# DIFFERENTIABILITY OF THE DIRICHLET TO NEUMANN MAP UNDER MOVEMENTS OF POLYGONAL INCLUSIONS WITH AN APPLICATION TO SHAPE OPTIMIZATION 

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#### Abstract

In this paper we derive rigorously the derivative of the Dirichlet to Neumann map and of the Neumann to Dirichlet map of the conductivity equation with respect to movements of vertices of triangular conductivity inclusions. We apply this result to formulate an optimization problem based on a shape derivative approach.


## 1. Introduction

This paper contains a rigorous proof of the formula for the derivative of the normal derivative of the solution to the following boundary value problem

$$
\left\{\begin{align*}
\operatorname{div}\left(\left(1+(k-1) \chi_{T}\right) \nabla u\right) & =0 \text { in } \Omega  \tag{1.1}\\
u & =f \text { on } \partial \Omega
\end{align*}\right.
$$

with respect to affine movements of a triangular inclusion $T \subset \Omega$.
More precisely, let us fix two functions $f, g \in H^{1 / 2}(\partial \Omega)$. Let $P:=\left(P_{1}, P_{2}, P_{3}\right) \in$ $\Omega \times \Omega \times \Omega$ represent the vertices of $T$. Let $F: \Omega \times \Omega \times \Omega \rightarrow \mathbb{R}$ denote the following function

$$
F(P)=\int_{\partial \Omega} \frac{\partial u}{\partial \nu} g d \sigma .
$$

We prove that $F$ is differentiable and we derive rigorously an explicit formula of the differential. Moreover, the quantitative proof of our main result allows us to infer differentiability of the Dirichlet to Neumann map with respect to motions of the vertices of the triangle $T$ (see Corollary 4.5). An analogous result is established for the Neumann to Dirichlet map.
We want to highlight that the derived formula can be cast in the framework of shape derivatives, a tool, which has been widely used in optimization problems, (see [1], [2], 3], 4], [5], 6], [11). Surprisingly, to our knowledge, it does not exist in the literature a rigorous proof in the case of polygonal inclusions. In fact, the formulas for shape derivatives obtained in, for example [1], [11, using a variational approach, require at least $C^{1,1}$ regularity of the boundary of the inclusion. Hence, we think it is important to present a rigorous proof of the formula for the derivative of $F$ in the case of polygonal inclusions. We present the result in the case of a triangular inclusion since this allows us to face the main difficulties of the problem without burdening the presentation with excessive notation. (see Remark 2.3).

[^0]Our interest in the derivative of $F$ is motivated by the following inverse problem: let $\left\{T_{j}\right\}_{j=1}^{N}$ be an unknown triangular mesh of $\Omega$ and let

$$
\sigma=\sum_{j=1}^{N} \sigma_{j} \chi_{T_{j}}
$$

we would like to recover the mesh from Neumann boundary measurements of solutions of

$$
\left\{\begin{aligned}
\operatorname{div}(\sigma \nabla u) & =0 \text { in } \Omega \\
u & =f \text { on } \partial \Omega
\end{aligned}\right.
$$

A similar inverse problem was considered in [8]. There, the authors considered the Helmholtz equation at fixed low frequency in a bounded three-dimensional domain. Assuming the wavespeed piecewise constant on an unknown regular tetrahedral partition of $\Omega$ they established a quantitative of the Hausdorff distance between partitions in terms of the norm of the difference of the corresponding Dirichlet to Neumann maps. One of the main ingredients in it is differentiability of the Dirichlet to Neumann map with respect to motions of the mesh. In order to extend the stability result derived in [8] to the case of piecewise constant conductivities in dimension two a crucial step concerns the differentiability of the Dirichlet to Neumann map with respect to motions of vertices of the mesh $\left\{T^{j}\right\}_{j=1}^{N}, N \geq 2$. It is worthwhile to notice that this case compared to the Helmholtz equation is much more difficult since solutions are less regular. In particular, the gradient of solutions may blow up at vertices of the mesh.
The main tools to establish our result are energy estimates, fine elliptic regularity results for solutions to transmission problems for elliptic systems and equations obtained in [12], [13] and the study of the exact asymptotic behaviour of gradients of solutions in a neighborhood of vertices (see [6]). As we mentioned above the result is important in the context of shape optimization (see [14, [10]), since it generalizes the computation of the shape derivative to a class of non smooth inclusions. Furthermore, in Section 5 we describe how the result can be used to formulate a reconstruction algorithm for the inverse problem of recovering a polygonal inclusion from boundary measurements based on minimization of a suitable boundary functional. A similar approach has been used in [1], [5] and [11] in the case of smooth inclusions.
The plan of the paper is the following: in Section 2 we present our main assumptions and the main results. In Section 3 we state some preliminary results concerning the local behaviour of solutions to the conductivity equation at the interface of the triangle. Based on these results we prove some energy estimates and some pointwise estimates of the gradient of the difference between the solutions of the conductivity equation corresponding to a fixed triangle $T$ and a perturbation of such a solution under a small motion of the vertices of the triangle $T, T^{t}$. In Section 4 we give the proof of our main result that we split in several steps: first we derive the formula of the derivative under suitable movements that move only one vertex of the triangle. Then, we extend the validity of the formula to arbitrary movements of one vertex. Finally, we show the general result by superposition of three displacements. As mentioned above, in the final Section we present an application to shape optimization.

## 2. Notations, ASSUMPTIONS AND MAIN RESULT

## Main Assumptions

Let $\Omega$ be a bounded domain in $\mathbb{R}^{2}$ and $\partial \Omega \in C^{0,1}$

$$
\operatorname{diam} \Omega \leq L
$$

Let $d_{0}>0$ be such that

$$
\Omega_{d_{0}}=\left\{(x, y) \in \Omega: \operatorname{dist}((x, y), \partial \Omega) \geq d_{0}\right\}
$$

is a nonempty subset of $\Omega$. Let $T^{P}$ denote an open triangle of vertices $P=$ $\left(P_{1}, P_{2}, P_{3}\right)$ where $P$ belongs to the following subset of $\mathbb{R}^{2} \times \mathbb{R}^{2} \times \mathbb{R}^{2}$

$$
\mathcal{V}=\left\{P \in \Omega_{d_{0}} \times \Omega_{d_{0}} \times \Omega_{d_{0}}:\left|P_{i}-P_{j}\right| \geq \alpha_{1}, \theta_{i} \geq \alpha_{0}, i, j=1,2,3\right\}
$$

where $\theta_{i}$ denotes the width of the angle at the vertex $P_{i}$ and $\alpha_{0}, \alpha_{1}$ are positive given constants. Let, for $0<k, k \neq 1$

$$
\sigma_{P}=1+(k-1) \chi_{T^{P}} \quad \text { in } \Omega
$$

Given $f \in H^{1 / 2}(\partial \Omega)$ we denote by $u_{P} \in H^{1}(\Omega)$ the unique weak solution to

$$
\left\{\begin{align*}
\operatorname{div}\left(\sigma_{P} \nabla u_{P}\right) & =0 \text { in } \Omega,  \tag{2.1}\\
u_{P} & =f \text { on } \partial \Omega .
\end{align*}\right.
$$

Define the Dirichlet to Neumann map

$$
\Lambda_{\sigma_{P}}: H^{1 / 2}(\partial \Omega) \rightarrow H^{-1 / 2}(\partial \Omega)
$$

as follows: given $f \in H^{1 / 2}(\partial \Omega)$,

$$
\Lambda_{\sigma_{P}}(f):=\frac{\partial u_{P}}{\partial \nu} \in H^{-1 / 2}(\partial \Omega)
$$

where $\nu$ is the unit outer normal to $\partial \Omega$.
For $f, g \in H^{1 / 2}(\partial \Omega)$ let us define $F: \mathcal{V} \rightarrow \mathbb{R}$ as follows

$$
F(P)=<\Lambda_{\sigma_{P}}(f), g>\quad \forall P \in \mathcal{V}
$$

where $<\cdot, \cdot>$ is the duality pairing between $H^{1 / 2}(\partial \Omega)$ and its dual $H^{-1 / 2}(\partial \Omega)$. Consider now $P^{0}=\left(P_{1}^{0}, P_{2}^{0}, P_{3}^{0}\right) \in \mathcal{V}$ and the corresponding triangle denoted by $T^{0}:=T^{P^{0}}$. Let $\vec{V}=\left(\vec{V}_{1}, \vec{V}_{2}, \vec{V}_{3}\right) \in \mathbb{R}^{2} \times \mathbb{R}^{2} \times \mathbb{R}^{2}$ be an arbitrary vector and let $\Phi_{0}^{\vec{V}}: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ be the affine map such that

$$
\Phi_{0}^{\vec{V}}\left(P_{i}^{0}\right)=\vec{V}_{i}, \quad i=1,2,3
$$

Consider now $P^{t}=P^{0}+t \vec{V}=\left(P_{1}^{t}, P_{2}^{t}, P_{3}^{t}\right)$ for $t$ sufficiently small (for example $\left.|t|<d_{0} /(2|\vec{V}|)\right)$ and the triangle of vertices $P^{t}$ that we denote by $T^{t}:=T^{P^{t}}$ and let

$$
G(t):=F\left(P^{t}\right)
$$

Then, let $u_{0}:=u_{P^{0}}$ the solution of (2.1) corresponding to

$$
\sigma_{0}:=\sigma_{P^{0}}=1+(k-1) \chi_{T^{0}},
$$

denote by $v_{0}$ the solution of

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{0} \nabla v_{0}\right) & =0 \text { in } \Omega \\
v_{0} & =g \text { on } \partial \Omega
\end{aligned}\right.
$$

Finally, denote by $u_{t}:=u_{P^{t}}$ the solution of (2.1) corresponding to

$$
\sigma_{t}:=\sigma_{P^{t}}=1+(k-1) \chi_{T^{t}}
$$

and by $v_{t}$ the solution to

$$
\left\{\begin{align*}
\operatorname{div}\left(\sigma_{t} \nabla v_{t}\right) & =0 \text { in } \Omega  \tag{2.2}\\
v_{t} & =g \text { on } \partial \Omega
\end{align*}\right.
$$

Let us define

$$
u_{0}^{e}=\left.u_{0}\right|_{\Omega \backslash T^{0}}, \quad v_{0}^{e}=\left.v_{0}\right|_{\Omega \backslash T^{0}} .
$$

