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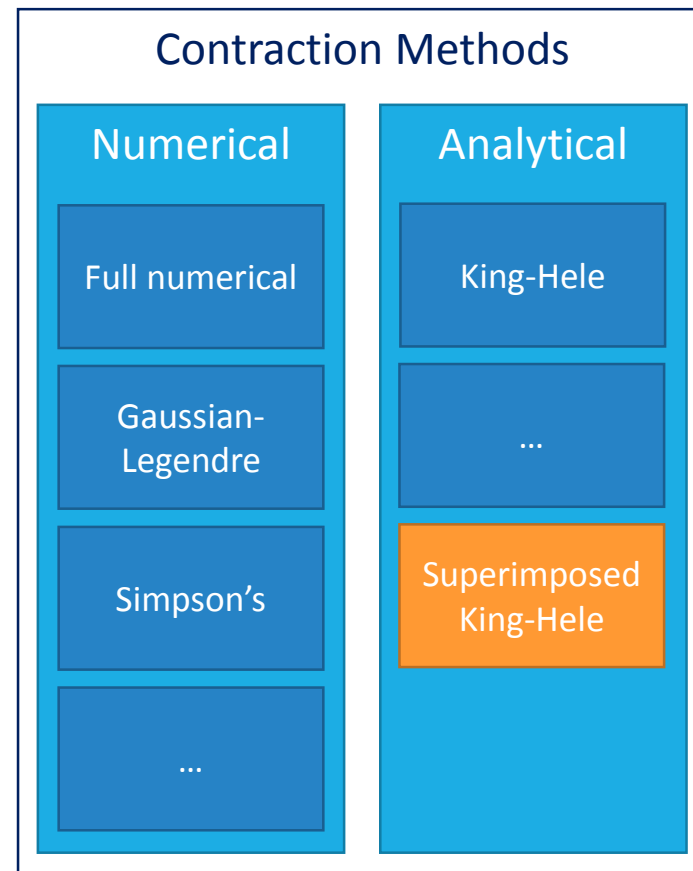
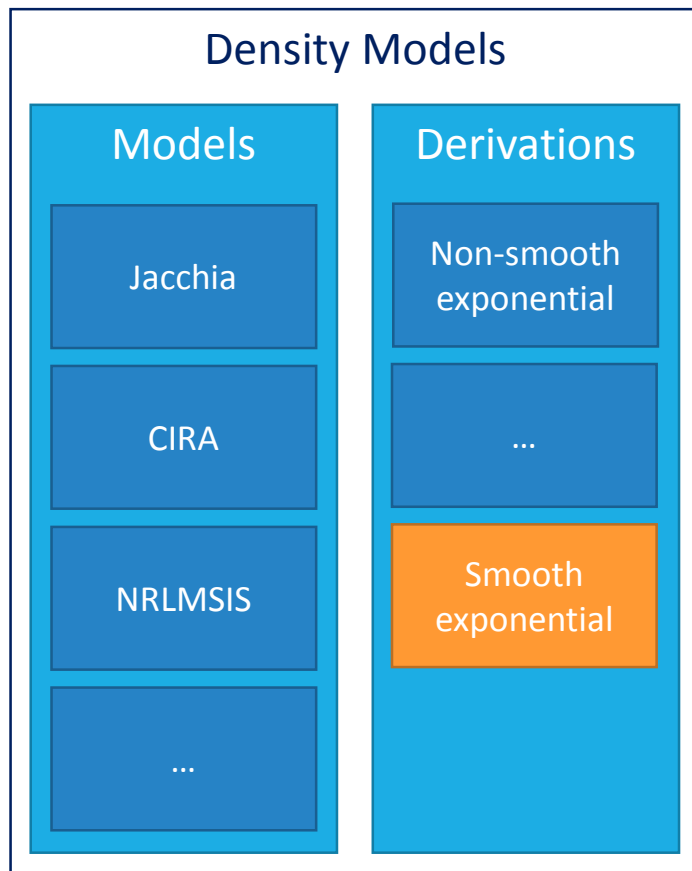
# Superimposition of the atmosphere density for fast and accurate semi-analytical propagation

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- Overall project
  - density based cloud propagation
  - of fragments originating from explosions or collisions
  - in all orbital regions
  - using semi-analytical methods
- Problems
  - most common atmosphere models are either
    - non-smooth or
    - expensive in terms of density evaluations
  - inaccurate results due to approximations especially for eccentric orbits



