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Abstract

In this paper, a novel strategy to generate broad-band earthquake ground motions from the results of 3D physics-based numerical simulations (PBS) is presented. Physics-based simulated ground motions embody a rigorous seismic wave propagation model (i.e., including source-, path- and site- effects), which is however reliable only in the long period range (typically above 0.75 – 1 s), owing to the limitations posed both by computational constraints and by insufficient knowledge of the medium at short wavelengths. To cope with these limitations, the proposed approach makes use of Artificial Neural Networks (ANN), trained on a set of strong motion records, to predict the response spectral ordinates at short periods. The essence of the procedure is, first, to use the trained ANN to estimate the short period response spectral ordinates using as input the long period ones obtained by the PBS, and, then, to enrich the PBS time-histories at short periods by scaling iteratively their Fourier spectrum, with no phase change, until their response spectrum matches the ANN target spectrum. After several validation checks of the accuracy of the ANN predictions, the case study of the M6.0 Po Plain earthquake of May 29, 2012 is illustrated as a comprehensive example of application of the proposed procedure. The capability of the proposed approach to reproduce in a realistic way the engineering features of earthquake ground motion, including the peak values and their spatial correlation structure, is successfully proved.

Introduction

30
31 Earthquake ground motion prediction tools underwent a major development in the recent years,
32 mainly because of the increasing number of strong motion records, especially in the near-field of
33 important earthquakes. This contributed to expand research on ground motion prediction equations
34 (GMPEs), i.e., the empirical models providing peak values of ground motion across the entire
35 frequency band of engineering interest, as a function of magnitude, of suitable measures of source-
36 to-site distance and of site conditions.

37 Due to simplicity and to limited computational cost, GMPEs are among the most important
38 ingredients of seismic hazard assessment. However, despite their overall effectiveness and ease-
39 of-use, the practical application of GMPEs presents several important shortcomings: (i) they
40 provide only peak values of motion, whereas the use of non-linear time history analyses requiring
41 reliable input motions is becoming more and more relevant within many applications of
42 performance-based seismic design; (ii) although their number is continuously growing, the
43 available records to calibrate a GMPE are still too few to cover the variety of situations, in terms
44 of combinations of magnitude, distance, fault slip distribution, directivity, and shallow geological
45 condition, which may cause a significant variability of ground motions in terms of amplitude,
46 duration and frequency content; (iii) the data-driven calibration of GMPEs implies that the
47 empirical coefficients vary when calibration datasets are updated; (iv) GMPEs encompass generic
48 site conditions, represented for instance by means of the average shear velocity in the top 30
49 meters, V_{S30} , therefore neglecting the site-specific features, such as surface or buried topographies,
50 basin edges, irregular soil layering, which may critically change the features of ground motion
51 with respect to the generic site response; (v) the point-wise prediction by GMPEs cannot reproduce
52 the spatial correlation structure of the peak values of motion at multiple sites, strongly limiting

53 their use for seismic hazard and risk assessment study at regional scale, such as within large urban
54 areas. As a matter of fact, in such situations additional models describing the spatial correlation of
55 ground motion have to be applied to standard GMPEs (see e.g. Jayaram and Baker, 2009; Esposito
56 and Iervolino, 2012).

57 A variety of procedures was proposed in the past to improve the above limitations of GMPEs and
58 the accuracy of earthquake ground motion prediction (see Douglas and Aochi, 2008, for a
59 comprehensive review). Among such procedures, boosted by the ever increasing availability of
60 parallel high performance computing, 3D physics-based numerical simulations (PBSs) are
61 becoming one of the leading tools to obtain synthetic ground motion time histories, whose use for
62 seismic hazard and engineering applications is subject to growing attention and debate (see e.g.
63 Bradley *et al.*, 2017).

64 Being based on a more or less detailed spatial discretization of the continuum and on the numerical
65 integration of the seismic wave equation, carried out according to different methods (such as finite
66 differences, finite elements or spectral elements), PBSs require a sufficiently detailed model of the
67 seismic source, of the propagation path, and of the Earth crustal layers. To enjoy the effectiveness
68 of semi-analytical solutions of elastic wave propagation, the shallow Earth's structure is often
69 modelled as a system of horizontal layers (see e.g. Spudich and Xu, 2002; Hisada and Bielak,
70 2003). In this paper, we will refer only to those approaches where 3D numerical models of the
71 shallow geological layers can be considered.

72 Physics-based numerical modeling already proved in the recent past to be well suited for global
73 (Graves, 1996; Wald and Graves, 1998; Pitarka *et al.*, 1998; Komatitsch and Tromp, 2002a,b) and
74 regional scale simulations (Bao *et al.*, 1998; Olsen, 2000; Dumbser and Käser, 2006; Day *et al.*,
75 2008; Tsuda *et al.*, 2011; Smerzini and Villani, 2012; Taborda and Bielak, 2014; Villani *et al.*,

76 2014; Paolucci *et al.*, 2015; Chaljub *et al.*, 2015; Gatti *et al.*, 2017), making potentially feasible
77 the challenging problem of a multi-scale simulation from the seismic source to the structural
78 response within a single computational model (Mazzieri *et al.*, 2013; Isbilibiroglu *et al.*, 2015).
79 Typically, PBSs are based either on a kinematic description of the co-seismic slip distribution
80 model or on a spontaneous dynamic rupture process. Spatially correlated random field models of
81 slip function parameters (e.g., Herrero and Bernard, 1994; Mai and Beroza, 2003; Crempien and
82 Archuleta, 2015; Anderson, 2015) are often considered to provide a realistic level of complexity
83 of the generated seismic wavefield and enhance its frequency content within physical constraints
84 from seismological observations. However, even in the presence of an ideal seismic source model,
85 exciting the whole frequency spectrum, the accuracy of the PBS in the high-frequency range is
86 limited, on the one hand, by the increased computational burden as the mesh gets finer, and, on
87 the other hand, by the lack of detailed knowledge to construct a geological model with sufficient
88 details also at short wavelengths, especially for complex configurations. As a result, accuracy
89 achieved by PBS is usually bounded up to 1 – 1.5 Hz, although some examples of higher frequency
90 ranges covered by deterministic PBS, with good performance validations against records, have
91 also been published (e.g., Smerzini and Villani, 2012, modeling the M6.3 L’Aquila near-source
92 earthquake ground motion up to 2.5 Hz; Taborda and Bielak, 2014, modeling the M5.4 Chino Hills
93 earthquake up to 4 Hz, Maufroy *et al.*, 2015, simulating a sequence of small earthquakes in the
94 Volvi basin, Greece, up to 4 Hz).
95 Different recent research works have addressed the high-frequency limitation of PBS, such as in
96 the framework of the Southern California Earthquake Center (SCEC) Broadband Platform, aiming
97 to extend the frequency band of synthetics and to enable PBS to be used with confidence in
98 engineering applications (see Goulet *et al.*, 2015). Broad-band (BB) waveforms are generally

99 produced by a hybrid approach combining low-frequency results from deterministic PBS with
100 high-frequency signals from stochastic approaches, typically through either point- or finite-source
101 methods (e.g., Boore, 2003; Motazedian and Atkinson, 2005) or stochastic Green's function
102 methods (e.g., Kamae *et al.*, 1998; Mai *et al.*, 2010). Hybrid waveforms are then obtained by gluing
103 the low-frequency and high-frequency portions of the spectrum with amplitude and phase
104 matching algorithms (e.g., Mai and Beroza, 2003). Table 1 lists a sample of recently published
105 studies of BB earthquake ground motions based on coupling low-frequency 3D PBS with high-
106 frequency stochastic contributions.

107 Although it has been applied to many case studies worldwide, the hybrid approach may have some
108 basic drawbacks, which prevent its use especially for regional applications: (i) typically, the low
109 (from PBS) and high (from stochastic) frequency parts turn out to be poorly correlated, being
110 generated through independent methods with different assumptions regarding the source and the
111 propagation medium; (ii) the low and high frequency seismograms are combined around a cross-
112 over frequency f_c , where the corresponding Fourier spectra are multiplied by weighting functions
113 and summed up. Such operation may result in a Fourier spectrum of the hybrid broadband ground
114 motion presenting artificial holes around the cross-over frequency and, to overcome this issue,
115 may require a site-specific calibration of f_c (see e.g. Ameri *et al.*, 2012).