Fix an orthonormal system $\left(\tau_{0}, n_{0}\right)$ in such a way that $n_{0}$ represents the outward unit normal to $\partial T^{0} \backslash P^{0}$, the tangent unit vector $\tau_{0}$ is oriented clockwise and denote by $M_{0}$ a $2 \times 2$ matrix valued function defined on $\partial T^{0}$ with eigenvalues 1 and $\frac{1}{k}$ and corresponding eigenvectors $\tau_{0}$ and $n_{0}$.
Our main result is the following
Theorem 2.1. There exist two positive constants $C$ and $\alpha$ depending only on $L$, $d_{0}, \alpha_{0}, \alpha_{1}, k$, such that

$$
\begin{align*}
& \mid G(t)-G(0)- t(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \mid  \tag{2.3}\\
& \leq C t^{1+\alpha}\|f\|_{H^{1 / 2}(\partial \Omega)}\|g\|_{H^{1 / 2}(\partial \Omega)}
\end{align*}
$$

for $|t|<d_{0} /(2|\vec{V}|)$.
An obvious consequence of Theorem 2.1 is:
Corollary 2.2. For given $f$ and $g$ in $H^{1 / 2}(\partial \Omega), G$ is differentiable and

$$
\begin{equation*}
G^{\prime}(0)=(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma . \tag{2.4}
\end{equation*}
$$

Remark 2.3. We want to point out that Theorem 2.1 extends to the case of a polygonal inclusion. Let $\mathcal{T}^{0}$ be a polygon that, for simplicity, we assume it is convex, of $N$ vertices, $P^{0}=\left(P_{1}^{0}, \ldots, P_{N}^{0}\right)$ ordered clockwise. Assume that

$$
\mathcal{T}^{0} \subset \Omega_{d_{0}}
$$

there exists $\alpha_{0} \in(0, \pi / 2)$ such that, denoting by $\theta_{i}$ the interior angle at vertex $P_{i}$,

$$
\alpha_{0} \leq \theta_{i} \leq \pi-\alpha_{0}, \quad \forall i=1, \ldots, N
$$

Assume also there exists $\alpha_{1}>0$ such that

$$
\left|P_{i+1}-P_{i}\right|>\alpha_{1}, \forall i=1, \ldots, N
$$

where we set $P_{N+1}:=P_{1}$.
Denote by $P^{t}=P^{0}+t \vec{V}$ where $\vec{V}=\left(\vec{V}_{1}, \ldots, \vec{V}_{N}\right), \vec{V}_{i} \in \mathbb{R}^{2}$ for all $i=1, \ldots, N$ and $t \in \mathbb{R}$ is sufficiently small. Let $\mathcal{T}^{t}$ be the polyon of vertices $P^{t}$ and define

$$
G(t)=<\Lambda_{\sigma_{t}}(f), g>
$$

where $f, g \in H^{1 / 2}(\partial \Omega)$ and $\Lambda_{\sigma_{t}}$ denotes the Dirichlet to Neumann map of the operator

$$
\operatorname{div}\left(\sigma_{t} \nabla \cdot\right)
$$

with

$$
\sigma_{t}=1+(k-1) \chi_{\mathcal{T}^{t}} .
$$

We have that $G$ is differentiable at $t=0$ and $G^{\prime}(0)$ can be expressed by the following formula

$$
G^{\prime}(0)=(k-1) \int_{\partial \mathcal{T}^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

where $\Phi^{\vec{V}}: \partial \mathcal{T}^{0} \rightarrow \mathbb{R}^{2}$ and

$$
\Phi^{\vec{V}}(Q)=\vec{V}_{i}+\frac{\left(Q-P_{i}^{0}\right) \cdot\left(P_{i+1}^{0}-P_{i}^{0}\right)}{\left|P_{i+1}^{0}-P_{i}^{0}\right|^{2}}\left(\vec{V}_{i+1}-\vec{V}_{i}\right) \text {, for } Q \text { on the side } P_{i}^{0} P_{i+1}^{0} \text {. }
$$

## 3. Preliminary Results

In this section we collect some preliminary results some of them concerning the regularity of solutions to Problem (2.1) and that are crucial to prove our main theorem. Let $u_{P}$ be the solution to Problem (2.1) with $P=\left(P_{1}, P_{2}, P_{3}\right) \in \mathcal{V}$. Let

$$
u_{P}^{e}=u_{\left.P\right|_{\Omega \backslash T^{P}}}, \quad u_{P}^{i}=u_{\left.P\right|_{\bar{T}^{P}}}
$$

Finally, let $B\left(P_{j}, \delta\right)$ denote the ball centered at $P_{j}$ and radius $\delta>0$. Then, the following estimates holds true
Proposition 3.1. There exist positive constants $C$ and $\gamma \in(0,1 / 4)$ and $\delta_{0}$ depending only on $\alpha_{0}, \alpha_{1}, k$ and $d_{0}$, such that, for any $\delta \in\left(0, \delta_{0}\right)$ we have

$$
\begin{gather*}
\left\|\nabla u_{P}^{i}\right\|_{C^{\gamma}\left(T^{P} \backslash \cup_{j=1}^{3} B\left(P_{j}, \delta\right)\right)} \leq \frac{C}{\delta^{\gamma+1}}\|u\|_{L^{2}(\Omega)}  \tag{3.1}\\
\left\|\nabla u_{P}^{e}\right\|_{C^{\gamma}\left(\Omega_{d_{0}} \backslash\left(T^{P} \cup\left(\cup_{j=1}^{3} B\left(P_{j}, \delta\right)\right)\right)\right.} \leq \frac{C}{\delta^{\gamma+1}}\|u\|_{L^{2}(\Omega)} \tag{3.2}
\end{gather*}
$$

The proposition is consequence of a more general regularity result for elliptic systems due to Li and Nirenberg and to Li and Vogelius for elliptic equations (cf. [12] and (13).
Moreover, by a result of Bellout, Friedman and Isakov (cf. [6]) it is possible to describe the exact behaviour of $u_{P}$ in a neighborhood of the vertices of $T^{P}$. In particular, the following estimates hold true
Proposition 3.2. There exist a constant $\omega>\frac{1}{2}$ and two positive constants $\delta_{0}$ and $C$ depending only on $\alpha_{0}, \alpha_{1}, k$ and $d_{0}$ such that, for $j=1,2,3$

$$
\begin{align*}
& \left|\nabla u_{P}^{i}(x, y)\right| \leq C\|u\|_{L^{2}(\Omega)} \quad \operatorname{dist}\left((x, y), P_{j}\right)^{\omega-1}  \tag{3.3}\\
& \left|\nabla u_{P}^{e}(x, y)\right| \leq C\|u\|_{L^{2}(\Omega)} \quad \operatorname{dist}\left((x, y), P_{j}\right)^{\omega-1} \tag{3.4}
\end{align*}
$$

for all $(x, y) \in B\left(P_{j}, \delta_{0}\right) \backslash\left\{P_{j}\right\}$.
Remark 3.3. In all the results that we state and prove from now on, the estimates depend linearly on the norms of the boundary data $f$ and $g$. For this reason, for sake of simplicity, we normalize functions $f$ and $g$ by taking

$$
\|f\|_{H^{1 / 2}(\partial \Omega)}=\|g\|_{H^{1 / 2}(\partial \Omega)}=1
$$

in the proofs, while we explicitly write the dependence on the norms in the statements.

We can prove the following energy estimates
Proposition 3.4. Let $P^{0} \in \mathcal{V}$ and $u_{0}$ be the solution of (2.1) corresponding to the triangle $T^{0}$ of vertices $P^{0}=\left(P_{1}^{0}, P_{2}^{0}, P_{3}^{0}\right)$. Let $u_{t}$ be the solution of (2.1) corresponding to the triangle $T^{t}$ of vertices $P^{t}=\left(P_{1}^{t}, P_{2}^{t}, P_{3}^{t}\right)$ with $P_{i}^{t}=P_{i}^{0}+t \vec{V}_{i}$, $i=1,2,3$ and $\vec{V}=\left(\vec{V}_{1} \cdot \vec{V}_{2}, \vec{V}_{3}\right)$ a vector in $\mathbb{R}^{2} \times \mathbb{R}^{2} \times \mathbb{R}^{2}$. Then, there exist positive constants $C$ and $0<\theta<\frac{1}{2}$ independent of $t$, such that

$$
\begin{equation*}
\left\|u_{t}-u_{0}\right\|_{H^{1}(\Omega)} \leq C\|f\|_{H^{1 / 2}(\partial \Omega)} t^{\theta} \tag{3.5}
\end{equation*}
$$

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for $|t|<d_{0} /(2|\vec{V}|)$.
Proof. Consider $w_{t}=u_{t}-u_{0}$. Then, $w_{t}$ solves

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{t} \nabla w_{t}\right) & =\operatorname{div}\left(\left(\sigma_{0}-\sigma_{t}\right) \nabla u_{0}\right) \text { in } \Omega, \\
w_{t} & =0 \text { on } \partial \Omega .
\end{aligned}\right.
$$

Multiplying the above equation by $w_{t}$, integrating over $\Omega$ and integrating by parts we get

$$
\begin{equation*}
\int_{\Omega} \sigma_{t}\left|\nabla w_{t}\right|^{2}=\int_{T^{t} \Delta T^{0}}\left(\sigma_{0}-\sigma_{t}\right) \nabla u_{0} \cdot \nabla w_{t} \tag{3.6}
\end{equation*}
$$

and by

$$
\sigma_{t} \geq \min \{1, k\}
$$

we get

$$
\begin{aligned}
\int_{\Omega}\left|\nabla w_{t}\right|^{2} & \leq \frac{|k-1|}{\min \{1, k\}} \int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|\left|\nabla w_{t}\right| \\
& \leq \frac{|k-1|}{\min \{1, k\}}\left(\int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2}\right)^{1 / 2}\left(\int_{T^{t} \Delta T^{0}}\left|\nabla w_{t}\right|^{2}\right)^{1 / 2} \\
& \leq \frac{|k-1|}{\min \{1, k\}}\left(\int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2}\right)^{1 / 2}\left(\int_{\Omega}\left|\nabla w_{t}\right|^{2}\right)^{1 / 2} .
\end{aligned}
$$

Hence,

$$
\int_{\Omega}\left|\nabla w_{t}\right|^{2} \leq\left(\frac{|k-1|}{\min \{1, k\}}\right)^{2} \int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2}
$$