## Non-Smooth Atmosphere Model

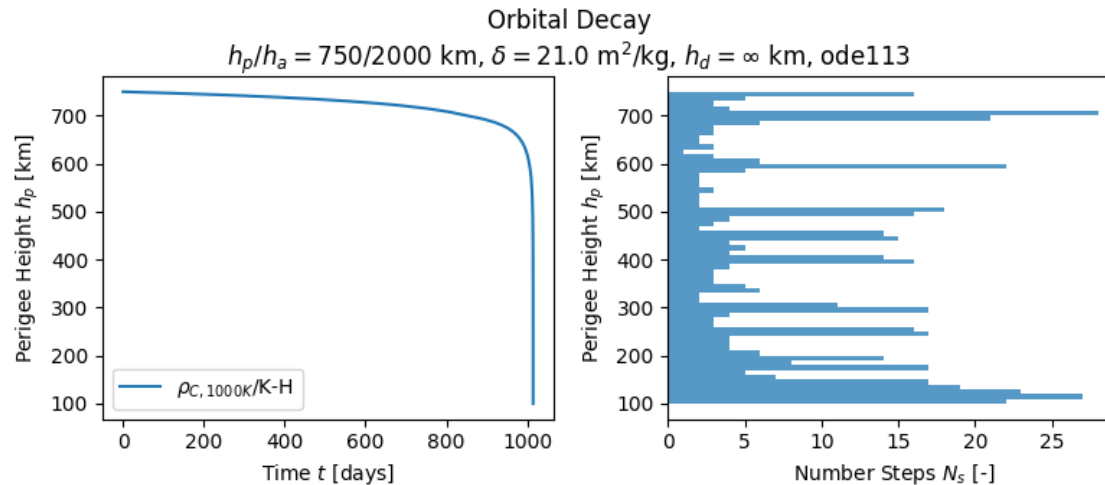
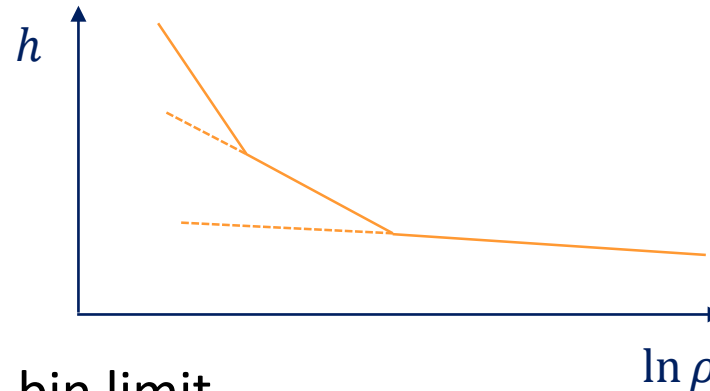
- Definition: for each altitude bin

$$\rho_C(h) = \rho_{0,i} \exp\left(-\frac{h - h_i}{H_i}\right)$$

$$h_i < h < h_{i+1}$$

- Problems

- non-smooth transition at each bin limit
- forces the variable step size integrator to increase number of steps



## Dynamical System

- Modified Lagrange's planetary equations in
- Ignoring all perturbations, apart from tangential drag force

$$f_T = \frac{1}{2} \rho v^2 \delta$$

- In this case, the dynamics become

$$\dot{a} = -\frac{a^2 \rho \delta v^3}{\mu}$$

$$\dot{e} = -\frac{a \rho \delta v}{r} (1 - e^2) \cos E$$

$$\dot{E} = \frac{1}{r} \sqrt{\frac{\mu}{a}}$$

where

$a$	semi-major axis
$e$	eccentricity
$E$	eccentric anomaly
$\mu$	gravitational parameter
$r$	radial distance
$v$	velocity
$\delta^{-1}$	ballistic coefficient
$\rho$	density

- This system propagated numerically is the baseline

## Dynamical System

- Over full period, the dynamics become (assuming  $a$  and  $e$  to be fixed)

$$\Delta a = -a^2 \delta \int_0^{2\pi} \rho \frac{(1 + e \cos E)^{3/2}}{(1 - e \cos E)^{1/2}} dE$$