116 In this paper we propose a novel approach to generate BB ground motions, which couples the
117 results of PBS for a specific earthquake ground motion scenario with the predictions of an
118 Artificial Neural Network (ANN), overcoming some of the main issues of hybrid modeling. The
119 basic steps of the procedure can be summarized as follows: (1) the ANN is trained on a strong
120 motion dataset, to correlate short-period ($T \leq T^*$) spectral ordinates with the long period ones
121 ($T > T^*$), being T^* the threshold period beyond which results of the PBS are supposed to be accurate;

122 (2) the trained ANN is used to obtain the short period spectral ordinates of the physics-based
123 earthquake ground motion for periods below T^* (Figure 1); (3) the PBS long period time histories
124 are enriched at high frequencies with an iterative spectral matching approach, until the response
125 spectrum matches the short period part obtained by the ANN.

126 A detailed introduction of the procedure, denoted hereafter by ANN2BB, is given in the following
127 chapters, with an application example to the PBS obtained for the M_w 6.0 Po Plain earthquake of
128 May 29, 2012 (Paolucci *et al.*, 2015), for which a comprehensive validation exercise can be made,
129 based on more than 30 strong motion records obtained at less than 30 km epicentral distance. Such
130 validation aims at encompassing different key aspects to evaluate the applicability of physics-
131 based earthquake ground motion to engineering practice, not only in terms of the high-frequency
132 content and of the proper attenuation of peak values with distance, but also in terms of the
133 verification of the spatial correlation of peak ground motion values.

134 **Correlation of long and short period spectral ordinates through an ANN**

135 **trained on a strong motion dataset**

136 **Design and training of an ANN**

137 Artificial Neural Networks are generally used to estimate the non-linear relationship between a
138 highly populated vector of input variables and a vector of output unknowns, for the correlation of
139 which fast and closed-form rules cannot easily be applied. As a matter of fact, under mild
140 mathematical conditions, any problem involving a continuous mapping between vector spaces can
141 be approximated to arbitrary precision (i.e. within an error tolerance) by *feed-forward* ANNs which
142 is the most often used type (Cybenko, 1989). Our purpose is to establish through the ANN a
143 correlation between N_{Sa}^{LP} long period response spectral ordinates selected for $T \geq T^*$, being T^* the

144 threshold period corresponding to the range of validity of PBS, with N_{Sa}^{SP} short period response
 145 spectral ordinates for $T < T^*$. A high-quality strong ground motion dataset (denoted in the
 146 following by SIMBAD, see Smerzini *et al.*, 2014 for details) was used for training. SIMBAD
 147 consists of $N_{ab} \sim 500$ three components records from about 130 shallow crustal earthquakes
 148 worldwide, roughly homogeneously distributed in the M_W range from 5 to 7.3 and epicentral
 149 distance $R_{epi} < 35$ km. Quantitative information on site characterization, preferably in terms of
 150 V_{S30} , is available for all stations.

151 Two separate ANNs are considered and trained independently, one referring to the geometric mean
 152 of the horizontal components and one to the vertical one. As long as the database is updated with
 153 new strong motion records, the procedure can ideally be extended by training different ANNs
 154 separately, for different homogeneous datasets (such as for different soil classes) and/or for
 155 different components of motion (such as fault normal and fault parallel). In our case, the neural
 156 network is designed as a two-layers (i.e. nodes are grouped in layers) feed-forward (i.e. the arcs
 157 joining nodes are unidirectional, and there are no cycles) neural network with N_n^h sigmoid hidden
 158 neurons (the so-called activation functions) and a linear output neuron. The number of nodes in
 159 the input layer N_n^i equals the number of input variables N_{Sa}^{LP} . The number of nodes in the output
 160 layer N_n^o equals the number of target values N_{Sa}^{SP} . With this kind of configuration, the ANN takes
 161 the name of Multi Layer Perceptron (Bishop, 1995; Bishop and Roach, 1992). The
 162 backpropagation of error was used in the training phase (McClelland *et al.*, 1986). The idea is to
 163 propagate the error signal, computed in single teaching step, back to all connected neurons. Back-
 164 propagation needs a *teacher* that knows the correct output for any input (supervised learning) and
 165 uses gradient descent methods (Levenberg, 1944; Marquardt, 1963) on the error to train the
 166 weights. In this work, a built-in neural network fitting tool available in Matlab, namely the package

167 *nftool*, was used. The *nftool* package solves the problem of data fitting using a two-layer feed-
168 forward network trained with the Levenberg-Marquardt algorithm. A simplified sketch of the logic
169 scheme at the basis of the ANN training process is shown in Figure 2.

170 Referring to Figures 1 and 2, the N_{Sa}^{LP} input parameters are $\{\log_{10}[SA(T_j)]\}_{j=1}^{N_{Sa}^{LP}}$, where SA is
171 the acceleration response spectral ordinates at period T_j , ranging from the corner period T^* (grey
172 line in Figure 1) to 5 s. The outputs are N_{Sa}^{SP} ground motion parameters, specifically,
173 $\{\log_{10}[SA(T_k)]\}_{k=1}^{N_{Sa}^{SP}}$, at periods $T_k = 0$ (i.e. $PGA =$ Peak Ground Acceleration), up to T^* . Note
174 that the ANN is designed to predict multiple outputs given multiple inputs: specifically,
175 considering $T^*=0.75$ s, as in this study, the number of outputs and inputs is 20 and 9, respectively,
176 with a sampling equal to $T_j = [0.75,0.8:0.1:1.0,1.25:0.25:5.0]$ s for the input and of $T_k =$
177 $[0,0.05,0.1:0.1:0.7]$ s. In such conditions, two common sets of weights w and biases b are
178 iteratively adjusted to map the input to the hidden layer, as well as the hidden layer to the output
179 layer.

180 As for the training of the ANN, the adopted scheme is based on the random subdivision of the
181 entire dataset of N_{db} input-output data into three subsets (as implemented in Matlab *nftool*): (1) a
182 training set, used to calibrate the adjustable ANN weights; (2) a validation set, made of patterns
183 different from those of the training set and thus used to monitor the accuracy of the ANN model
184 during the training procedure; (3) a test set, not used during ANN training and validation, but
185 needed to evaluate the network capability of generalization in the presence of new data. This
186 distinction helps limiting the problem of overfitting, which is a well-known shortcoming of ANN
187 design. As a matter of fact, even though the error on the training set is driven to a very small value,
188 the network may fail in generalizing the learned training patterns if the patterns of the training set
189 do not sufficiently cover the variety of new situations. An *early stop* criterion was adopted to stop

190 the training phase when the error on the validation set starts growing. In our computations, the
191 training/validation/testing sets were set to 85%/10%/5%. More specifically, before selecting the
192 final network, different ANNs were constructed, for a total of $N_{train} = 50$, each based on a
193 different training subset randomly extracted among 95% of the records. The final ANN was
194 selected as the one providing the best performance, i.e., the lowest mean square error on the
195 remaining 5% of the dataset.

196 A number of hidden neurons $N_n^h = 30$ was assumed, after a parametric analysis proving that this
197 number provides a reasonable compromise in terms of accuracy of the network (see for details
198 Gatti, 2017).

199 200 **Testing the ANN performance**

201 The performance of the selected ANN in predicting the actual recordings has been evaluated by
202 computing the logarithmic residuals of the response spectral ordinates predicted by the ANN
203 (SA_{ANN}) with respect to the observed ones from SIMBAD dataset (SA_{Obs}), i.e. $\log_{10}(SA_{ANN}/SA_{Obs})$.
204 Figure 3 illustrates the residual bars corresponding to $\pm 1\sigma$ for the geometric mean of horizontal
205 components, as a function of T/T^* , for different values of T^* , corresponding to different possible
206 intervals of validity of the PBS results, namely $T^*=0.50$ s (left panel), 0.75 s (center) and 1.0 s
207 (right). The number of input and output parameters (N_{Sa}^{LP}, N_{Sa}^{SP}) in the three cases are (22,6), (20,9)
208 and (17, 11), respectively. Results are shown and compared for the training, validation and test
209 phases. It is shown that, in terms of normalized period, performance is similar for the different
210 values of T^* , with an obvious tendency of larger uncertainties as period gets lower, being more
211 distant than the corner period T^* . In spite of this effect, it is noted that typically the accuracy of
212 PGA prediction is higher. When expressed in non-normalized terms, the lower is T^* the more
213 accurate is the prediction. It is worth underling that, with few exceptions, the error of both the

214 validation and test phases is bounded to ± 0.3 in \log_{10} scale (i.e., a factor of 2), which corresponds
215 incidentally to the total standard deviation, $\sigma_{\log_{10}}$, of typical GMPEs (see e.g. Cauzzi *et al.* 2015
216 derived on a similar database). This suggests that, with respect to standard empirical approaches,
217 the reduction of uncertainty is improved as the period gets close to T^* .