Let $\mathcal{S}_{\delta_{t}}=\cup_{j=1}^{3} B\left(P_{j}^{0}, \delta_{t}\right)$ with $\delta_{t}>0$ to be chosen later. Using (3.1) and (3.2) we obtain the following bounds

$$
\begin{aligned}
\int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2} & =\int_{\left(T^{t} \Delta T^{0}\right) \cap \mathcal{S}_{\delta_{t}}}\left|\nabla u_{0}\right|^{2}+\int_{\left(T^{t} \Delta T^{0}\right) \backslash \mathcal{S}_{\delta_{t}}}\left|\nabla u_{0}\right|^{2} \\
& \leq \int_{\left(T^{t} \Delta T^{0}\right) \cap \mathcal{S}_{\delta_{t}}}\left|\nabla u_{0}\right|^{2}+\sup _{\left(T^{t} \Delta T^{0}\right) \backslash \mathcal{S}_{\delta_{t}}}\left|\nabla u_{0}\right|^{2}\left|T^{t} \Delta T^{0}\right| \\
& \leq \int_{\left(T^{t} \Delta T^{0}\right) \cap S_{\delta_{t}}}\left|\nabla u_{0}\right|^{2}+\frac{C t}{\delta_{t}^{2(\gamma+1)}} \\
& \leq \int_{\left(T^{t} \Delta T^{0}\right) \cap \mathcal{S}_{\delta_{t}}}\left|\nabla u_{0}\right|^{2}+\frac{C t}{\delta_{t}^{2(\gamma+1)}} .
\end{aligned}
$$

Now, using (3.3), for any $j=1,2,3$, we get

$$
\begin{aligned}
\int_{T^{t} \Delta T^{0} \cap B\left(P_{j}^{0}, \delta_{t}\right)}\left|\nabla u_{0}\right|^{2} & \leq C \int_{B\left(P_{j}^{0}, \delta_{t}\right)}\left(\operatorname{dist}\left((x, y), P_{j}\right)\right)^{2(\omega-1)} \\
& \leq C \int_{0}^{\theta_{j}} \int_{0}^{\delta_{t}} \rho^{2(\omega-1)} \rho d \rho d \theta \leq C \int_{0}^{\delta_{t}} \rho^{2 \omega-1} d \rho \leq C \delta_{t}^{2 \omega} .
\end{aligned}
$$

In conclusion, we have

$$
\int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2} \leq C\left(\delta_{t}^{2 \omega}+\frac{t}{\delta_{t}^{2(\gamma+1)}}\right) .
$$

Picking up $\delta_{t}=t^{\alpha}$ with $\alpha=\frac{1}{2(\omega+\gamma+1)}$ we derive

$$
\int_{T^{t} \Delta T^{0}}\left|\nabla u_{0}\right|^{2} \leq C t^{\frac{\omega}{\omega+\gamma+1}}
$$

Finally, by last inequality and by (3.6) we obtain

$$
\left(\int_{\Omega}\left|\nabla w_{t}\right|^{2}\right)^{1 / 2} \leq C t^{\frac{\omega}{2(\omega+\gamma+1)}}=C t^{\theta}
$$

with $0<\theta<\frac{1}{2}$ which ends the proof.

We have also the following
Proposition 3.5. Let $\mathcal{L}=\bigcup_{j=1}^{3}\left(B\left(P_{j}^{0}, \delta_{t}\right) \cup B\left(P_{j}^{t}, \delta_{t}\right)\right)$ with $\delta_{t}=t^{\beta_{1}}$ and $\beta_{1}=$ $\frac{\theta \gamma}{2(\gamma+1)}$ and let $u_{t}$ and $u_{0}$ be defined as in Proposition 3.4. Then, there exists a positive constant $C$, independent of $t$, such that
(3.7) $\left\|\nabla u_{t}^{e}-\nabla u_{0}^{e}\right\|_{L^{\infty}\left(\partial T^{t} \backslash\left(T^{0} \cup \mathcal{L}\right)\right.}+\left\|\nabla u_{t}^{i}-\nabla u_{0}^{i}\right\|_{L^{\infty}\left(\partial T^{t} \cap T^{0} \backslash \mathcal{L}\right)} \leq C\|f\|_{H^{1 / 2}(\partial \Omega)} t^{\beta_{1}}$ and

$$
\left\|\nabla u_{t}^{e}-\nabla u_{0}^{e}\right\|_{L^{\infty}\left(\partial T^{0} \backslash\left(T^{t} \cup \mathcal{L}\right)\right.}+\left\|\nabla u_{t}^{i}-\nabla u_{0}^{i}\right\|_{L^{\infty}\left(\partial T^{0} \cap T^{t} \backslash \mathcal{L}\right)} \leq C\|f\|_{H^{1 / 2}(\partial \Omega)} t^{\beta_{1}}
$$ for $|t|<d_{0} /(2|\vec{V}|)$.

Proof. It is sufficient to show the first inequality (3.7) since (3.8) follows similarly. Let $t<d<\frac{d_{0}}{2}$ and denote by

$$
\Omega_{d}^{t}=\left\{(x, y) \in \Omega \backslash\left(T^{t} \cup T^{0}\right): \operatorname{dist}\left((x, y), \partial\left(\Omega \backslash\left(T^{t} \cup T^{0}\right)\right)\right) \geq d\right\}
$$

Observe that since $\nabla\left(u_{t}^{e}-u_{0}^{e}\right)$ is harmonic in $\Omega \backslash\left(T^{t} \cup T^{0}\right)$, by the mean value theorem we get

$$
\left\|\nabla u_{t}^{e}-\nabla u_{0}^{e}\right\|_{L^{\infty}\left(\Omega_{d}^{t}\right)} \leq \frac{C}{d}\left\|\nabla u_{t}-\nabla u_{0}\right\|_{L^{2}(\Omega)}
$$

Then, by (3.5) we obtain

$$
\begin{equation*}
\left\|\nabla u_{t}^{e}-\nabla u_{0}^{e}\right\|_{L^{\infty}\left(\Omega_{d}^{t}\right)} \leq \frac{C}{d} t^{\theta} \tag{3.9}
\end{equation*}
$$

Let now $(x, y) \in \partial T^{t} \backslash\left(T^{0} \cup \mathcal{L}\right)$ and let $\left(x_{d}, y_{d}\right)$ be the closest point to $(x, y)$ in $\Omega_{d}^{t}$. Then, by Proposition 3.1 we have

$$
\left|\nabla u_{t}^{e}(x, y)-\nabla u_{t}^{e}\left(x_{d}, y_{d}\right)\right| \leq C \frac{d^{\gamma}}{\delta_{t}^{\gamma+1}}
$$

and

$$
\left|\nabla u_{0}^{e}(x, y)-\nabla u_{0}^{e}\left(x_{d}, y_{d}\right)\right| \leq C \frac{d^{\gamma}}{\delta_{t}^{\gamma+1}}
$$

Combining last two inequalities with (3.9) we get

$$
\left|\nabla u_{t}^{e}(x, y)-\nabla u_{0}^{e}(x, y)\right| \leq C\left(\frac{d^{\gamma}}{\delta_{t}^{\gamma+1}}+\frac{t^{\theta}}{d}\right)
$$

By choosing $d=t^{\frac{\theta+\beta_{1}(\gamma+1)}{\gamma+1}}$ and $\delta_{t}=t^{\frac{\theta \gamma}{2(\gamma+1)}}$ we obtain, for $(x, y) \in \partial T^{t} \backslash\left(T^{0} \cup \mathcal{L}\right)$,

$$
\left|\nabla u_{t}^{e}(x, y)-\nabla u_{0}^{e}(x, y)\right| \leq C t^{\frac{\theta_{\gamma}}{2(\gamma+1)}}
$$

so that

$$
\left\|\nabla u_{t}^{e}-\nabla u_{0}^{e}\right\|_{L^{\infty}\left(\partial T^{t} \backslash\left(T^{0} \cup \mathcal{L}\right)\right)} \leq C t^{\frac{\theta \gamma}{2(\gamma+1)}}
$$

Let now $(x, y) \in\left(\partial T^{t} \cap T^{0}\right) \backslash \mathcal{L}$ and define the set

$$
\left(T^{t} \cap T^{0}\right)_{d}=\left\{(x, y) \in T^{t} \cap T^{0}: \operatorname{dist}\left((x, y), \partial T^{t} \cup \partial T^{0}\right) \geq d\right\}
$$

and let $\left(x_{d}, y_{d}\right) \in\left(T^{t} \cap T^{0}\right)_{d}$ be the closest point to $(x, y)$. Since, $\nabla\left(u_{t}^{i}-u_{0}^{i}\right)$ is harmonic in $T^{t} \cap T^{0}$ we get, applying the mean value theorem and using (3.5)

$$
\left\|\nabla u_{t}^{i}-\nabla u_{0}^{i}\right\|_{L^{\infty}\left(\left(T^{t} \cap T^{0}\right)_{d}\right)} \leq \frac{C}{d} t^{\theta}
$$

and by (3.1) we get

$$
\left|\nabla u_{t}^{i}(x, y)-\nabla u_{0}^{i}(x, y)\right| \leq\left(\frac{d^{\gamma}}{\delta_{t}^{\gamma+1}}+\frac{t^{\theta}}{d}\right)
$$

and choosing $d=t^{\frac{\theta+\beta_{1}(\gamma+1)}{\gamma+1}}$ and $\delta_{t}=t^{\frac{\theta \gamma}{2(\gamma+1)}}$ we finally derive

$$
\left\|\nabla u_{t}^{i}-\nabla u_{0}^{i}\right\|_{L^{\infty}\left(\left(\partial T^{t} \cap T^{0}\right) \backslash \mathcal{L}\right)} \leq C t^{\frac{\theta \gamma}{2(\gamma+1)}}
$$

which concludes the proof.

