 131 invoking the conservative power balance $(\tau_d|_{\eta=0} + r_d|_{\eta=0} = 1)$, we obtain the 132 following set of N uncoupled equations: 133

$$\delta \eta_i \left[\frac{\partial \tau_d}{\partial \eta_i} + \frac{\partial r_d}{\partial \eta_i} + \frac{\omega}{\Pi_{\text{inc}}} \left(E_i + \sum_{j=1}^N \frac{\partial E_j}{\partial \eta_i} \eta_j \right) \right]_{\eta=\mathbf{0}} = 0 .$$
 (5)

¹³⁴ Since Eq. (5) has to hold for any arbitrary damping perturbation, $\delta \eta_i$, the

 $_{135}$ desired expression for the energy of the *i*-th layer of the panel is obtained:

$$E_i = -\frac{\Pi_{\rm inc}}{\omega} \left(\frac{\partial \tau_d}{\partial \eta_i} + \frac{\partial r_d}{\partial \eta_i} \right)_{\eta=\mathbf{0}} . \tag{6}$$

¹³⁶ Finally, the expression for the ensemble average DLF, Eq. (2), becomes

$$\eta_s = \frac{\sum_{i=1}^N F_i \eta_i}{\sum_{i=1}^N F_i} , \qquad (7)$$

137 where

$$F_i = \left(\frac{\partial \tau_d}{\partial \eta_i} + \frac{\partial r_d}{\partial \eta_i}\right)_{\eta=\mathbf{0}} \tag{8}$$

¹³⁸ is the frequency dependent *loss function* for the *i*-th layer.

139 2.2. Weak coupling and non-resonant path

The expression for the ensemble average DLF, Eq. (7), is derived under 140 i) the hypothesis of negligibility of the non-resonant path in the power trans-141 mission and ii) the SEA hypothesis concerning the weak coupling between 142 subsystems [19] $(\eta_{ij} \ll \min(\eta_i, \eta_j))$. The only way to fulfil these hypothe-143 ses is to properly choose the properties of the fluid for which the sound 144 transmission is evaluated. In particular, the non-resonant path in the sound 145 transmission is related to the mass-law contribution, which is predominant 146 below the acoustic coincidence. Moreover, a strong coupling between the two 147 semi-infinite fluids (rooms) is due to coincidence phenomena. As a result, 148 moving the coincidence region to low frequencies, well below the frequency 149 range of interest, ensures both a negligibility of the non-resonant contribu-150 tion to the sound transmission and a weak coupling between the rooms. To 151 this end, the speed of sound, c, must be small enough to fulfil the above 152 discussed hypotheses at the minimum frequency at which the DLF is de-153 sired. Additionally, it can be observed that for a diffuse field at a given 154

frequency, ω , the modulus of the projection of the incident wave on the interface, $k_t = \sqrt{k_x^2 + k_y^2} = \omega \sin(\theta)/c$, where θ defines the wave elevation, spans as $0 \le k_t < \omega/c$. As a consequence, the speed of sound, c, must be set as small as possible to ensure the excitation of all the propagating waves contributing to the energy field within the medium. Moreover, the limit of the mechanical impedance of a thin plate can be expressed in terms of its mass per unit area, m, and flexural rigidity, B, as [16]

$$\lim_{c \to 0} Z_p = j\omega \lim_{c \to 0} \left(m - \frac{Bk_t^4}{\omega^2} \right) = -j\omega^3 B \frac{\sin^4(\theta)}{c^4} , \qquad (9)$$

where the panel mass and, consequently, the non-resonant contribution disappear. Instead, the choice of the fluid density, ρ , is less critical. In fact, a low speed of sound of the surrounding fluid yields to $Z = \rho c \ll Z_p$, so granting a weak coupling between the structure and the fluid and, consequently, between the rooms, regardless of the chosen density, ρ . The expression for the loss functions, Eq. (8), can therefore be modified as

$$F_i(\omega) = \lim_{c \to 0} \left(\frac{\partial \tau_d(\omega, \rho, c)}{\partial \eta_i} + \frac{\partial r_d(\omega, \rho, c)}{\partial \eta_i} \right)_{\eta = \mathbf{0}} \quad \forall \rho \in \mathbb{R}^+ , \qquad (10)$$

where the limit ensures fulfilment of the hypotheses involved to derive Eq. (7)
in the frequency range of interest.