218 A similar exercise was made for training, validating and testing an ANN to predict short period
219 vertical spectral ordinates, based on the same dataset. Results are shown in Figure 4 and denote,
220 as expected, a slightly worst performance of the vertical ANN with respect to the horizontal one,
221 owing to the generally poor correlation of short vs long period spectral ordinates of vertical ground
222 motions. This is clear especially for the ANN trained for $T^*=1$ s, with error bars of the validation
223 and testing phases exceeding a factor of 3 (i.e., 0.5 in \log_{10} scale) and with a significant bias on
224 the negative side, showing that, for both the validation and test datasets, the ANN predictions
225 underestimate significantly the observations. However, results get significantly better when
226 decreasing T^* and, already with $T^* = 0.75$ s, the error bars do not exceed a factor 0.4 in \log_{10} scale
227 and the bias is significantly reduced.

228 Note that the previous horizontal and vertical ANNs were trained on a dataset (about 500 three-
229 component waveforms), containing strong motion records within relatively limited epicentral
230 distance and magnitude ranges. For this reason, we did not find a significant improvement on the
231 results when distance and magnitude were considered as additional input parameters of the training
232 phase, as it could be in case of training of more general ANNs on wider record datasets. On the
233 other hand, more specific ANNs may be trained on subsets of records, aiming for example at
234 distinguishing between soft and stiff soil conditions and, hence, at providing improved accuracy
235 for site-specific evaluations. A check was made with such objective, as documented in Gatti
236 (2017), but only a slight decrease of performance was found with respect to the ANN trained on

237 the complete dataset, as if the improved classification of records was not sufficient to balance the
238 significant decrease of number of records for each ANN. As a final remark, although we did not
239 make quantitative tests on the minimum number of records needed for robust estimates, our
240 performance checks indicate that stable results are obtained only within the magnitude and distance
241 ranges of the dataset, and extrapolation out of such ranges is not reliable.

242 **The ANN2BB procedure to produce broad-band strong ground motions from** 243 **3D physics-based numerical simulations**

244 Based on the tests illustrated in the previous section, different ANNs may be trained for different
245 values of T^* , related to the frequency resolution of the numerical model (in this application,
246 $T^*=0.75$ s is considered). Therefore, this first step allows one to compute, for all PBS with range
247 of validity $T>T^*$, a site-specific ANN-based broad-band response spectrum, denoted in the
248 following by ANN2BB, as well as maps of peak values of short period ground motion. Note that,
249 at this stage, such BB response spectrum does not correspond to a specific waveform.

250 To obtain BB time histories from the ANN2BB spectra, a spectral matching approach is used,
251 similar to those adopted in the engineering practice to adapt a real accelerogram to a prescribed
252 target spectrum (NIST, 2011), where the record is iteratively scaled either in the frequency domain
253 (see e.g. Shahbazian and Pezeshk, 2010) or by wavelet transforms (e.g. Atik and Abrahamson,
254 2010), with no phase change, until its response spectrum approaches the target within a given
255 tolerance. In our case, instead of a recorded accelerogram, we consider the time history resulting
256 from the physics-based simulation, and, as a target, the ANN2BB spectrum. In this work we
257 selected the scaling in the frequency domain, but other spectral matching procedures can obviously
258 be used.

259 The difficulty, with respect to the standard spectral matching approach, comes from the low-
260 frequency band-limited nature of the simulated time-history, which implies that the high-frequency
261 content of the waveform, essentially consisting of numerical noise, is not usable for scaling. To
262 overcome this issue, before spectral matching to the desired target ANN2BB spectrum, the high-
263 frequency portion of the simulated waveform was enriched by a stochastic component, by gluing
264 the low and high-frequency parts with the procedure described in Smerzini and Villani (2012). For
265 high-frequency signals, we successfully tested both the Sabetta and Pugliese (1996) and the Boore
266 (2003) approaches, the latter implemented in the code EXSIM (Motazedian and Atkinson, 2005),
267 and selected the result providing the best fit to the target ANN2BB spectrum. Note that, as spectral
268 matching is achieved by scaling only amplitudes, the high-frequency random phases generated in
269 the hybrid step are maintained.

270 To summarize, the main steps of the ANN2BB procedure are the following:

- 271 1) an earthquake ground motion scenario is produced based on 3D PBS, whose accuracy in terms
272 of response spectral ordinates is limited to $T \geq T^*$, owing to mesh discretization issues as well
273 as to limited information on the geological models;
- 274 2) an ANN is trained based on a strong motion records dataset to predict short period spectral
275 ordinates ($T < T^*$) based on long period ones ($T \geq T^*$);
- 276 3) for each simulated waveform, a ANN2BB response spectrum is computed, the spectral
277 ordinates of which, for $T \geq T^*$, coincide with the simulated ones, while, for $T < T^*$, they are
278 obtained from the ANN. Both horizontal and vertical components can be obtained, although
279 with a lower level of accuracy for the vertical case;
- 280 4) the simulated low-frequency waveform is enriched in the high-frequency by a stochastic
281 contribution, characterized by the magnitude and source-to-site distance of the scenario

282 earthquake under consideration;
283 5) the hybrid PBS-stochastic waveform is iteratively modified in the frequency domain, with no
284 phase change, until its response spectrum matches the target ANN2BB spectrum.

285 **A case study: broad-band ground motions from the numerical simulations of** 286 **the May 29 2012 Po Plain earthquake**

287 To test the proposed approach for the generation of BB ground motions and to verify the accuracy
288 of results against observations during recent earthquakes, we considered as a case study the
289 numerical simulation of the Mw6 May 29 2012 Po Plain earthquake, Northern Italy. This
290 earthquake is very meaningful for validation purposes, because of the availability of a significant
291 number of near-source strong-motion records, some of which obtained at very short inter-station
292 distances, as well as of the good knowledge on the complex geologic setting of the Po Plain, which
293 enabled the construction of a robust 3D numerical model including its complex buried
294 morphology. 3D physics-based numerical modelling of ground shaking during the May 29 2012
295 Po Plain earthquake, has been addressed in a previous work (Paolucci *et al.*, 2015), where the
296 validation of simulated ground motions against recordings has been thoroughly analysed and
297 discussed, limited to the frequency range of design of the numerical mesh.

298 We aim herein at extending the validation to the simulated BB ground motions, encompassing
299 several aspects of engineering relevance, from the comparison of BB simulated with records at
300 selected near-source sites, as well as the spatial distribution of peak values of ground motion and
301 their spatial correlation features.

302 **Review of the case study and main results**

303 On May 20 and 29 2012, two earthquakes with moment magnitude M_w of 6.1 and 6, respectively,
304 occurred in the Po Plain region, Northern Italy, along a thrust fault system with a nearly East-West
305 strike and dipping to the South (Luzi *et al.* 2013). The May 29 earthquake was extensively recorded
306 by several accelerometric networks, making available a unique dataset of high-quality strong-
307 motion recordings in the near-source region of a major thrust event and within a deep soft sediment
308 basin structure like the Po Plain. More than 30 recordings are available at epicentral distances less
309 than 30 km and have been the basis for the validation of the 3D PBSs.

310 Referring to Paolucci *et al.* (2015) for a detailed description of the spectral-element model, we
311 limit herein to underline its main features. The model, with an extension of about 74 km x 51 km
312 x 20 km, can propagate up to about 1.5 Hz and includes the following distinctive elements: (i) an
313 *ad hoc* calibrated kinematic source model of the Mirandola fault with a major slip asperity in the
314 up-dip direction; (ii) the 3D velocity model of the Po Plain which accounts for the pronounced
315 irregularity of the base of Quaternary sediments, with thickness varying abruptly in a short distance
316 range from few tens of m in the epicentral area down to several km; (iii) a linear visco-elastic soil
317 model, with frequency proportional quality factor Q .