## 4. Proof of the main result

In order to prove our main result we will first establish the validity of (2.3) for particular choices of the vector $\vec{V}$. Indeed, we first consider a special direction $\vec{V}=$ $\left(\vec{V}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ where $\vec{V}_{1}$ is $\frac{P_{2}^{0}-P_{1}^{0}}{\left|P_{2}^{0}-P_{1}^{0}\right|}$ or $\frac{P_{3}^{0}-P_{1}^{0}}{\left|P_{3}^{0}-P_{1}^{0}\right|}$. The reason for this choice is that $T^{0} \triangle T^{t}$, that is the support of $\sigma_{t}-\sigma_{0}$, is easier to describe. Then we consider $\vec{V}=\left(\overrightarrow{v_{1}}, \overrightarrow{0}, \overrightarrow{0}\right)$ where $\vec{v}_{1}$ is an arbitrary vector that we decompose as a linear combination of the vectors $\frac{P_{2}^{0}-P_{1}^{0}}{\left|P_{2}^{0}-P_{1}^{0}\right|}$ and $\frac{P_{3}^{0}-P_{1}^{0}}{\left|P_{3}^{0}-P_{1}^{0}\right|}$. In order to perform this step we need to show that the functional

$$
D(t):=\int_{\partial T^{t}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot \vec{n}_{t}\right) d \sigma
$$

is continuous at $t=0$. The last step is just based on linearity of the limit process.
Lemma 4.1. Let $\vec{V}=\left(\vec{V}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ where $\vec{V}_{1}=\frac{P_{2}^{0}-P_{1}^{0}}{\left|P_{2}^{0}-P_{1}^{0}\right|},\left(\frac{P_{3}^{0}-P_{1}^{0}}{\left|P_{3}^{0}-P_{1}^{0}\right|}\right)$. Then

$$
\begin{align*}
& \mid G(t)-G(0)- t(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \mid  \tag{4.1}\\
& \leq C t^{1+\alpha}\|f\|_{H^{1 / 2}(\partial \Omega)}\|g\|_{H^{1 / 2}(\partial \Omega)}
\end{align*}
$$

for $|t|<d_{0} / 2$.
Proof. Without loss of generality let $\vec{V}=\left(\frac{P_{2}^{0}-P_{1}^{0}}{\mid P_{2}^{0}-P_{1}^{0}}, \overrightarrow{0}, \overrightarrow{0}\right)$ and consider $P^{t}=P^{0}+$ $t \vec{V}$. By Alessandrini's identity

$$
\begin{equation*}
\frac{G(t)-G(0)}{t}=\frac{1}{t}<\left(\Lambda_{t}-\Lambda_{0}\right) f, g>=\frac{1}{t} \int_{\Omega}\left(\sigma_{t}-\sigma_{0}\right) \nabla u_{t} \cdot \nabla v_{0} \tag{4.2}
\end{equation*}
$$

where $\Lambda_{t}:=\Lambda_{\sigma_{t}}$ and $\Lambda_{0}:=\Lambda_{\sigma_{0}}$ and $u_{t}$ is solution to Problem (2.1) corresponding to $\sigma_{t}$ and $v_{0}$ the solution to Problem (2.2) corresponding to $\sigma_{0}$. We choose a coordinate frame in such a way that $P_{1}^{0}=(0,0), P_{2}^{0}=\left(-x_{2}, 0\right), x_{2}>0, P_{3}^{0}=\left(x_{3}, y_{3}\right)$ with
$y_{3}<0$. Then, $\vec{V}=\left(-\vec{e}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ and $P^{t}=\left((-t, 0),\left(-x_{2}, 0\right),\left(x_{3}, y_{3}\right)\right)$. Assume $t>0$ (the case $t<0$ can be treated similarly) and consider the set

$$
\mathcal{C}_{\delta_{t}}=T^{0} \backslash\left(T^{t} \cup\left\{(x, y):-\delta_{t}<y<y_{3}+\delta_{t}\right\}\right),
$$

where $\delta_{t}$ will be chosen later. For every $(x, y) \in \mathcal{C}_{\delta_{t}}$ let $(x(y), y)=\left(\frac{x_{3}}{y_{3}} y, y\right)$ be the corresponding point on the side $P_{2}^{0} P_{1}^{0}$ of $T^{0}$. By Proposition 3.1 applied to $u_{t}^{e}$ and $v_{0}^{i}$ we get

$$
\begin{align*}
\nabla u_{t}^{e}(x, y) & =\nabla u_{t}^{e}(x(y), y)+R_{1}(x, y) \\
\nabla v_{0}^{e}(x, y) & =\nabla v_{0}^{e}(x(y), y)+R_{2}(x, y) \tag{4.3}
\end{align*}
$$

where

$$
\left|R_{i}(x, y)\right| \leq C \frac{|x-x(y)|^{\gamma}}{\delta_{t}^{\gamma+1}}, \quad i=1,2
$$

Since

$$
|x-x(y)| \leq\left|x_{1}(y)-x(y)\right| \leq t \frac{\left|y-y_{3}\right|}{\left|y_{3}\right|}
$$

where $x_{1}(y)=\frac{x_{3}+t}{y_{3}} y-t$, we get

$$
\begin{equation*}
\left|R_{i}(x, y)\right| \leq C \frac{t^{\gamma}}{\delta_{t}^{\gamma+1}} \frac{\left|y-y_{3}\right|}{\left|y_{3}\right|}, \quad i=1,2 . \tag{4.4}
\end{equation*}
$$

Using (4.2) we can write

$$
\begin{equation*}
\frac{G(t)-G(0)}{t}=\frac{1-k}{t} \int_{\mathcal{C}_{\delta_{t}}} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i}+\frac{1-k}{t} \int_{T^{0} \backslash\left(T^{t} \cup \mathcal{C}_{\delta_{t}}\right)} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i}=I_{1}+I_{2} \tag{4.5}
\end{equation*}
$$

Let us first estimate $I_{1}$. We use (3.3) and (3.4) and we split the integral over $\mathcal{C}_{\delta_{t}}=\mathcal{C}_{\delta_{t}}^{1} \cup \mathcal{C}_{\delta_{t}}^{2}$ in two parts

$$
\begin{aligned}
\left|\frac{1}{t} \int_{\mathcal{C}_{\delta_{t}}^{1}} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i}\right| & =\left|\frac{1}{t} \int_{-\delta_{t}}^{0}\left(\int_{x_{1}(y)}^{x(y)} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i} d x\right) d y\right| \\
& \leq \frac{C}{t} \int_{-\delta_{t}}^{0}\left(\int_{-t}^{0} \frac{d x}{\left((x+t)^{2}+y^{2}\right)^{\frac{1-\omega}{2}}\left(x^{2}+y^{2}\right)^{\frac{1-\omega}{2}}}\right) d y
\end{aligned}
$$

By the change of variables $x=t X$ and $y=t Y$ we get

$$
\begin{aligned}
\left|\frac{1}{t} \int_{\mathcal{C}_{\delta_{t}}^{1}} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i}\right| & \leq C \frac{t^{2 \omega}}{t} \int_{-\delta_{t} / t}^{0}\left(\int_{-1}^{0} \frac{d X}{\left((X+1)^{2}+Y^{2}\right)^{\frac{1-\omega}{2}}\left(X^{2}+Y^{2}\right)^{\frac{1-\omega}{2}}}\right) d Y \\
& \leq C \delta_{t}^{2 \omega-1} \int_{-\frac{\delta_{t}}{t}}^{0} \frac{d Y}{|Y|^{2-2 \omega} \leq C t^{2 \omega-1}\left(\frac{\delta_{t}}{t}\right)^{2 \omega-1} \leq C \delta_{t}^{2 \omega-1}}
\end{aligned}
$$

and proceeding similarly one can see that

$$
\begin{aligned}
\left|\frac{1}{t} \int_{\mathcal{C}_{\delta_{t}}^{2}} \nabla u_{t}^{e} \cdot \nabla v_{0}^{i}\right| & \leq\left|\frac{C}{t} \int_{y_{3}}^{y_{3}+\delta_{t}}\left(\int_{x_{1}(y)}^{x(y)} \frac{d x}{\left(\left(x-x_{3}\right)^{2}+\left(y-y_{3}\right)^{2}\right)^{1-\omega}}\right) d y\right| \\
& \leq C \int_{y_{3}}^{y_{3}+\delta_{t}} \frac{d y}{\left(\left(x(y)-x_{3}\right)^{2}+\left(y-y_{3}\right)^{2}\right)^{1-\omega}} \\
& \leq C \int_{y_{3}}^{y_{3}+\delta_{t}} \frac{d y}{\left(y-y_{3}\right)^{2-2 \omega}} \leq C \delta_{t}^{2 \omega-1}
\end{aligned}
$$

Hence, alltogether we end up with

$$
\begin{equation*}
\left|I_{1}\right| \leq C \delta_{t}^{2 \omega-1} \tag{4.6}
\end{equation*}
$$

Let us now consider $I_{2}$ and let $B_{t}=T^{0} \backslash\left(T^{t} \cup \mathcal{C}_{\delta_{t}}\right)$. Inserting (4.3) into $I_{2}$ leads to

$$
\begin{aligned}
I_{2} & =\frac{1-k}{t}\left\{\int_{B_{t}} \nabla u_{t}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y) d x d y\right. \\
& \left.+\int_{B_{t}}\left(R_{1}(x, y) \cdot \nabla v_{0}^{i}(x, y)+\nabla u_{t}^{e}(x, y) \cdot R_{2}(x, y)+R_{1}(x, y) \cdot R_{2}(x, y)\right) d x d y\right\} \\
& =: \quad I_{3}+I_{4}
\end{aligned}
$$

Let us evaluate $I_{3}$. We know that

$$
\begin{aligned}
I_{3} & =\frac{(1-k)}{t} \int_{B_{t}} \nabla u_{t}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y) d x d y \\
& =\frac{(1-k)}{t} \int_{y_{3}+\delta_{t}}^{-\delta_{t}} \nabla u_{t}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(x(y)-x_{1}(y)\right) d y \\
& =(1-k) \int_{y_{3}+\delta_{t}}^{-\delta_{t}} \nabla u_{t}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y \\
& =(1-k) \int_{y_{3}+\delta_{t}}^{-\delta_{t}}\left(\nabla u_{0}^{e}(x(y), y)+\rho(y, t)\right) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y \\
(\rho(y, t) & \left.:=\nabla u_{t}^{e}(x(y), y)-\nabla u_{0}^{e}(x(y), y)\right) \\
& =(1-k)\left\{\int_{y_{3}+\delta_{t}}^{-\delta_{t}} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+\right. \\
& \left.+\int_{y_{3}+\delta_{t}}^{-\delta_{t}} \rho(y, t) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y\right\} \\
& =(1-k)\left\{\int_{y_{3}}^{0} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y-\right. \\
& -\int_{\left[-\delta_{t}, 0\right] \cup\left[y_{3}+\delta_{t}, y_{3}\right]} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+ \\
& \left.+\int_{y_{3}+\delta_{t}}^{-\delta_{t}} \rho(y, t) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y\right\} .
\end{aligned}
$$

Observe now that

$$
\begin{aligned}
& \left|\int_{\left[-\delta_{t}, 0\right] \cup\left[y_{3}+\delta_{t}, y_{3}\right]} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y\right| \\
& \quad \leq \int_{\left[-\delta_{t}, 0\right] \cup\left[y_{3}+\delta_{t}, y_{3}\right]}\left|\nabla u_{0}^{e}(x(y), y)\right|\left|\nabla v_{0}^{i}(x(y), y)\right| d y .
\end{aligned}
$$