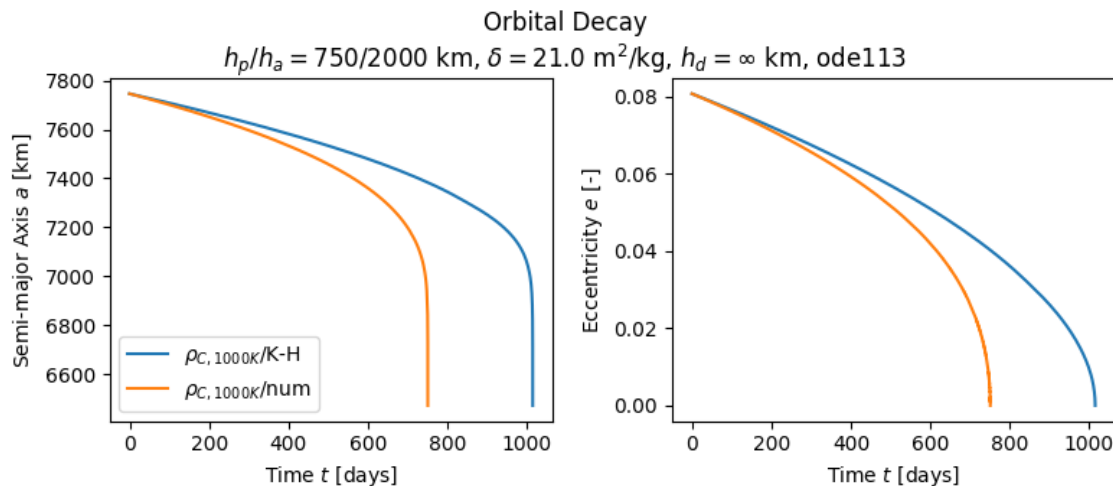
$$\Delta e = -a \delta \int_0^{2\pi} \rho \frac{(1 + e \cos E)^{1/2}}{(1 - e \cos E)^{1/2}} \cos E (1 - e^2) dE$$

- This system needs approximation, if full numerical integration is to be avoided
- Then the following semi-analytical propagation can be performed

$$\dot{x} = \frac{dx}{dt} \approx \frac{\Delta x}{\Delta t} = \frac{\Delta x}{P} \quad x \in \{a, e\} \quad \text{where } P \text{ is the period}$$

## Approximation of Integral: King-Hele

- Analytical approximation of the integral, using series expansion, assuming  $H$  to be constant above perigee\*
- Dis-/Advantages
  - constant  $H$  assumptions introduces large errors for eccentric orbits
  - discontinuity between transition of low/high eccentric approximation
  - + retain analytic formulation



\*another approach is to linearly fit  $H = H_0 + \eta(h - h_0)$ , but the slope parameter  $\eta$  depends on the orbit configuration

## Approximation of Integral: Quadrature

- Numerical approximation of the integral using quadrature:
  - Evaluate the integrand at nodes  $n$  and sum them weighted with  $w_i$
  - Here, Gauss-Legendre quadrature was chosen (with  $n = 33$ )

$$\int_0^{2\pi} f(E)dE \approx \pi \sum_{i=1}^n w_i f(E_i)$$

- Dis-/Advantages
  - + independent of atmosphere model
  - + no series expansion necessary; valid across all conditions (however care needs to be taken for low perigees)
  - not an analytical solution; cannot directly derive Jacobian or find closed form solution for lifetime