318 The numerical model was found to predict with satisfactory accuracy, measured through
319 quantitative goodness-of-fit criteria, the most salient features of near-source ground motion, such
320 as, in particular, (i) the strong up-dip directivity effects leading to large fault-normal velocity
321 pulses, (ii) the small-scale variability at short distance from the source, resulting in the out-of-
322 phase motion at stations separated by only 3 km distance, (iii) the prominent trains of surface
323 waves propagating with larger amplitudes in the Northern direction and dominating ground motion
324 already at some 10 km distance from the epicenter, (iv) the spatial distribution of ground uplift on
325 the hanging wall of the fault, in substantial agreement with geodetic measurements, (v) the

326 macroseismic intensity distribution.

327 **Maps of peak values of ground motion**

328 The validation checks quoted in the previous section, and reported in detail by Paolucci *et al.*
329 (2015), were limited to information extracted from the numerical results up to about 1.5 Hz, i.e.,
330 the range of validity of the PBS. We consider now additional tests, based on the BB results
331 obtained with the ANN2BB procedure outlined previously.

332 The spatial variability of peak values of ground motion is first addressed and compared with
333 available observations. To this end, Figure 5 compares the maps of simulated *PGA* (geometric
334 mean of horizontal components) obtained by (a) the ANN2BB procedure (steps 1 to 5 of the
335 previous section), (b) the hybrid PBS-stochastic approach (steps 1 to 4) and (c) the PBS results
336 filtered at 1.5 Hz (only step 1). The Sabetta and Pugliese (1996) approach was considered to
337 produce the stochastic high-frequency portion of motion at step 4. On the same maps of Figure 5,
338 the values of recorded *PGA* are also superimposed, taken from processed ITACA waveforms. In
339 Figure 5d, recorded and simulated (ANN2BB) horizontal *PGA* values are shown as a function of
340 the Joyner-Boore distance, R_{JB} , and compared with the GMPE of Bindi *et al.* (2014), referred to
341 as BI14. The latter was obtained assuming $M_W=6.0$, reverse focal mechanism and $V_{S30}=220$ m/s.

342 The following observations can be made:

343 - the proposed ANN2BB approach provides high-frequency ground motion predictions correlated
344 to the low-frequency motion obtained by PBS. This is made evident by the similarity of the spatial
345 pattern, related to source effects, of Figure 5a (ANN2BB) and Figure 5c (PBS), although PBS
346 values are bounded because of the low frequency range of the simulations. Furthermore, from the
347 comparison between the maps at top of Figure 5, it is apparent that the *PGAs* obtained by the
348 present approach reflect some physical features related to the wave propagation phenomenon itself

349 (directivity, directionality, site conditions, etc.), that are missing from the stochastic approach.
350 Namely, (i) the larger values of peaks on the northern side of the fault are consistent with the up-
351 dip directivity effects, (ii) the pronounced NW-SE alignment of the peak corresponds to the
352 prevailing orientation of the submerged bedrock topography included in the 3D numerical model,
353 thus giving evidence of a complex 3D site effect, as discussed in more detail by Paolucci *et al.*
354 (2015);

355 - there is an overall good agreement between the spatial distribution of simulated *PGA* and the
356 recorded values, although simulations tend to be lower than records. This is consistent with a
357 similar tendency of underestimation of recorded motions from PBS also in the long period range,
358 as previously noted by Paolucci *et al.* (2015);

359 - the comparison with the GMPE by BI14 puts in evidence that *PGAs* recorded within the Po Plain
360 lie well below the median empirical prediction. This can be attributed to the reduction of *PGA*
361 values that is usually noted at the surface of deep sedimentary basins (Lanzano *et al.*, 2016). It is
362 also noted that the ANN2BB predicted values are below the GMPE results, consistently with
363 records, but their decay with distance is faster, probably due to an overestimation of damping
364 within the shallow soil layers of the numerical model.

365 **Comparison between simulated BBs and recordings**

366 Performance of the ANN2BB approach can be evaluated by checking the BB simulated ground
367 motions. For this purpose, we show in Figure 6, from left to right, the acceleration, velocity and
368 displacement time histories of the NS component of the Mirandola (MRN) station, located at an
369 epicentral distance of 4 km, in one of the areas mostly affected by the earthquake. From top to
370 bottom, the figure shows in sequence the result of PBS, according to Paolucci *et al.* (2015), the
371 stochastic waveform (STO) obtained using the Sabetta and Pugliese (1996) approach, the hybrid

372 (HYB) waveform obtained by combining PBS at low-frequency and STO at high-frequency,
373 having selected 1.5 Hz as the cross-over frequency for gluing the low and high-frequency parts,
374 the ANN2BB waveform obtained by scaling HYB to the target response spectrum based on the
375 application of ANN to the PBS spectral ordinates. The last row of Figure 6 portrays the recorded
376 (REC) waveform. Comparison is further clarified in Figure 7, in terms of response spectra (left)
377 and Fourier spectra (right) of the waveforms in Figure 6.

378 It turns out that both the HYB and the ANN2BB waveforms provide a remarkable approximation
379 of recorded ground motion, both in time and frequency domain, enjoying for the MRN station a
380 very good performance of the PBS at long periods, as confirmed by comparison with a larger set
381 of stations, at different distances and azimuths (Figure 8). From this comparison, it is noted that
382 the performance of ANN2BB is less satisfactory at those sites (e.g. MOG0) where the PBS results
383 at long periods do not fit closely the observed values.

384 The main advantage of ANN2BB vs HYB is that the high-frequency part is related through the
385 ANN to the low-frequency one: therefore, as illustrated in the next section, a good agreement is
386 also expected in terms of the spatial correlation of peak values of ground motion.

387 **Spatial correlation of peak values of ground motion**

388 The most important motivation driving the search for a recipe to produce BB from 3D physics-
389 based simulations using the ANN2BB approach, is that the correlation provided through the ANN
390 between the low- and high-frequency parts of simulated ground motions is expected to ensure a
391 realistic spatial correlation of peaks of ground motion also in the high-frequency range, not covered
392 by the numerical simulations. For this purpose, a standard tool to quantify the spatial variability of
393 a random process of spatially distributed samples is the semivariogram $\gamma(h)$ (Webster and Oliver,
394 2007) measuring, in general terms, the average dissimilarity of data at inter-station distance h .

395 Taking advantage of the well-known methods to model the spatial correlation between earthquake
396 ground motion values (see e.g. Jayaram and Baker, 2009; Esposito and Iervolino, 2011; Loth and
397 Baker, 2013), the semivariogram $\gamma(h)$ and the corresponding correlation coefficient $\rho(h)$ (Webster
398 and Oliver, 2007) can be evaluated through the following steps: (i) computing the semivariogram
399 by the method of moments (Matheron, 1965) under the hypothesis of second order stationarity,
400 (iii) selecting the theoretical model of the semivariogram, (iii) estimating the parameters of the
401 model, referred to as sill (i.e., the variance of the random process) and range (i.e., the inter-station
402 distance at which $\gamma(h)$ tends to the sill, indicating that motions are uncorrelated), by fitting the
403 computed semivariogram values with the functional form chosen at the previous point and (iv)
404 computing the correlation coefficient as the complementary to the semivariogram normalized by
405 the sill. Referring to literature studies for the analytical background (Jayaram and Baker, 2009;
406 Esposito and Iervolino, 2011; 2012), we note that, in this work, the residual terms, on which the
407 semivariogram is computed, are evaluated with respect to an average trend defined as:

$$408 \quad P(R_{line}) = a + \log_{10}(R_{line} + b) \quad (1)$$

409 where P is the peak parameter of ground motion of interest (e.g., PGA) and R_{line} is the closest
410 distance from the surface fault projection of the segment at the top edge of the rupture plane, which
411 was found to be the best distance metrics for the Po Plain simulations (Hashemi *et al.*, 2015), as
412 well as for other case studies of normal and reverse fault earthquakes (Paolucci *et al.*, 2016).
413 Furthermore, a and b are regression coefficients calibrated either on records or on simulated
414 results.