From Proposition 3.2 and using the fact that $\omega>1 / 2$, we get

$$
\begin{aligned}
\int_{\left[-\delta_{t}, 0\right]}\left|\nabla u_{0}^{e}(x(y), y)\right|\left|\nabla v_{0}^{i}(x(y), y)\right| d y & \leq C \int_{\left[-\delta_{t}, 0\right]} \frac{d y}{\left(y^{2}+(x(y))^{2}\right)^{1-\omega}} \\
& \leq C \int_{\left[-\delta_{t}, 0\right]} \frac{d y}{|y|^{2(1-\omega)} \leq C \delta_{t}^{2 \omega-1}}
\end{aligned}
$$

For $\int_{\left[y_{3}+\delta_{t}, y_{3}\right]}\left|\nabla u_{0}^{e}(x(y), y)\right|\left|\nabla v_{0}^{i}(x(y), y)\right| d y$ we can proceed similary getting

$$
\int_{\left[y_{3}+\delta_{t}, y_{3}\right]}\left|\nabla u_{0}^{e}(x(y), y)\right|\left|\nabla v_{0}^{i}(x(y), y)\right| d y \leq C \delta_{t}^{2 \omega-1}
$$

Hence, we have

$$
\begin{aligned}
I_{3} & =(1-k)\left\{\int_{y_{3}}^{0} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+\right. \\
& \left.+\int_{y_{3}+\delta_{t}}^{-\delta_{t}} \rho(y, t) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+O\left(\delta_{t}^{2 \omega-1}\right)\right\}
\end{aligned}
$$

Note that the following estimate holds

$$
\begin{align*}
\int_{y_{3}+\delta_{t}}^{-\delta_{t}}\left|\nabla v_{0}^{i}(x(y), y)\right| d y \leq & \int_{y_{3}+\delta_{t}}^{y_{3} / 2} \frac{d y}{\left.\left(x(y)-x_{3}\right)^{2}+\left(y-y_{3}-\delta_{t}\right)^{2}\right)^{\frac{1-\omega}{2}}}+  \tag{4.7}\\
& +\int_{y_{3} / 2}^{-\delta_{t}} \frac{d y}{\left(x(y)^{2}+y^{2}\right)^{\frac{1-\omega}{2}}} \leq C .
\end{align*}
$$

Applying Proposition 3.5 for $\delta_{t}=t^{\beta_{1}}$ with $\beta_{1}=\frac{\theta \gamma}{2(\gamma+1)}$ we have

$$
|\rho(y, t)| \leq C t^{\beta_{1}}
$$

By last inequality and by (4.7) we derive

$$
\left|\int_{y_{3}+\delta_{t}}^{-\delta_{t}} \rho(y, t) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y\right| \leq C t^{\beta_{1}}
$$

Eventually, we get

$$
\begin{equation*}
I_{3}=(1-k) \int_{y_{3}}^{0} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+O\left(t^{\beta_{2}}\right) \tag{4.8}
\end{equation*}
$$

where $\beta_{2}=\min \left\{\beta_{1},(2 \omega-1) \beta_{1}\right\}$.
Finally, let us evaluate $I_{4}$.
Using the estimates (3.3), (3.4), (3.7), (4.3) and (4.4) and choosing $\delta_{t}=t^{\beta_{1}}$ with $\beta_{1}=\frac{\theta \gamma}{2(\gamma+1)}$ as in Proposition 3.5 we can estimate $I_{4}$ in the following way

$$
\begin{aligned}
&\left|I_{4}\right| \leq \frac{C}{t} \int_{y_{3}+\delta_{t}}^{-\delta_{t}} d y \int_{x_{1}(y)}^{x(y)}\left\{\frac { t ^ { \gamma } } { \delta _ { t } ^ { \gamma + 1 } } | \frac { y - y _ { 3 } } { y _ { 3 } } | ^ { \gamma } \left(\left|\nabla u_{t}^{e}(x(y), y)\right|+\right.\right. \\
&\left.\left.\quad+\left|\nabla v_{0}^{i}(x(y), y)\right|\right)+\frac{t^{2 \gamma}}{\delta_{t}^{2(\gamma+1)}}\left|\frac{y-y_{3}}{y_{3}}\right|^{2 \gamma}\right\} d x \\
& \leq \frac{C}{t} \int_{y_{3}+\delta_{t}}^{-\delta_{t}}\left|x(y)-x_{1}(y)\right|\left\{\frac{t^{\gamma}}{\delta_{t}^{\gamma+1}}\left(\left|\nabla u_{t}^{e}(x(y), y)\right|+\left|\nabla v_{0}^{i}(x(y), y)\right|\right)+\frac{t^{2 \gamma}}{\delta_{t}^{2(\gamma+1)}}\right\} d y \\
& \leq C \int_{y_{3}+\delta_{t}}^{-\delta_{t}} \frac{t^{\gamma}}{\delta_{t}^{\gamma+1}}\left(\left|\nabla u_{t}^{e}(x(y), y)\right|+\left|\nabla v_{0}^{i}(x(y), y)\right|\right) d y+C\left(\frac{t^{\gamma}}{\delta_{t}^{\gamma+1}}\right)^{2} .
\end{aligned}
$$

Finally, using the fact that, by Proposition 3.5

$$
\left|\nabla u_{t}^{e}(x(y), y)\right| \leq\left|\nabla u_{0}^{e}(x(y), y)\right|+C t^{\beta_{1}}
$$

and noting that, proceeding similarly as in (4.7), we have $\int_{y_{3}+\delta_{t}}^{-\delta_{t}}\left|\nabla u_{0}^{e}(x(y), y)\right| \leq C$ we get

$$
\begin{equation*}
\left|I_{4}\right| \leq C t^{\left(1-\frac{\theta}{2}\right) \gamma}\left(1+t^{\beta_{1}}+t^{\left(1-\frac{\theta}{2}\right) \gamma}\right) \tag{4.9}
\end{equation*}
$$

Inserting (4.6), (4.8) and (4.9) into (4.5) we get

$$
\frac{G(t)-G(0)}{t}=(1-k) \int_{y_{3}}^{0} \nabla u_{0}^{e}(x(y), y) \cdot \nabla v_{0}^{i}(x(y), y)\left(\frac{y-y_{3}}{-y_{3}}\right) d y+r(t)
$$

where $|r(t)| \leq C t^{\beta_{3}}$ where $\beta_{3}=\min \left(\beta_{1}, \beta_{2},\left(1-\frac{\theta}{2}\right) \gamma\right)$. Finally, observing that $\Phi_{0}^{\vec{V}} \cdot \vec{n}_{0}=\frac{y_{3}-y}{\sqrt{x_{3}^{2}+y_{3}^{2}}}$ on the side $P_{3}^{0} P_{1}^{0}$ and $\Phi_{0}^{\vec{V}} \cdot \vec{n}_{0}=0$ on the other sides of $T^{0}$ we can write

$$
\frac{G(t)-G(0)}{t}=(k-1) \int_{\partial T^{0}} \nabla u_{0}^{e} \cdot \nabla v^{i}\left(\Phi_{0}^{\vec{V}} \cdot \vec{n}_{0}\right) d \sigma+r(t)
$$

Finally, using the transmission conditions we have

$$
\nabla v_{0}^{i}=M_{0} \nabla v_{0}^{e} \text { a.e. on } \partial T^{0}
$$

and we get

$$
\begin{aligned}
\frac{G(t)-G(0)}{t} & =(k-1) \int_{\partial T^{0}} \nabla u_{0}^{e} \cdot M_{0} \nabla v^{e}\left(\Phi_{0}^{\vec{V}} \cdot \vec{n}_{0}\right) d \sigma+r(t) \\
& =(k-1) \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v^{e}\left(\Phi_{0}^{\vec{V}} \cdot \vec{n}_{0}\right) d \sigma+r(t)
\end{aligned}
$$

from which the claim follows.

Remark 4.2. Observe that an analogous formula can be derived similarly choosing $\vec{V}=\left(\overrightarrow{0}, \vec{V}_{2}, \overrightarrow{0}\right)$ where $\vec{V}_{2}=\frac{P_{1}^{0}-P_{2}^{0}}{\left|P_{1}^{0}-P_{2}^{0}\right|},\left(\frac{P_{3}^{0}-P_{2}^{0}}{\left|P_{3}^{0}-P_{2}^{0}\right|}\right)$ or $\vec{V}=\left(\overrightarrow{0}, \overrightarrow{0}, \vec{V}_{3}\right)$ where $\vec{V}_{3}=$ $\frac{P_{1}^{0}-P_{3}^{0}}{\left|P_{1}^{0}-P_{3}^{0}\right|},\left(\frac{P_{2}^{0}-P_{3}^{0}}{\left|P_{2}^{0}-P_{3}^{0}\right|}\right)$.