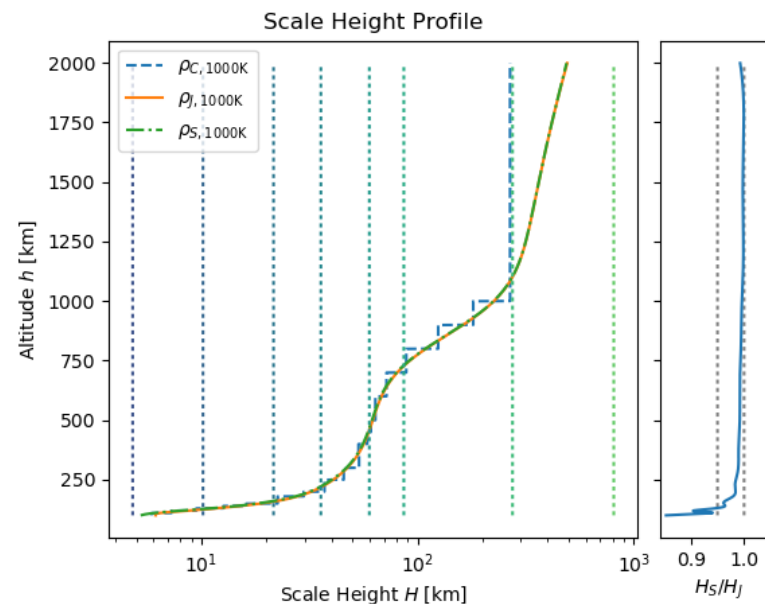
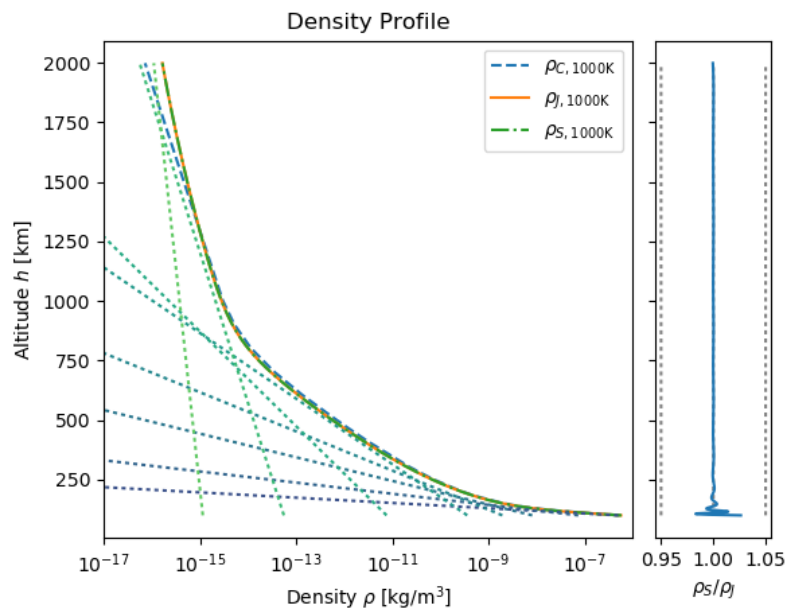


## Smooth Exponential Atmosphere Model

- Atmosphere as sum of exponentials (idea is not new, older Jacchia models have one exponential per constituent)

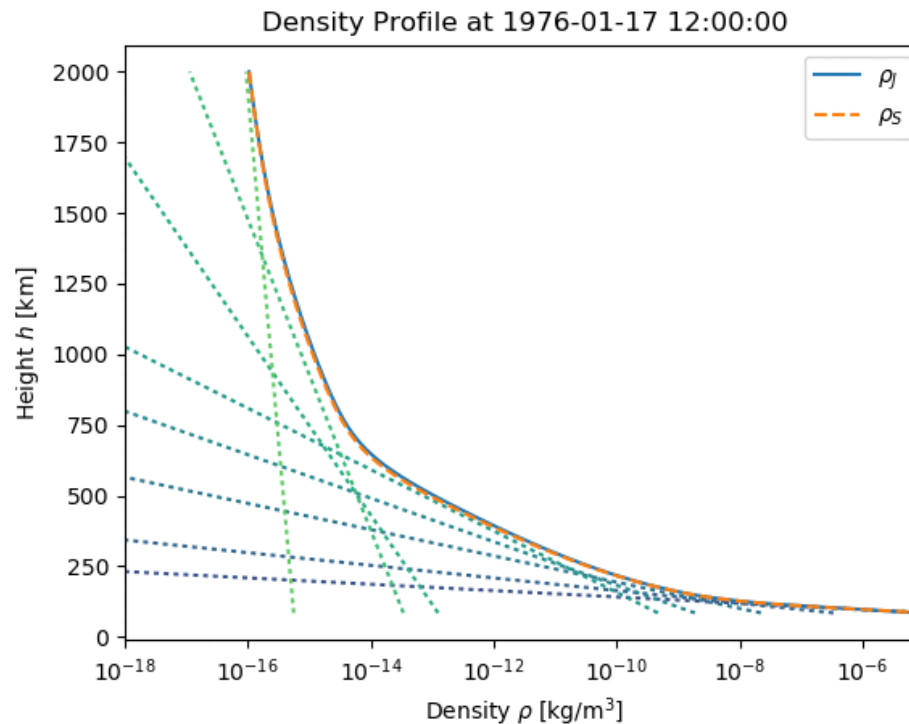
$$\rho_S(h) = \sum_p \rho_{0,p} \exp\left(-\frac{h}{H_p}\right)$$