415 Figure 9 shows the semivariograms as a function of the inter-station distance from both recorded
416 and simulated ground motions along the NS component at the accelerometric stations illustrated
417 in Figure 5. Symbols denote the semivariogram values associated with different response spectral

418 ordinates, specifically, PGA , $SA(0.2s)$, $SA(1.0s)$, $SA(2.0s)$, both for the records (crosses) and for
419 the BB results simulated either through the ANN2BB procedure (open dots) or the HYB procedure
420 (filled squares). The functional form chosen to fit the corresponding semivariogram data is the
421 exponential model (Cressie, 1985), shown by continuous and dashed lines for REC and ANN2BB,
422 respectively. In analogy with previous studies (see e.g. Jayaram and Baker, 2009; Esposito and
423 Iervolino, 2011), to provide a better representation at short separation distances, we have decided
424 to fit manually the semivariograms starting from the least-square estimation. On each subplot of
425 Figure 9 the values of range resulting from the best-fitting model are indicated. Note that larger
426 values of the range, i.e., the inter-station distance at which the correlation coefficient drops to zero,
427 means that correlation is preserved at larger distances.

428 It turns out that the best-fitting exponential models on records and on the ANN2BB results are in
429 good agreement. In both cases, the value of the range varies between 19 to 25 km, with a relative
430 error between the two range estimates (i.e. from REC and ANN2BB) bounded between 1% (for
431 $SA 0.2s$) and 20% (for PGA). This points out that the ANN2BB approach succeeds in reproducing
432 accurately the spatial correlation structure of response spectral ordinates even at short periods.
433 Instead, it is apparent that the application of the HYB procedure produces at short periods (see
434 PGA and $SA 0.2s$) a semivariogram which is almost flat, thus denoting a zero correlation
435 coefficient at all interstation distances. As a final remark, it is found that that the trend of ranges
436 obtained with ANN2BB method is increasing with the vibration period, passing from 20 km for
437 PGA to 24 km for $SA 2.0s$, in agreement with the other research works previously mentioned.

438 Although the Po Plain earthquake considered in this work provided one of the widest set of near-
439 source records from moderate-to-large earthquakes worldwide, the number of stations has to be
440 considered limited for the computation of the semivariograms. For this reason, it is not possible to

441 group the stations in order to study possible anisotropies in the features of spatial correlation of
442 ground motion, because the number of stations in each sub-group would be too small. Instead, this
443 is possible when using the results of numerical simulations, because the number of receivers may
444 be made arbitrarily large.

445 Figure 10 shows the correlation models for *PGA*, left, and *SA I.Os*, right, obtained from both
446 recordings and ANN2BB results. In addition to the results obtained at the accelerometric stations
447 (solid lines), possible anisotropy patterns have been investigated by considering a sufficiently large
448 set of synthetic receivers located in the Northern and Southern sector with respect to the fault at
449 distances R_{line} lower than 10 km (N and S set, respectively). This figure points out an interesting
450 feature of the ANN2BB simulated waveforms: when considering only receivers with $R_{line} < 10$
451 km, both in the North and South direction, spatial correlation drops to 0 faster than when the whole
452 set of receivers is considered (i.e., correlation distances are significantly shorter). This is very clear
453 in the intermediate-to-long period range (see e.g. right side of Figure 10, referring to $T = 1$ s), while
454 this trend is less evident at short periods (see left side of the figure, referring to *PGA*), although it
455 still appears for the receivers lying on the surface fault projection (Figure 10, left subplot, for R_{line}
456 < 10 km, Southern side).

457 It can be concluded that such spatial anisotropy features of peak values of earthquake ground
458 motion are mainly related to near-source effects. More specifically, proximity to the extended
459 seismic source produces a faster decay of spatial correlation at very short distances, owing to the
460 small-scale spatial variability of ground motion induced by the heterogeneous fault rupture
461 combined with complex site effects related to the approximately NS orientation of the submerged
462 bedrock topography.

463

Conclusions

464 In this paper we introduced the ANN2BB procedure, suitable to create realistic BB waveforms
465 from 3D physics-based numerical simulations. It turns out that the performance of this procedure
466 is rather good, provided that the simulations are accurate within a frequency band at least extended
467 to approximately 1.5 Hz, roughly corresponding to $T^* = 0.75\text{s}$. In such range, the ANN trained to
468 correlate long period response spectral ordinates ($T \geq T^*$) with those at short periods, was found
469 to provide satisfactory results. The ANN used in this work was trained on a strong motion dataset
470 consisting of about 500 records with moment magnitude from 5 to 7.3 and epicentral distance up
471 to 35 km, but other ANNs can be trained with a similar purpose on wider datasets. Separate ANNs
472 were trained on the geometric mean of the horizontal components and on the vertical components
473 to allow the prediction of three-component ground motions.

474 An extension of the training dataset is planned to encompass a wider range of magnitude, distance
475 and site conditions. Furthermore, since all ANNs considered in this work are deterministic, i.e.,
476 for one set of input spectral ordinates at long period, a single set of output spectral ordinates at
477 short period is provided, the training of stochastic ANNs is also envisioned, by defining weights
478 and biases as random variables.

479 As a comprehensive validation benchmark, we considered the strong motion records obtained in
480 the near-source region of the May 29, 2012 Po Plain earthquake and the corresponding 3D physics-
481 based numerical simulations carried out by the spectral element code SPEED and illustrated in
482 detail in Paolucci *et al.* (2015). Compared to a standard hybrid approach to produce BB waveforms,
483 consisting of enriching the high-frequency portion of ground motion by a stochastic contribution,
484 the proposed ANN2BB procedure allows one to obtain a similar realistic aspect of the waveform,
485 both in time and frequency domains, but, in addition, it also allows one to obtain maps of short-
486 period peak values of ground motion which reproduce more closely the coupling of source-related

487 and site-related features of earthquake ground motion. And, as a further important asset of the
488 proposed procedure, as also illustrated by a similar application in Thessaloniki (Smerzini and
489 Pitilakis, 2017), it is suitable to portray in a realistic way the spatial correlation features of the peak
490 values of ground motion also at short periods, with the possibility to point out possible spatial
491 anisotropies, typically related to the near-source or complex geology conditions.

492 To conclude, we remark that, while the correlation structure of the high-frequency peak values is
493 simulated in a satisfactory way, the procedure is not suitable yet to obtain sets of waveforms with
494 realistic spatial coherency features at high-frequency (measured in terms of the coherency
495 operator, see Zerva, 2009), apt for use as input motions for seismic analyses of spatially extended
496 structures. As a matter of fact, the high-frequency stochastic contributions added to the simulated
497 motions need to be re-phased to reproduce properly travelling waveforms. This is probably the
498 single major limitation still existing preventing yet to provide simulated BBs fulfilling all the
499 characteristics of a real earthquake ground motion wavefield.

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Data and Resources

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734 where T^* is the minimum period of validity of the physics-based numerical model, are computed

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736 **Figure 2.** Logic scheme of the ANN training patterns: the long period spectral ordinates (in this

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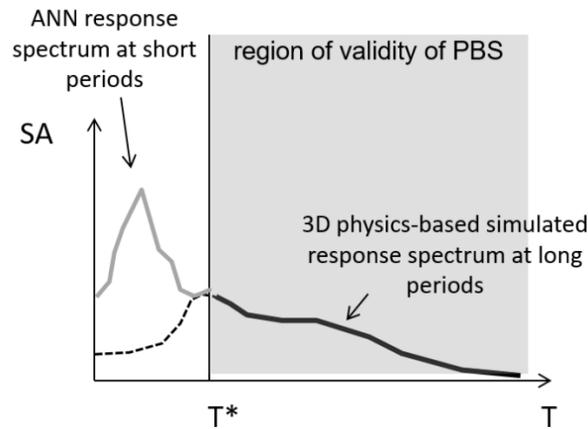
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766 (circle) for *PGA* (top left), *SA 0.2s* (top right), *SA 1.0s* (bottom left) and *SA 2.0s* (bottom right).
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769 top panel), the semivariograms (filled squares) and the corresponding best-fitting model (solid
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771 **Figure 10.** Spatial correlation models, $\rho(h)$, obtained from the REC and ANN2BB values obtained
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773 dot lines show the correlation models computed using a larger number of ANN2BB receivers
774 located in the Northern (N) and Southern (S) side with respect to the fault at $R_{line} < 1$

776 **Table 1.** Selection of BB earthquake ground motion simulation case studies relying on hybrid
 777 approaches*.