Remark 4.3. We note that the formula 4.1) applies also to the case where $\vec{V}$ is not a unit vector. In fact, using the linearity of the map $\Phi^{\vec{V}}$ an easy computation gives

$$
\begin{aligned}
G^{\prime}(0) & =(k-1)|\vec{V}| \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\frac{\vec{V}}{\mid \vec{V}}} \cdot n_{0}\right) d \sigma \\
& =(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
\end{aligned}
$$

Let now $\vec{V}$ indicate an arbitrary vector of $\mathbb{R}^{2} \times \mathbb{R}^{2} \times \mathbb{R}^{2}$ and let $T^{0}$ be a triangle of vertices $P^{0} \in \mathcal{V}$. Let $P^{t}=P^{0}+t \vec{W}$ for $t$ sufficiently small and with $\vec{W}=\left(\vec{w}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ and let $T^{t}$ be the triangle of vertices $P^{t}$. Consider

$$
D(t):=\int_{\partial T^{t}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma
$$

where $u_{t}$ and $v_{t}$ are respectively the solutions of (2.1) and (2.2) corresponding to $\sigma_{t}$ and $n_{t}$ is the unit outer normal to $\partial T^{t}$. Then, we have the following

Lemma 4.4. There exists constants $\beta \in(0,1)$ and $C>0$ independent on $t$ such that

$$
|D(t)-D(0)| \leq C\|f\|_{H^{1 / 2}(\partial \Omega)}\|g\|_{H^{1 / 2}(\partial \Omega)} t^{\beta}
$$

for $|t|<d_{0} /(2|\vec{V}|)$.
Proof. Let $\mathcal{L}=\bigcup_{j=1}^{3}\left(B\left(P_{j}^{0}, \delta_{t}\right) \cup B\left(P_{j}^{t}, \delta_{t}\right)\right)$ with $\delta_{t}=t^{\beta_{1}}$ with $\beta_{1}$ defined as in Lemma 4.1. Let us consider

$$
\begin{align*}
D(t)-D(0) & =\int_{\partial T^{t} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{\partial T^{0} \backslash \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \\
& +\int_{\partial T^{t} \cap \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{\partial T^{0} \cap \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma  \tag{4.10}\\
& =J_{1}-J_{2}+J_{3}-J_{4}
\end{align*}
$$

We assume without loss of generality that $t>0$. Let us start estimating $J_{3}$ and $J_{4}$. We accomplish this proceeding with similar calculations as in the estimation of $I_{1}$ in Lemma 4.1. In fact, we have

$$
\begin{equation*}
\left|J_{3}\right|,\left|J_{4}\right| \leq C \delta_{t}^{(2 \omega-1)} \leq C t^{(2 \omega-1) \beta_{1}} \tag{4.11}
\end{equation*}
$$

Let us now estimate

$$
J_{1}-J_{2}=\int_{\partial T^{t} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{\partial T^{0} \backslash \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

From this last difference we just consider and estimate

$$
\int_{P_{1}^{t} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

since the terms on $P_{1}^{t} P_{3}^{0}$ and on $P_{1}^{0} P_{3}^{0}$ can be treated similarly. Let us evaluate, then,

$$
\begin{aligned}
& \int_{P_{1}^{t} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \\
= & \int_{P_{1}^{t} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma \\
+ & \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \\
= & A_{1}+A_{2} .
\end{aligned}
$$

We have

$$
\begin{aligned}
A_{2}= & \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}}\left\{M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right)\right\} d \sigma \\
= & \int_{P_{1}^{0} P_{2}^{o} \backslash \mathcal{L}}\left\{\left(M_{t}-M_{0}\right) \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right)+\right. \\
& \left.\quad+M_{0}\left(\nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right)-\nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right)\right)\right\} d \sigma \\
= & \int_{P_{1}^{0} P_{2}^{o} \backslash \mathcal{L}}\left(M_{t}-M_{0}\right) \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma \\
& +\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{0}\left(\nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\right)\left(\Phi_{t}^{\vec{V}} \cdot n_{t}-\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \\
& +\int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}} M_{0}\left(\nabla u_{t}^{e} \cdot \nabla v_{t}^{e}-\nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma .
\end{aligned}
$$

Using now the following estimates

$$
\begin{align*}
\left|M_{t}-M_{0}\right|,\left|\Phi_{t}^{\vec{V}} \cdot n_{t}-\Phi_{0}^{\vec{V}} \cdot n_{0}\right| & \leq C t \\
\left|\Phi_{t}^{\vec{V}}\left(Q_{1}\right)-\Phi_{t}^{\vec{V}}\left(Q_{2}\right)\right|,\left|\Phi_{0}^{\vec{V}}\left(Q_{1}\right)-\Phi_{0}^{\vec{V}}\left(Q_{2}\right)\right| & \leq C\left|Q_{1}-Q_{2}\right|  \tag{4.12}\\
\left|M_{0}\right|,\left|\Phi_{0}^{\vec{V}} \cdot n_{0}\right|,\left|\Phi_{t}^{\vec{V}} \cdot n_{t}\right| & \leq C
\end{align*}
$$

where $C$ is independent on $t$, and the fact that $\left|\nabla u_{0}^{e}\right|,\left|\nabla v_{0}^{e}\right| \in L^{1}$ and (4.4), we obtain

$$
\begin{aligned}
\left|A_{2}\right| & \leq C t \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}}\left|\nabla u_{t}^{e}\right|\left|\nabla v_{t}^{e}\right|+C \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}}\left(\nabla u_{t}^{e} \cdot \nabla v_{t}^{e}-\nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right) \\
& \leq C t \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}}\left(\left|\nabla u_{0}^{e}\right|+t^{\beta_{1}}\right)\left(\left|\nabla v_{0}^{e}\right|+t^{\beta_{1}}\right) \\
& +C \int_{P_{1}^{0} P_{2}^{0} \backslash \mathcal{L}}\left(\left|R_{1}\right|\left|\nabla v_{0}^{e}(x(y), y)\right|+\left|R_{2}\right|\left|\nabla u_{0}^{e}(x(y), y)\right|+\left|R_{1}\right|\left|R_{2}\right|\right) \\
& \leq C\left(t+\frac{t^{\gamma}}{\delta_{t}^{\gamma+1}}+\left(\frac{t^{\gamma}}{\delta_{t}^{\gamma+1}}\right)^{2}\right) .
\end{aligned}
$$

Finally, recalling the definition of $\delta_{t}$ we have

$$
\left|A_{2}\right| \leq C t^{\gamma\left(1-\frac{\theta}{2}\right)} .
$$

Let us now consider

$$
\left|A_{1}\right|=\left|\int_{P_{1}^{t} P_{2}^{0} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma-\int_{P_{1}^{0} P_{2}^{o} \backslash \mathcal{L}} M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) d \sigma\right| .
$$

Let us set

$$
F_{t}=M_{t} \nabla u_{t}^{e} \cdot \nabla v_{t}^{e}\left(\Phi_{t}^{\vec{V}} \cdot n_{t}\right) .
$$

Then, assuming without loss of generality that $P_{1}^{0}=(0,0)$ and $P_{2}^{0}=\left(-x_{2}, 0\right)$ with $x_{2}>0$, we can write, for a suitable positive $c$ and $c_{1}$,

$$
\int_{P_{1}^{t} P_{2}^{0} \backslash \mathcal{L}} F_{t} d \sigma=\int_{x_{2}+\frac{\delta_{t}}{c}}^{-\frac{\delta_{t}}{c}} F_{t}\left(x_{t}(\eta), y_{t}(\eta)\right) \sqrt{\left(x_{t}^{\prime}(\eta)\right)^{2}+\left(y_{t}^{\prime}(\eta)\right)^{2}} d \eta
$$

and we consequently obtain

$$
\begin{aligned}
&\left|A_{1}\right|=\left\lvert\, \int_{x_{2}+\frac{\delta_{t}}{c}}^{-\frac{\delta_{t}}{c}} F_{t}\left(x_{t}(\eta), y_{t}(\eta)\right) \sqrt{\left(x_{t}^{\prime}(\eta)\right)^{2}+\left(y_{t}^{\prime}(\eta)\right)^{2}} d \eta\right. \\
& \left.-\int_{x_{2}+\frac{\delta_{t}}{c}}^{-\frac{\delta_{t}}{c}} F_{t}(\eta, 0) d \eta+\int_{I_{\delta_{t}}} F_{t}(\eta, 0) d \eta \right\rvert\,
\end{aligned}
$$

where $I_{\delta_{t}}=\left[-\frac{\delta_{t}}{c_{1}},-\frac{\delta_{t}}{c}\right] \cup\left[x_{2}+\frac{\delta_{t}}{c_{1}}, x_{2}+\frac{\delta_{t}}{c}\right]$. Note now, that by Proposition 3.1 and estimates (4.12), we have

$$
\left|F_{t}\left(x_{t}(\eta), y_{t}(\eta)\right)-F_{t}(\eta, 0)\right| \leq \frac{C}{\delta_{t}^{2(\gamma+1)}} t^{\gamma} \leq C t^{\gamma\left(1-\frac{\theta}{2}\right)}
$$

and also by using Proposition 3.2 we have

$$
\left|\int_{I_{\delta_{t}}} F_{t}(\eta, 0) d \eta\right| \leq C \delta_{t}^{2 \omega-1} \leq C t^{\beta_{1}(2 \omega-1)}
$$

In conclusion, we derive an estimate for $J_{1}-J_{2}$

$$
\begin{equation*}
\left|J_{1}-J_{2}\right| \leq C t^{\beta} \tag{4.13}
\end{equation*}
$$

where $\beta=\min \left(\beta_{1}, \beta_{1}(2 \omega-1), \gamma\left(1-\frac{\theta}{2}\right)\right)$. Insertion of (4.13) and (4.11) into (4.10) concludes the proof.

We are now ready to prove our main result.

Proof of Theorem 2.1. We proceed in two steps. First we prove the claim for $\vec{V}=\left(\vec{V}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ where $\vec{V}_{1}=\left(v_{1}, v_{2}\right)$. Assume without loss of generality that $P_{1}^{0}=(0,0)$ and $P_{2}^{0}=\left(-x_{2}, 0\right)$ with $x_{2}>0$ and $P_{3}^{0}=\left(x_{3}, y_{3}\right)$ with $y_{3}<0$. Let $T^{t}$ be the triangle of vertices $P^{t}=P^{0}+t \vec{V}$ and let $\bar{P}_{1}^{t}$ denote the intersection of the side $P_{1}^{t} P_{3}^{0}$ with the side $P_{1}^{0} P_{2}^{0}$ axis. Assume without loss of generality $t>0$. We now decompose the displacement from $T^{0}$ to $T^{t}$ as the superposition of the dispalcement from $T^{0}$ to $\bar{T}^{t}$ of vertices $\bar{P}^{t}=\left(\bar{P}_{1}^{t}, P_{2}^{0}, P_{3}^{0}\right)$ and the one from $\bar{T}^{t}$ to $T^{t}$. By Lemma4.1 applied in the direction of $\bar{P}^{t}-P^{0}=\left(\vec{w}_{1}^{t}, \overrightarrow{0}, \overrightarrow{0}\right)$ where $\vec{w}_{1}^{t}=-\lambda_{t} \vec{e}_{1}$ and $\lambda_{t}=v_{2} \frac{x_{3}-t v_{1}}{y_{3}-t v_{2}}-v_{1}$ and Remark 3.3 we get

$$
F\left(\bar{P}^{t}\right)-F\left(P^{0}\right)=(k-1) t \lambda_{t} \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{W}_{1}^{0}} \cdot n_{0}\right) d \sigma+\sigma_{1}(t)
$$

where $\vec{W}_{1}^{0}=\left(-\vec{e}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$ and $\sigma_{1}(t)=o(t)$ as $t \rightarrow 0$. Hence, also

$$
\begin{equation*}
F\left(\bar{P}^{t}\right)-F\left(P^{0}\right)=(k-1) t \lambda_{0} \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{W}_{1}^{0}} \cdot n_{0}\right) d \sigma+\sigma_{1}(t) \tag{4.14}
\end{equation*}
$$

with $\lambda_{0}=v_{2} \frac{x_{3}}{y_{3}}-v_{1}$.