2.3. Evaluation of the transmission and reflection coefficients

The diffuse transmission factor, τ_d , and reflection factor, r_d , can be defined by expressing the diffuse acoustic field in the reverberant room as a combination of plane waves traveling in all the possible directions [16]. At a given frequency, ω , each plane wave impinging upon the flat structure is defined by its amplitude, I, azimuth, α , and elevation, $\pi/2 - \theta$. Both a transmitted wave and a reflected wave therefore propagate from the medium and their amplitudes, T and R, depend on the properties of the barrier. Assuming a complete $(0 \le \theta \le \pi/2, 0 \le \alpha < 2\pi)$ and unitary $(I = 1 \forall \theta, \alpha)$ diffuse field, the classical expressions for the power transmission and reflection factors [16] can be simplified as

$$\tau_d(\omega) = \frac{1}{\pi} \int_0^{2\pi} \int_0^{\pi/2} |T(\omega, \theta, \alpha)|^2 \cos(\theta) \sin(\theta) d\theta d\alpha , \qquad (11)$$

181 and

$$r_d(\omega) = \frac{1}{\pi} \int_0^{2\pi} \int_0^{\pi/2} |R(\omega, \theta, \alpha)|^2 \cos(\theta) \sin(\theta) d\theta d\alpha .$$
(12)

A practical and efficient tool for evaluating the transmission and reflec-182 tion coefficients, T and R, of planar, stratified media is the TMM. This 183 approach easily allows for multilayers made from a combination of elastic, 184 porous and fluid layers. It assumes the multilayer of infinite extent and uses 185 a representation of plane wave propagation in different media in terms of 186 transfer matrices. The transfer matrix of a layered medium is obtained from 187 the transfer matrices of individual layers by imposing continuity conditions 188 at interfaces. Enforcing the impedance condition of the surrounding fluid, at 189 both the excitation and the termination sides, allows calculation of the trans-190 mission coefficient, T, and the reflection coefficient, R. This methodology is 191 explained in detail in chapter 11 of Ref. [16]. In the frame of linear vibro-192 acoustics, the wave approach on the basis of the TMM provides accuracy and 193 efficiency in defining the sound transmission through planar structures with 194 infinite extent, flat interfaces and homogeneous layers. However, the last two 195 limitations can be overcome by involving a FE model for the periodic unit 196 cell of each heterogeneous layer [18]. 197

Even though the TMM is exact from a mathematical point of view, some 198 researchers found divergences in its results for high frequencies and/or large 199 layer thicknesses. The reason of this divergence has been ascribed to a bad 200 numerical evaluation of the involved exponential terms because of the finite 201 arithmetic. An alternative approach to determine the acoustic reflection 202 and transmission coefficients of multilayered panels which avoids exponential 203 terms is proposed in Ref. [20]. However, since no numerical issues were found 204 for the treated laminates in the frequency range explored, the standard TMM 205 [16] was used in the present work. 206

207 3. Validation Examples

The derivatives of the transmission and reflection coefficients required 208 to compute loss functions, F_i , are evaluated by means of finite differences. 209 A perturbing damping factor of 10^{-6} usually ensures satisfactory precision 210 and avoids numerical issues. As prescribed by Eq. (10), the speed of sound 211 of the fluid is reduced starting from a guess, c_0 , until every loss function, 212 $F_i,$ converges in the whole frequency range explored. A fluid density ρ = 213 $1.225 \ \rm kgm^{-3}$ is used for all applications. At fixed fluid conditions and for each 214 frequency of interest, ω_j , N+1 evaluations of the transmission and reflection 215 coefficients are needed to evaluate all the loss functions, $F_i(\omega_i, \rho, c)$, where 216 N is the number of layers. In case of structures characterized by symmetric 217 stacking, the number of required analyses can be reduced by exploiting the 218 symmetry of the sound transmission $(F_i = F_{N+1-i})$. 219

220 3.1. Damping of a sandwich panel with soft core

The first application involves a sandwich panel with a 1 mm-thick soft 221 core ($\rho = 1425 \text{ kgm}^{-3}$, E = 4.186 MPa, $\nu = 0.495$) and aluminum ($\rho = 2700$ 222 kgm^{-3} , E = 71 GPa, $\nu = 0.3$) 1 mm-thick skins. The configuration is typical 223 of the application of viscoelastic materials with constraint layer and enables 224 comparison of the present theory with the RKU method [3] for the evaluation 225 of damping of a three-layer structure. In the RKU method, the contribution 226 made by core damping to the total damping of the structure can be evaluated 227 by setting a unitary core damping and null skin damping. Figures 1 and 228 2 show the effects of the sound speed, c, and the damping perturbation 229 employed for the finite differences, $\delta\eta$, on the core loss function, $F_{\rm core}$, scaled 230 with respect to $F_s = 2F_{\rm skin} + F_{\rm core}$. A good degree of agreement can be 231 observed, in the frequency range explored, between the estimation acquired 232 from the RKU method and the result obtained by means of the proposed 233 methodology with $c = 25 \text{ ms}^{-1}$ and $\delta \eta = 10^{-6}$. Higher values of sound 234 speed prevent convergence at low frequencies, and a damping perturbation 235 lower than 10^{-6} can imply numerical issues, especially at low frequencies. 236 The value of sound speed which grants the convergence of the DLF at a 237 specific frequency depends on the stacking properties of the laminate since 238 it is related to coincidence phenomena. On the contrary, the discussion 239 about the damping perturbation, $\delta\eta$, has general validity. Therefore, all the 240 subsequent applications employ a damping perturbation $\delta \eta = 10^{-6}$. 241