Publications	f_c [Hz]	Methods (LF + HF)	Area under study	Validation
Causse <i>et al.</i> , 2009	1.0	SE + EGF	Grenoble, France	against GMPE
Graves and Pitarka, 2010	1.0	FD + SFF	California, USA	M6.4, Imperial Valley, 1979 M6.9, Loma Prieta 1989 M7.3, Landers, 1992 M6.7, Northridge, 1994 against GMPE
Mena <i>et al.</i> , 2010	0.5	FD + Sc-GF	San Andreas fault, California, USA	against GMPE
Roten <i>et al.</i> , 2012	1.0	FD + Sc-GF	Salt Lake City, Utah, USA	against GMPE
Smerzini and Villani, 2012	2.5	SE + SFF	L'Aquila, Italy	M6.3, L'Aquila, 2009
Seyhan <i>et al.</i> , 2013	1.0	FD + SFF	California, USA	against GMPE
Ramirez-Guzman <i>et al.</i> 2015	1.0	FD, FE + SFF, St-GF	New Madrid seismic zone, USA	against GMPE
Iwaki <i>et al.</i> , 2016	1.0	FD + St-GF	Japan	M6.7, Tottori, 2000 M6.6, Chuetsu, 2004
Razafindrakoto <i>et al.</i> , 2016	1.0	FD + SFF	Christchurch area, New Zealand	2010-2011 earthquake sequence
Akinci <i>et al.</i> , 2017	1.0	FD + SFF	Marmara Sea, Turkey	against GMPE

778 * Low-frequency (LF) methods: FD = Finite Difference; FE = Finite Element, SE = Spectral Element. High-
 779 frequency (HF) methods: SFF = stochastic finite-fault (Boore, 2003; Motazedian and Atkinson, 2005; Graves and
 780 Pitarka, 2010); EGF = Empirical Green's functions (Hartzell, 1978); Sc-GF = scattering Green's functions (Mai *et al.*
 781 *et al.*, 2010); St-GF = stochastic Green's functions (Kamae *et al.*, 1998). f_c denotes the cross-over frequency where low
 782 frequency (from PBS) and high frequency (stochastic) synthetics are combined.



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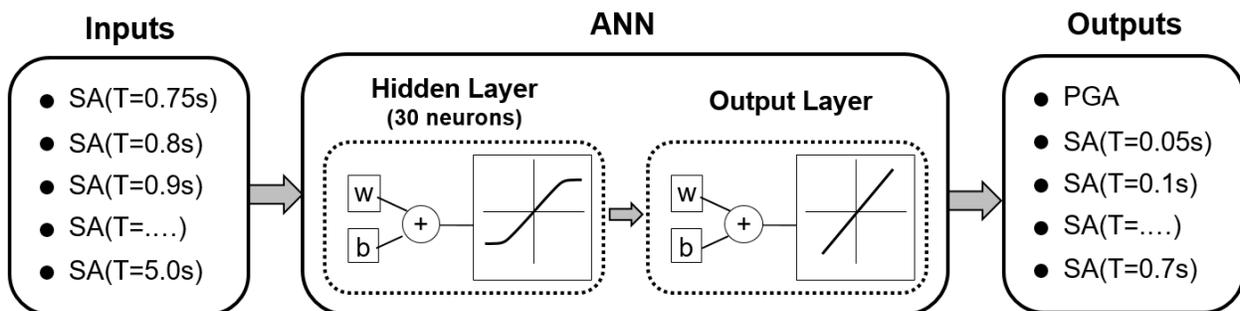
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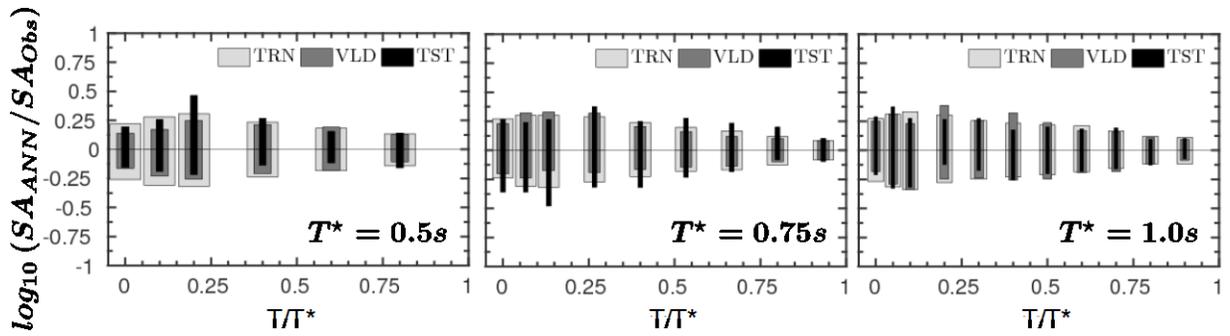