To compute $F\left(P^{t}\right)-F\left(\bar{P}^{t}\right)$ we now apply Lemma 4.1] in the direction $\vec{W}_{2}^{t}=\bar{P}^{t}-P^{t}=\left(\vec{w}_{2}^{t}, \overrightarrow{0}, \overrightarrow{0}\right)$. Then, again by Lemma 4.1, we can write

$$
\begin{aligned}
F\left(P^{t}\right)-F\left(\bar{P}^{t}\right)= & F\left(\bar{P}^{t}+\mu_{t} \vec{W}_{2}^{t}\right)-F\left(\bar{P}^{t}\right)=\int_{0}^{\mu_{t}} \frac{d}{d \eta} F\left(\bar{P}^{t}+\eta \vec{W}_{2}^{t}\right) d \eta \\
= & \int_{0}^{\mu_{t}}\left(\frac{d}{d \eta} F\left(\bar{P}^{t}+\eta \vec{W}_{2}^{t}\right)-\left.\frac{d}{d \eta} F\left(\bar{P}^{t}+\eta \vec{W}_{2}^{t}\right)\right|_{\eta=0}\right) d \eta \\
& +\left.\mu_{t} \frac{d}{d \eta} F\left(\bar{P}^{t}+\eta \vec{W}_{2}^{t}\right)\right|_{\eta=0}
\end{aligned}
$$

and, by Lemma 4.4,

$$
\left.\left|F\left(\bar{P}^{t}+\mu_{t} \vec{W}_{2}^{t}\right)-F\left(\bar{P}^{t}\right)-\mu_{t} \frac{d}{d \eta} F\left(\bar{P}^{t}+\eta \vec{W}_{2}^{t}\right)\right|_{\eta=0}\left|\leq C t^{\beta}\right| \mu_{t} \right\rvert\, \leq C t^{\beta+1}
$$

where $\mu_{t}=\left|\bar{P}^{t}-P^{t}\right|=t\left|v_{2}\right| \sqrt{\left(\frac{x_{3}-t v_{1}}{y_{3}-t v_{2}}\right)^{2}+1}$ and we get

$$
\begin{equation*}
F\left(P^{t}\right)-F\left(\bar{P}^{t}\right)=(k-1) t \mu_{0} \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{W}_{2}^{0}} \cdot n_{0}\right) d \sigma+r(t) \tag{4.15}
\end{equation*}
$$

where $|r(t)| \leq C t^{\beta+1}, \mu_{0}=\left|v_{2}\right| \sqrt{\frac{x_{3}^{2}}{y_{3}^{2}}+1}$ and $\vec{W}_{2}^{0}=\frac{v_{2}}{\left|v_{2}\right|}\left(\frac{\left(\frac{x_{3}}{y_{3}}, 1\right)}{\sqrt{\frac{x_{3}^{2}}{y_{3}^{2}}+1}}, \overrightarrow{0}, \overrightarrow{0}\right)$.
Finally, putting (4.14) and (4.15) together, we end up with the following formula

$$
\begin{aligned}
F\left(P^{t}\right)-F\left(P^{0}\right)= & (k-1) t\left\{\lambda_{0} \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{W}_{1}^{0}} \cdot n_{0}\right) d \sigma+\right. \\
& \left.\quad+\mu_{0} \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{W}_{2}^{0}} \cdot n_{0}\right) d \sigma\right\}+r(t) \\
= & (k-1) t \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\lambda_{0} \vec{W}_{1}^{0}+\mu_{0} \vec{W}_{2}^{0}} \cdot n_{0}\right) d \sigma+r(t)
\end{aligned}
$$

and since

$$
\lambda_{0} \vec{W}_{1}^{0}+\mu_{0} \vec{W}_{2}^{0}=\vec{V}
$$

the statement of step 1 follows.
Now we are left with the general case where we consider an arbitrary vector $\vec{V}=$ $\left(\vec{v}_{1}, \vec{v}_{2}, \vec{v}_{3}\right)$. Let $P^{t}=P^{0}+t \vec{V}$; we consider now the displacement form $T^{0}$ to $T^{t}$ as superposition of three displacements. The first one for $T^{0}$ to $\bar{T}^{t}$ of vertices $\bar{P}^{t}=\left(P_{1}^{0}+t \vec{v}_{1}, P_{2}^{0}, P_{3}^{0}\right)$, the second one from $\bar{T}^{t}$ to $\tilde{T}^{t}$ of vertices $\tilde{P}^{t}=\left(P_{1}^{0}+\right.$ $\left.t \vec{v}_{1}, P_{2}^{0}+t \vec{v}_{2}, P_{3}^{0}\right)$ and the third one from $\tilde{T}^{t}$ to $T^{t}$. We then split
$F\left(P^{t}\right)-F\left(P^{0}\right)=F\left(P^{t}\right)-F\left(\tilde{P}^{t}\right)+F\left(\tilde{P}^{t}\right)-F\left(\bar{P}^{t}\right)+F\left(\bar{P}^{t}\right)-F\left(P^{0}\right)=D_{1}+D_{2}+D_{3}$
The last term $D_{3}$ can be estimated using the result obtained in the first step of the proof. Indeed,

$$
D_{3}=(k-1) t \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}_{1}^{0}} \cdot n_{0}\right) d \sigma+r(t)
$$

where $\vec{V}_{1}=\left(\vec{v}_{1}, \overrightarrow{0}, \overrightarrow{0}\right)$. For $D_{2}$ we proceed similarly as in step 1 decomposing the displacement from $\bar{T}^{t}$ to $\tilde{T}^{t}$ as superposition of the displacements along the sides
obtaining

$$
D_{2}=(k-1) t \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}_{2}^{0}} \cdot n_{0}\right) d \sigma+r(t)
$$

where $\vec{V}_{2}=\left(\overrightarrow{0}, \vec{v}_{2}, \overrightarrow{0}\right)$ and analogously

$$
D_{1}=(k-1) t \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}_{3}^{0}} \cdot n_{0}\right) d \sigma+r(t)
$$

where $\vec{V}_{3}=\left(\overrightarrow{0}, \overrightarrow{0}, \vec{v}_{3}\right)$. Finally, summing up $D_{1}, D_{2}$ and $D_{3}$ we eventually get

$$
F\left(P^{t}\right)-F\left(P^{0}\right)=(k-1) t \int_{\partial T^{0}} M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma+r(t)
$$

thus ending the proof.

Corollary 4.5. The map $P \rightarrow \Lambda_{\sigma_{P}}$ is differentiable.
Proof. If we define the linear operator

$$
\tilde{L}: H^{1 / 2}(\partial \Omega) \rightarrow H^{-1 / 2}(\partial \Omega)
$$

by

$$
<\tilde{L}(f), g>=(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

we can state (2.3) as

$$
\begin{equation*}
\left\|\Lambda_{\sigma_{P_{t}}}-\Lambda_{\sigma_{P}}-t \tilde{L}\right\|_{\mathcal{L}\left(H^{1 / 2}(\partial \Omega), H^{-1 / 2}(\partial \Omega)\right)} \leq C t^{1+\alpha} \tag{4.16}
\end{equation*}
$$

Since $\tilde{L}$ is linear in $\vec{V}$ and by continuity of $\tilde{L}$ with respect to $P$ (see Lemma 4.4), we actually obtained the differentiability of the map $P \rightarrow \Lambda_{\sigma_{P}}$.

A similar result can be derived when considering, instead of the Dirichlet to Neumann map, the Neumann to Dirichlet map with suitable normalization conditions. In fact, consider the spaces

$$
H_{\diamond}^{1 / 2}(\partial \Omega)=\left\{f \in H^{1 / 2}(\partial \Omega): \int_{\partial \Omega} f=0\right\}
$$

and

$$
H_{\diamond}^{-1 / 2}(\partial \Omega)=\left\{g \in H^{-1 / 2}(\partial \Omega):<g, 1>=0\right\} .
$$

It is well known that the Dirichlet to Neumann map maps onto $H_{\diamond}^{-1 / 2}(\partial \Omega)$ and when restricted to $H_{\diamond}^{1 / 2}(\partial \Omega)$ it is injective and has bounded inverse. So, we can define the Neumann to Dirichlet map as the inverse of the Dirichlet to Neumann map restricted to $H_{\diamond}^{1 / 2}(\partial \Omega)$ i.e.

$$
\mathcal{N}_{\sigma_{P}}: H_{\diamond}^{-1 / 2}(\partial \Omega) \rightarrow H_{\diamond}^{1 / 2}(\partial \Omega)
$$

with

$$
\mathcal{N}_{\sigma_{P}}=\left(\left.\Lambda_{\sigma_{P}}\right|_{H_{\diamond}^{1 / 2}(\partial \Omega)}\right)^{-1}
$$

For $f, g \in H_{\diamond}^{-1 / 2}(\partial \Omega)$ we can define $\tilde{F}: \mathcal{V} \rightarrow \mathbb{R}$ as follows

$$
\tilde{F}(P)=<g, \mathcal{N}_{\sigma_{P}}(f)>\quad \forall P \in \mathcal{V}
$$

Consider now $P^{0}=\left(P_{1}^{0}, P_{2}^{0}, P_{3}^{0}\right) \in \mathcal{V}$ and the corresponding triangle denoted by $T^{0}$. Let $\vec{V}=\left(\vec{V}_{1}, \vec{V}_{2}, \vec{V}_{3}\right) \in \mathbb{R}^{2} \times \mathbb{R}^{2} \times \mathbb{R}^{2}$ be an arbitrary vector and let $\Phi_{0}^{\vec{V}}: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ be the affine map that gives

$$
\Phi_{0}^{\vec{V}}\left(P_{i}^{0}\right)=\vec{V}_{i}, \quad i=1,2,3 .
$$

Consider now $P^{t}=P^{0}+t \vec{V}=\left(P_{1}^{t}, P_{2}^{t}, P_{3}^{t}\right)$ for $t \in[0,1]$ and the triangle of vertices $P^{t}$ that we denote by $T^{t}$ and denote by $\tilde{G}(t)=\tilde{F}\left(P^{t}\right)$.
Let $\sigma_{0}=1+(k-1) \chi_{T^{0}}$ and let $u_{0} \in H^{1}(\Omega)$ the unique weak solution to

$$
\left\{\begin{align*}
\operatorname{div}\left(\sigma_{0} \nabla u_{0}\right) & =0 \text { in } \Omega  \tag{4.17}\\
\frac{\partial u_{0}}{\partial \nu} & =f \text { on } \partial \Omega, \\
\int_{\partial \Omega} u_{0} & =0
\end{align*}\right.
$$