242 3.2. Damping of a sandwich panel with honeycomb core

The second application involves a sandwich panel [10] made of aluminum ($\rho = 2700 \text{ kgm}^{-3}$, E = 71 GPa, $\nu = 0.3296$) with isotropic 0.6 mm-thick



Figure 1: Core contribution to the damping of a sandwich panel $(\delta\eta=10^{-6})$



Figure 2: Core contribution to the damping of a sandwich panel ($c = 25 \text{ ms}^{-1}$)

skins and a 15 mm-thick honeycomb core made of hexagonal cells with a foil 245 thickness of 0.0508 mm and a side length of 5.5 mm. The equivalent material 246 properties for the core are obtained by means of a homogenization technique 247 [21]. The DLF of the panel is computed according to Eq. (7) for a particular 248 distribution of damping through thickness. As proposed by Cotoni et al [10], 249 the internal damping loss factor of the core is kept constant at $\eta_{\rm core} = 2\%$ 250 while the damping of the skins takes on the values $\eta_{\text{skins}} = 1\%, 3\%, 5\%$. The 251 predicted loss factors are shown in Figure 3 as functions of frequency. A 252 speed of sound $c = 40 \text{ ms}^{-1}$ grants the convergence of the DLF in the whole 253 frequency range explored. The results according to Nilsson [22] are plotted as 254 a reference. They were obtained by substituting the undamped wavenumber 255 into the expression of the strain energy and taking the ratio of the imaginary 256 part over the real part. It can be seen that the damping loss factor depends 257 on which part of the composite undergoes the most deformation. At low fre-258 quencies, the wave motion is essentially governed by the extensional motion 259 of the skins, and the resulting loss factor is close to the skin loss factor. At 260 high frequencies, the shear of the core governs wave motion, and the damping 261 loss factor gets close to that of the core. This behavior is ruled by the *loss* 262 functions F_{skin} and F_{core} . 263

²⁶⁴ 3.3. Damping of laminates with multiple viscoelastic inclusions

The last application involves some of the specimens tested in [23]. The laminates considered are made of 0.5 mm-thick aluminum plates ($\rho = 2780$ kgm⁻³, E = 73.1 GPa, $\nu = 0.33$) separated by 0.31 mm-thick foils made of styrene butadiene rubber ($\rho = 1450$ kgm⁻³, $\nu = 0.49$). The identification of the viscoelastic properties of the rubber leads, in the frequency range



Figure 3: Loss factor of a sandwich panel with honeycomb core $(\eta_{\text{core}} = 2\%)$

100-2500 Hz, to the following approximations for the real part of the shear
modulus

$$\Re(G) = [2.1282 \log(f) - 5.5217] \text{ MPa},$$
 (13)

²⁷² and damping

$$\eta = [1.8487 \log(f) - 5.1500] \% . \tag{14}$$

The DLF measured for three different batches (#15, #9 and #10 with 2, 3 and 5 viscoelastic inclusions respectively [23]) are shown in Figures 4, 5 and 6 along with the results obtained with a *General Laminate* model [15], implemented in the ESI VAOne code to predict subsystem properties in the frame of an SEA, the results obtained in terms of MSE [1], and the results obtained with the proposed methodology (TMM). Comparisons are satisfactory among all methods, thus proving that boundary effects are negligible.



Figure 4: Damping of a laminate with 2 viscoelastic inclusions



Figure 5: Damping of a laminates with 3 viscoelastic inclusions



Figure 6: Damping of a laminates with 5 viscoelastic inclusions

4. Conclusions

A connection is identified between the sound transmission through the 281 thickness of a planar layered structure and its DLF. Complex dynamics in-282 volved in dissipative mechanisms are assessed by means of a statistical anal-283 ysis of the sound transmission. The exposed theory reveals the influence of 284 each layer on the ensemble average loss factor of a structure. A loss func-285 tion in the frequency domain is assigned to each layer, making it possible to 286 build the DLF of the whole structure once individual damping properties are 287 assigned to each layer. 288

Good agreement with respect to the RKU method was observed for a 289 three-layered structure in terms of the influence of the core damping on the 290 global damping of the structure. The effects of the speed of sound of the fluid 291 for which the sound transmission is evaluated and of the damping pertur-292 bation employed to evaluate the finite differences have also been addressed. 293 Results on a sandwich panel with honeycomb core highlight the role of loss 294 *functions* in defining the ensemble average loss factor of a layered structure. 295 The comparison with the DLF measured for some laminates with multiple 296 viscoelastic inclusions demonstrates the effectiveness of the proposed method-297 ology even at low-medium frequencies in the case of complex layouts. 298

²⁹⁹ Ultimately, the proposed methodology may represent a reliable tool for ³⁰⁰ investigating the DLF of a layered structure. In particular, the so-called ³⁰¹ loss functions may guide an optimization process for the stacking of a lay-³⁰² ered panel, *e.g.* when the optimal location of a damping material must be ³⁰³ determined. Moreover, the transfer matrix approach adopted for evaluating ³⁰⁴ the required transmission and reflection coefficients provides efficiency and 305 accuracy.

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