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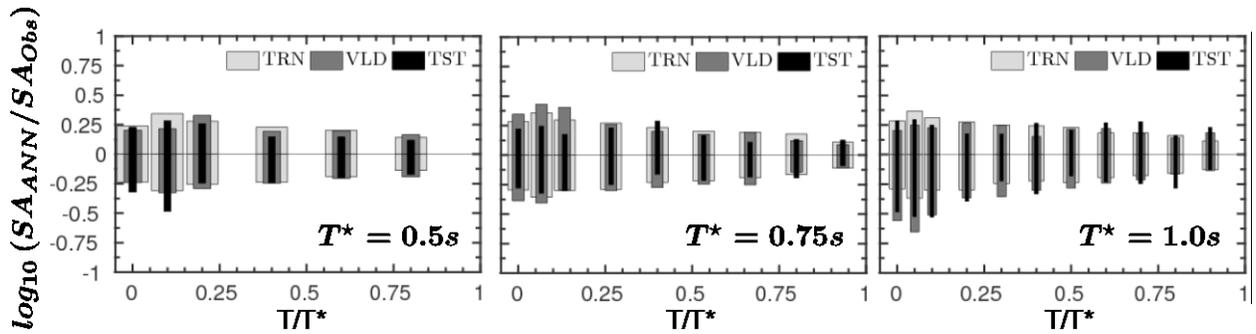
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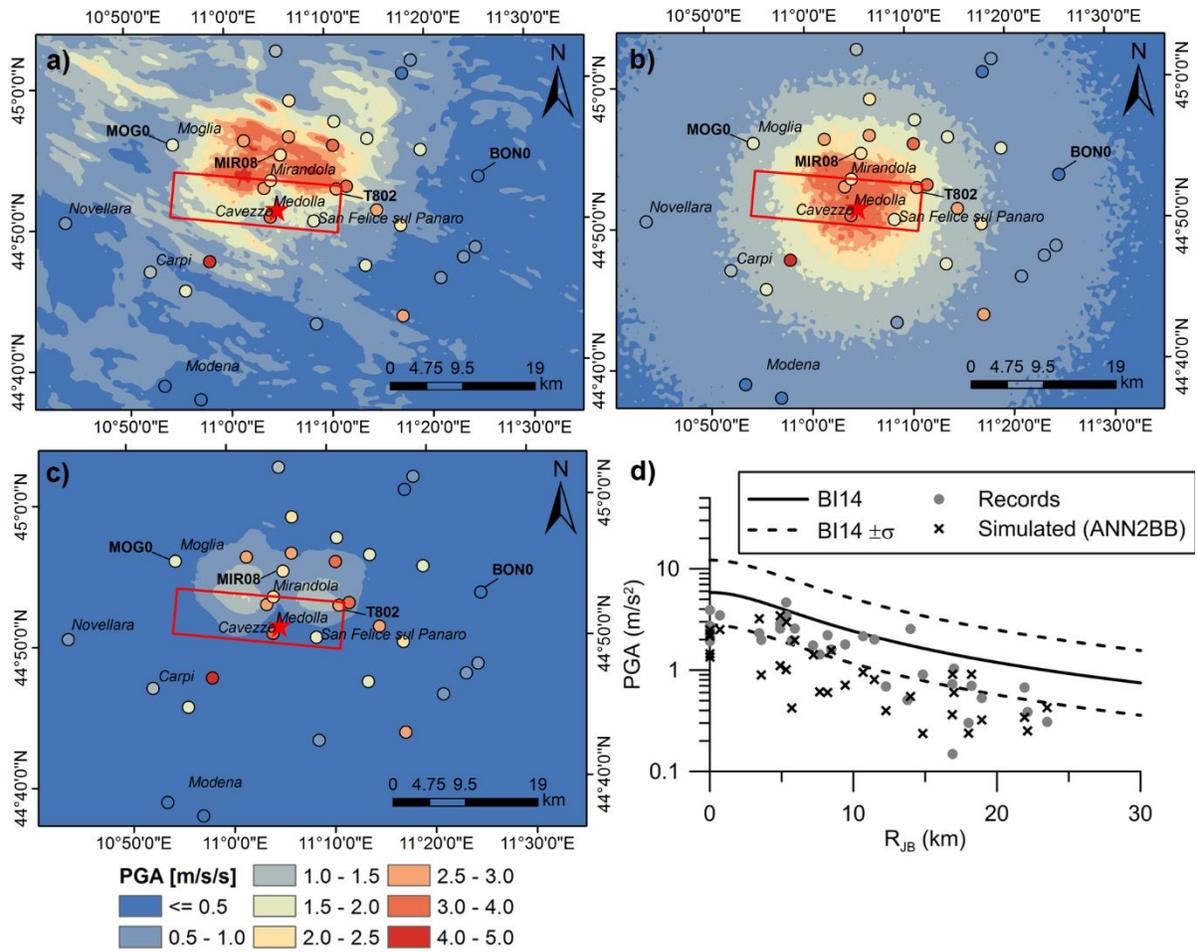
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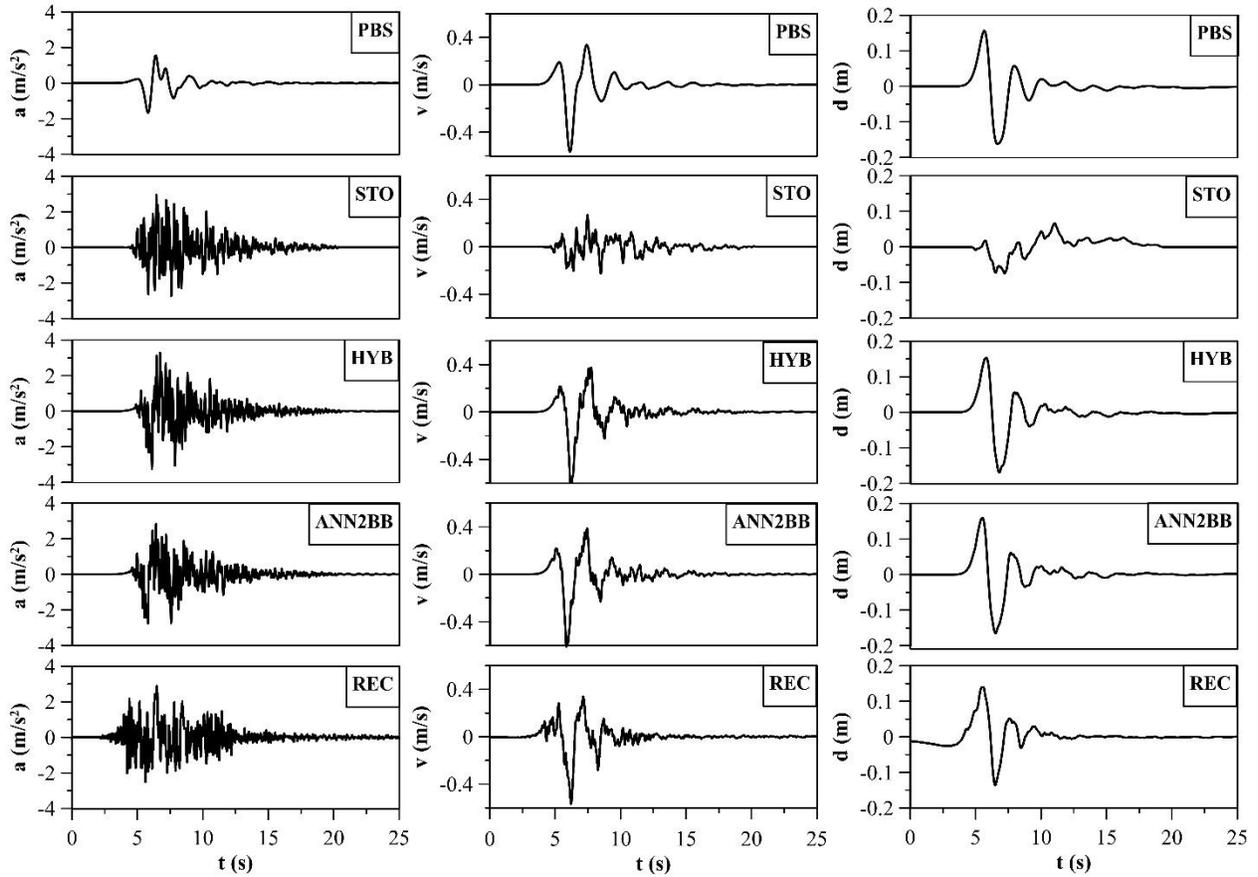
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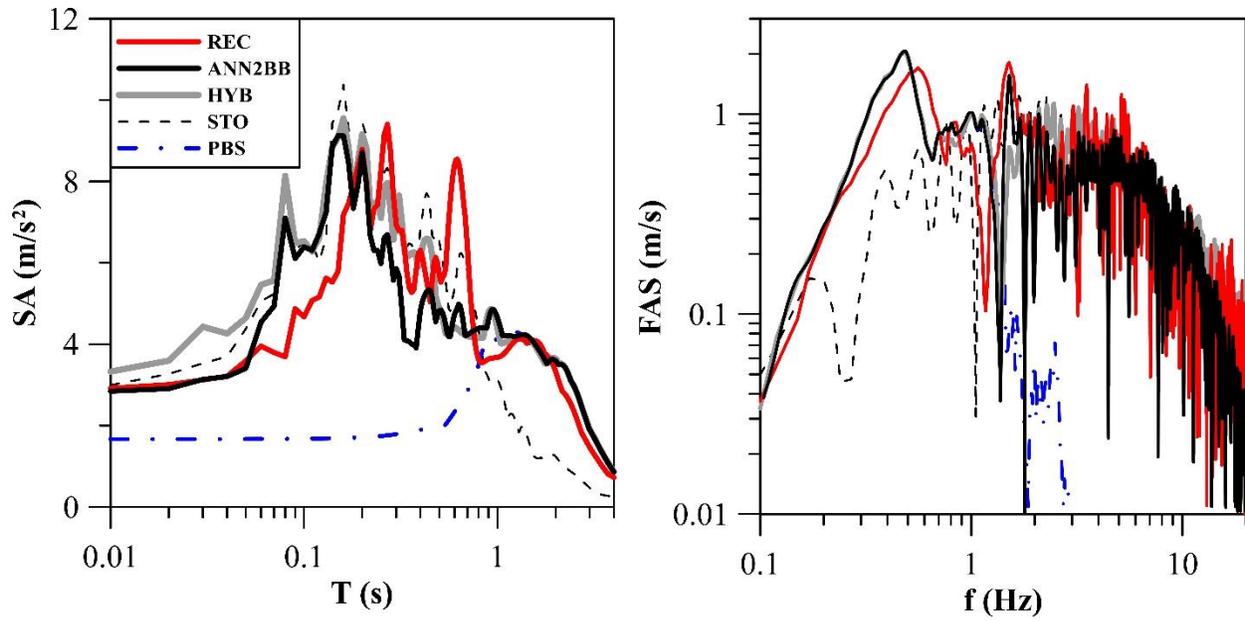