Denote by $v_{0}$ the solution of

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{0} \nabla v_{0}\right) & =0 \text { in } \Omega \\
\frac{\partial v_{0}}{\partial \nu} & =g \text { on } \partial \Omega \\
\int_{\partial \Omega} v_{0} & =0
\end{aligned}\right.
$$

Finally, denote by $u_{t}:=u_{P^{t}}$ the solution of (4.17) corresponding to $\sigma_{t}=1+(k-$ 1) $\chi_{T^{t}}$ and by $v_{t}$ the solution to

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{t} \nabla v_{t}\right) & =0 \text { in } \Omega, \\
\frac{\partial v_{t}}{\partial \nu} & =g \text { on } \partial \Omega, \\
\int_{\partial \Omega} v_{t} & =0 .
\end{aligned}\right.
$$

Let

$$
u_{0}^{e}=\left.u_{0}\right|_{\Omega \backslash T^{0}}, \quad v_{0}^{e}=\left.v_{0}\right|_{\Omega \backslash T^{0}} .
$$

We have the following:
Theorem 4.6. There exits two positive constants $C$ and $\alpha$ depending only on $L$, $d_{0}, \alpha_{1}, \alpha_{0}, k$, such that

$$
\begin{aligned}
& \mid \tilde{G}(t)-\tilde{G}(0)- t(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \mid \\
& \leq C t^{1+\alpha}\|f\|_{H^{-1 / 2}(\partial \Omega)}\|g\|_{H^{-1 / 2}(\partial \Omega)},
\end{aligned}
$$

for $|t|<d_{0} /(2|\vec{V}|)$, that implies

$$
\tilde{G}^{\prime}(0)=(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

The proof of Theorem 4.6 can be derived similarly as the one of Theorem 2.1 observing that all the preliminary results of Section 2 continue to hold also for solutions to the Neumann problem and that

$$
\frac{\tilde{G}(t)-\tilde{G}(0)}{t}=\frac{1}{t}<g,\left(\mathcal{N}_{t}-\mathcal{N}_{0}\right)(f)>=\frac{1}{t} \int_{\Omega}\left(\sigma_{t}-\sigma_{0}\right) \nabla u_{t} \cdot \nabla v_{0}
$$

## 5. A Shape derivative approach to an optimization problem

We now want to see some interesting consequences of Theorem4.6.
Let $u_{P} \in H^{1}(\Omega)$ be the unique weak solution to

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{P} \nabla u_{P}\right) & =0 \text { in } \Omega, \\
\frac{\partial u_{P}}{\partial \nu} & =f \text { on } \partial \Omega, \\
\int_{\partial \Omega} u_{P} & =0
\end{aligned}\right.
$$

corresponding to conductivity $\sigma_{P}=1+(k-1) \chi_{T^{P}}$ and let $\left.u\right|_{\partial \Omega}=u_{\text {meas }}$. It is well known by the results obtained in [7] that under suitable choice of $f$ the datum $u_{\text {meas }}$ uniquely determines the triangle $T^{P} \subset \Omega$.
Let $T^{0}$ of vertices $P^{0}$ be an initial guess close enough to the exact solution $T^{P}$. Let $\sigma_{t}=1+(k-1) \chi_{T^{t}}$ where $T^{t}$ has vertices $P^{t}=P^{0}+t \vec{V}=\left(P_{1}^{t}, P_{2}^{t}, P_{3}^{t}\right)$ and $u_{t}$ is the solution to (4.17) for $\sigma_{t}=1+(k-1) \chi_{T^{t}}$.
Consider the following boundary functional

$$
\mathcal{J}\left(T^{t}\right)=\frac{1}{2} \int_{\partial \Omega}\left(u_{t}-u_{\text {meas }}\right)^{2}
$$

and consider the optimization problem of minimizing the functional with respect to all possible affine motions of the triangle $T^{0}$. It is well known that in order to solve this minimization problem we might use an iterative procedure like for example Newton's method which involves the computation of shape derivative of the functional $\mathcal{J}\left(T^{t}\right)$ (see [3], [5], [10] and [14]).
We now will derive a formula for the shape derivative of the functional $\mathcal{J}\left(T^{t}\right)$ defined as

$$
D \mathcal{J}\left(T^{0}\right)[\vec{V}]=\lim _{t \rightarrow 0} \frac{\mathcal{J}\left(T^{t}\right)-\mathcal{J}\left(T^{0}\right)}{t} .
$$

For, we will show the following preliminary result.
Lemma 5.1. There exists positive constants $C$ and $\beta>0$ such that

$$
\begin{equation*}
\left\|u_{t}-u_{0}\right\|_{L^{2}(\partial \Omega)} \leq C t^{1+\beta} \tag{5.1}
\end{equation*}
$$

for $|t|<d_{0} /(2|\vec{V}|)$.
Proof. Let $w_{t}$ be the solution to the problem

$$
\left\{\begin{aligned}
\operatorname{div}\left(\sigma_{0} \nabla w_{t}\right) & =0 \text { in } \Omega \\
\frac{\partial w_{t}}{\partial \nu} & =u_{t}-u_{0} \text { on } \partial \Omega \\
\int_{\partial \Omega} w_{t} & =0
\end{aligned}\right.
$$

From Theorem 4.6 we have

$$
\begin{align*}
<g,\left(\mathcal{N}_{t}-\mathcal{N}_{0}\right)(f)> & =<g, u_{t}-u_{0}> \\
& =(k-1) t \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma+r(t) \tag{5.2}
\end{align*}
$$

for any $g \in H^{-1 / 2}(\partial \Omega)$ and where

$$
\begin{equation*}
|r(t)| \leq C t^{1+\beta} \tag{5.3}
\end{equation*}
$$

with $\beta=\min \left(\beta_{1}, \beta_{1}(2 \omega-1), \gamma\left(1-\frac{\theta}{2}\right)\right)$. Choosing $g=u_{t}-u_{0}$ and since $u_{t}-u_{0} \in$ $L^{2}(\partial \Omega)$ we can rewrite last relation in the form

$$
\begin{equation*}
\int_{\partial \Omega}\left(u_{t}-u_{0}\right)^{2}=(k-1) t \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma+r(t) \tag{5.4}
\end{equation*}
$$

We now estimate the first term on the right hand side of (5.4). Observe that by the energy estimates

$$
\left\|w_{t}\right\|_{H^{1}(\Omega)} \leq C\left\|u_{t}-u_{0}\right\|_{L^{2}(\partial \Omega)} \leq C\left\|u_{t}-u_{0}\right\|_{H^{1}(\Omega)} \leq C t^{\theta}
$$

and arguing similary as in Proposition 3.5 we get

$$
\begin{equation*}
\left\|\nabla w_{t}\right\|_{L^{\infty}\left(\partial T^{0} \backslash \mathcal{L}\right)} \leq C t^{\beta_{1}} \tag{5.5}
\end{equation*}
$$

We split

$$
\begin{aligned}
\int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma= & \int_{\partial T^{0} \backslash \mathcal{L}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma \\
& +\int_{\partial T^{0} \cap \mathcal{L}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
\end{aligned}
$$

By (5.5) and by the fact that $\left|\nabla u_{0}^{e}\right| \in L^{1}$ we have

$$
\left|\int_{\partial T^{0} \backslash \mathcal{L}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma\right| \leq C\left\|\nabla w_{t}\right\|_{L^{\infty}\left(\partial T^{0} \backslash \mathcal{L}\right)} \int_{\partial T^{0} \backslash \mathcal{L}}\left|\nabla u_{0}^{e}\right| \leq C t^{\beta_{1}}
$$

On the other hand proceeding as in Lemma 4.4 we have that

$$
\left|\int_{\partial T^{0} \cap \mathcal{L}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma\right| \leq C t^{\beta_{2}}=C t^{\beta_{1}(2 \omega-1)} .
$$

Hence, we have

$$
\left|t \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{t}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma\right| \leq C t^{1+\min \left(\beta_{1}, \beta_{1}(2 \omega-1)\right)}
$$

and inserting last inequality and (5.3) into (5.4) we get (5.1).

Let

$$
\left\{\begin{align*}
\operatorname{div}\left(\sigma_{0} \nabla w_{0}\right) & =0 \text { in } \Omega  \tag{5.6}\\
\frac{\partial w_{0}}{\partial \nu} & =u_{0}-u_{\text {meas }} \text { on } \partial \Omega \\
\int_{\partial \Omega} w_{0} & =0
\end{align*}\right.
$$

We are now ready to prove

## Proposition 5.2.

$$
D \mathcal{J}\left(T^{0}\right)[\vec{V}]=(k-1) \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla w_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma
$$

where $u_{0}$ denotes the solution to 4.17) corresponding to $\sigma_{T^{0}}$ and $w_{0}$ the solution to (5.6).

Proof. Let us consider

$$
\begin{aligned}
\mathcal{J}\left(T^{t}\right)-\mathcal{J}\left(T^{0}\right) & =\frac{1}{2} \int_{\partial \Omega}\left(u_{t}-u_{\text {meas }}\right)^{2}-\frac{1}{2} \int_{\partial \Omega}\left(u_{0}-u_{\text {meas }}\right)^{2} \\
& =\int_{\partial \Omega}\left(u_{0}-u_{\text {meas }}\right)\left(u_{t}-u_{0}\right)+\frac{1}{2} \int_{\partial \Omega}\left(u_{t}-u_{0}\right)^{2} .
\end{aligned}
$$

Then, by Lemma 5.1 and by (5.2) applied for $g=u_{0}-u_{\text {meas }}$ we get

$$
\begin{aligned}
\mathcal{J}\left(T^{t}\right)-\mathcal{J}\left(T^{0}\right) & =\int_{\partial \Omega}\left(u_{0}-u_{\text {meas }}\right)\left(u_{t}-u_{0}\right)+o(t) \\
& =(k-1) t \int_{\partial T^{0}}\left(M_{0} \nabla u_{0}^{e} \cdot \nabla v_{0}^{e}\right)\left(\Phi_{0}^{\vec{V}} \cdot n_{0}\right) d \sigma+o(t)
\end{aligned}
$$

Finally, dividing last expression by $t$ and passing to the limit as $t \rightarrow 0$ the thesis follows.

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