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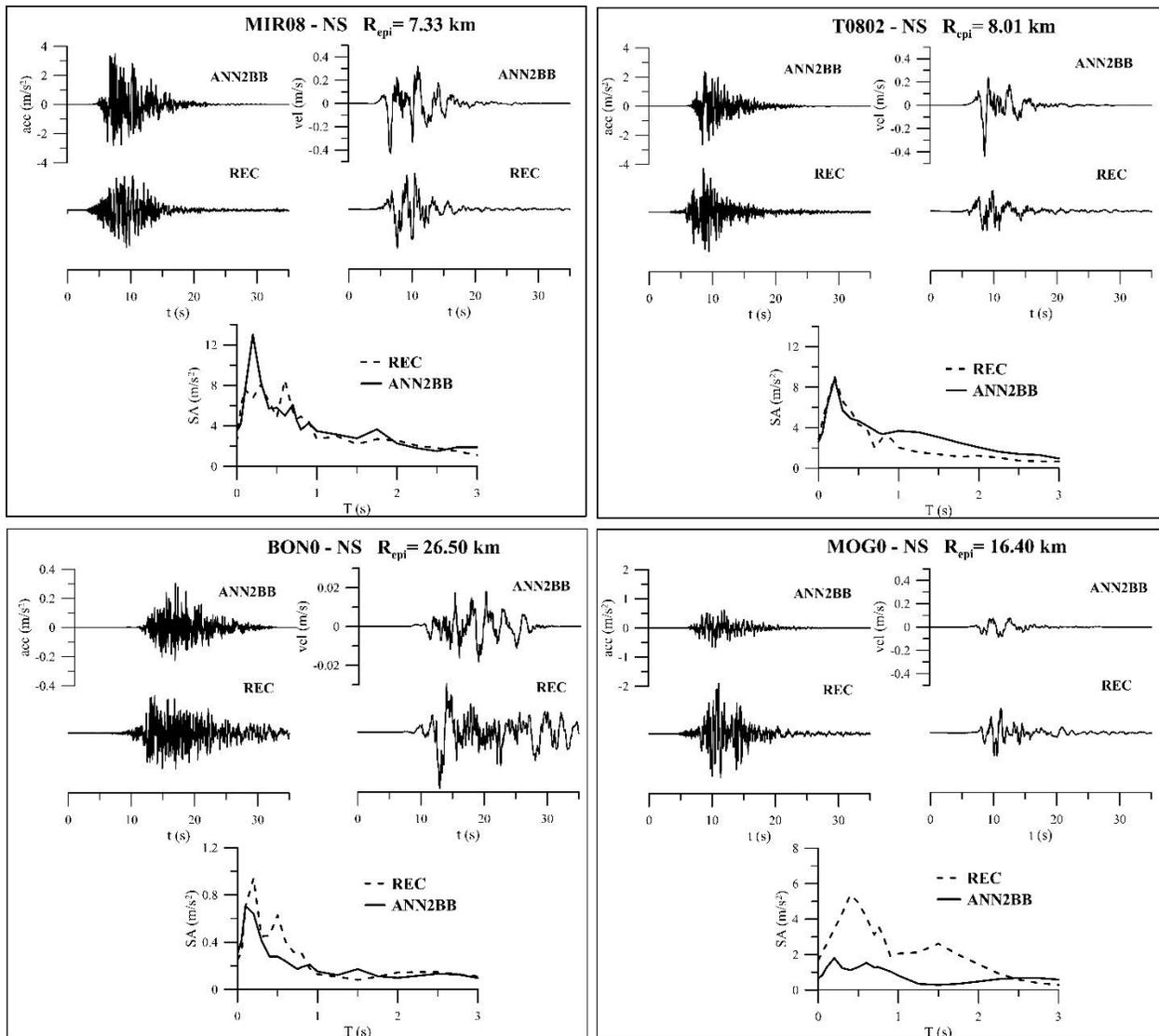
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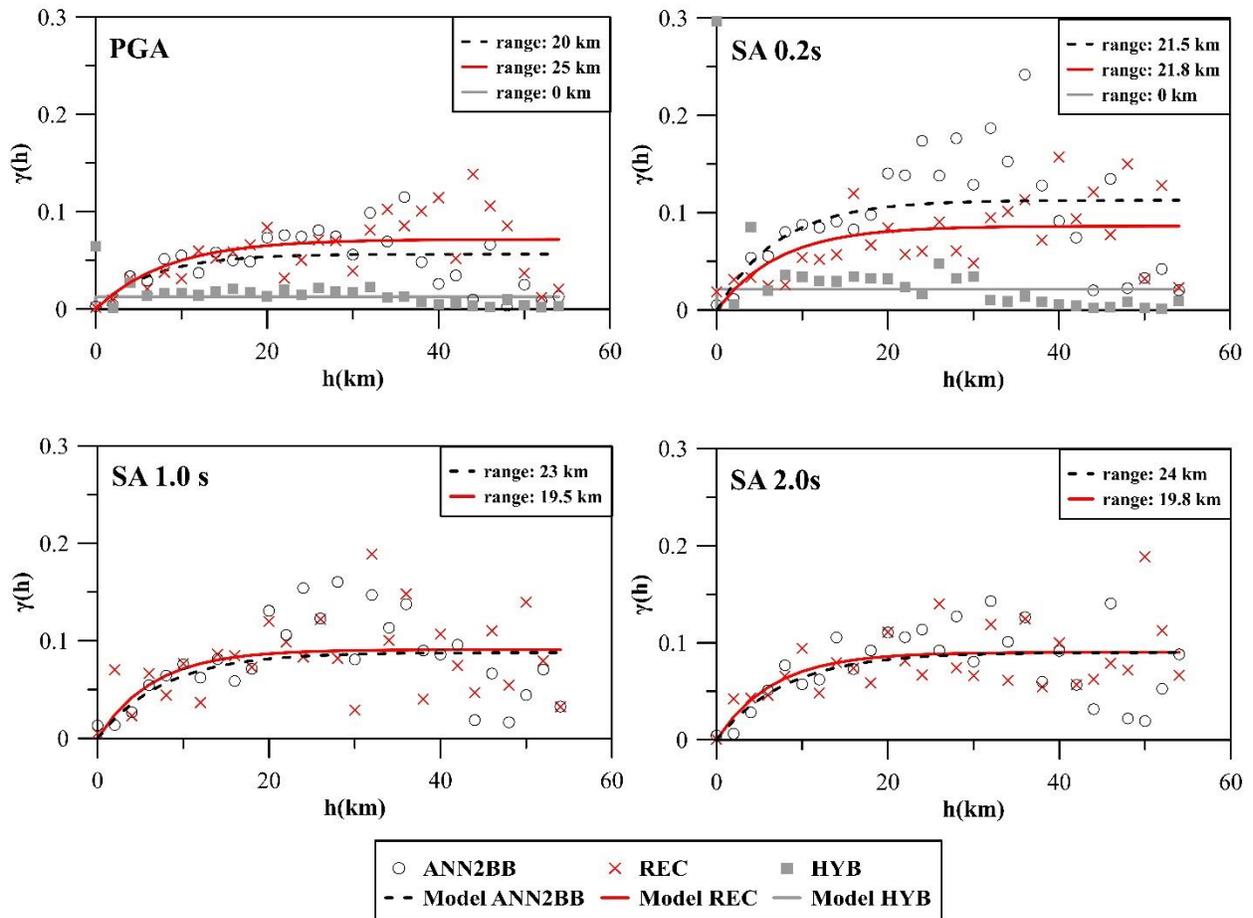
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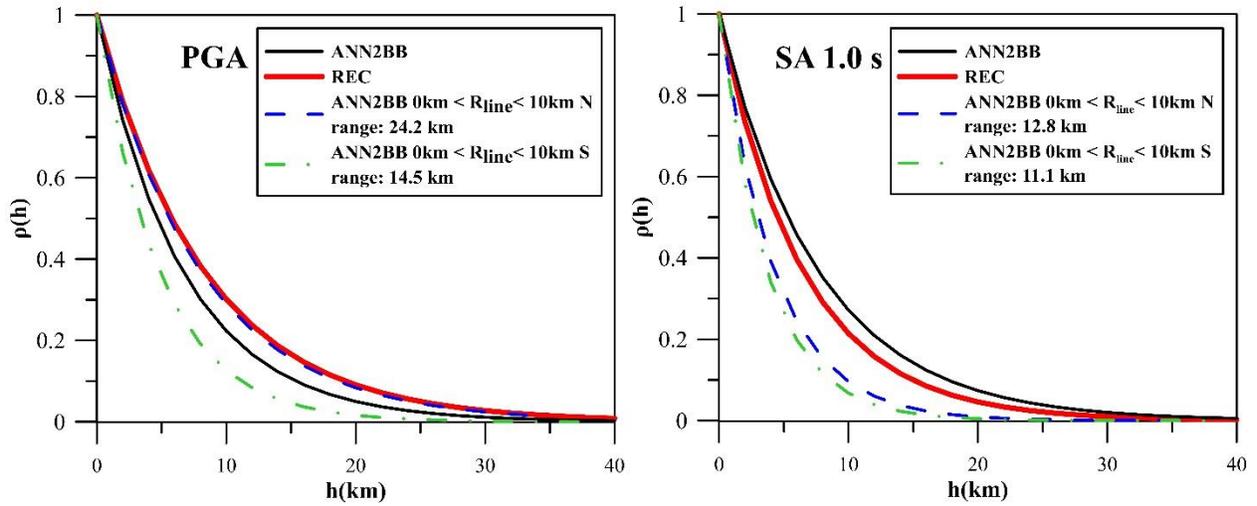
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