- Possible to fit to any of the atmosphere models, given  $H$  increases



## Smooth Exponential Atmosphere Model

- Can be extended to contain time-dependencies (daily, annual, solar-cycle), or latitude-dependency
- E.g. solar cycles 21-23



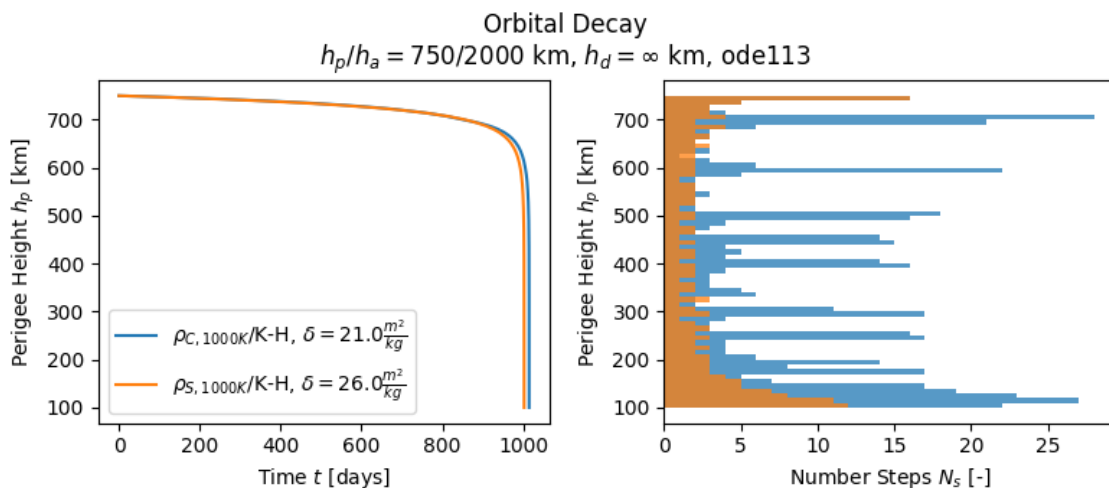
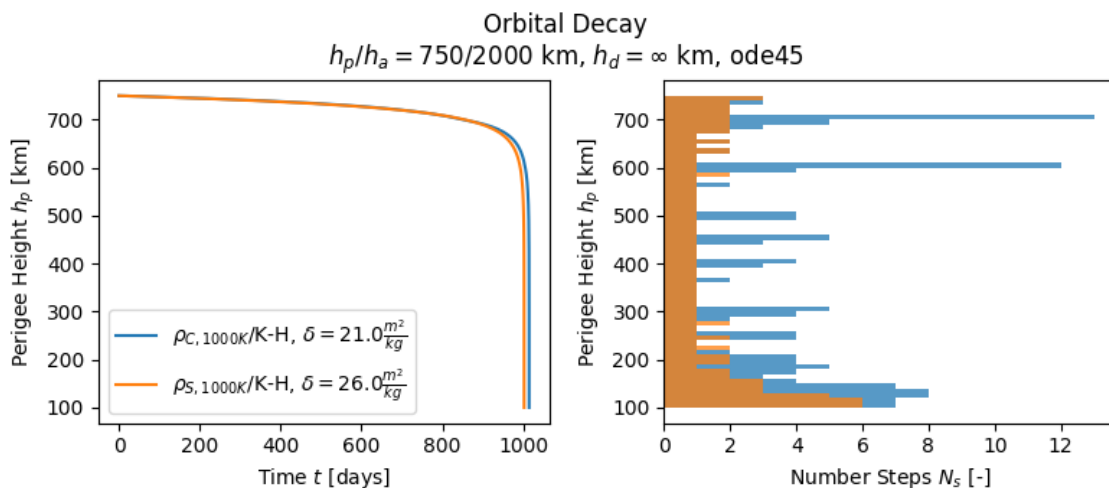
## Superimposition of King-Hele Method

- Given the sum of exponentials with truly fixed  $H$ , King-Hele can be summed for each partial atmosphere

$$\Delta a = \sum_p \Delta a_p \quad \Delta e = \sum_p \Delta e_p$$

- No error due to changing scale heights  $H$
- Further adaptations made on method:
  - Change directly in  $e$  rather than  $x = ae$
  - Up to fifth order retained to address large  $H$ , i.e. not so small  $z^{-1}$
  - Bridge function introduced to mitigate discontinuity

## Non-smooth vs Smooth Atmosphere



Number of function evaluations  $N_f$  needed for the integration using MATLAB's ode solvers:

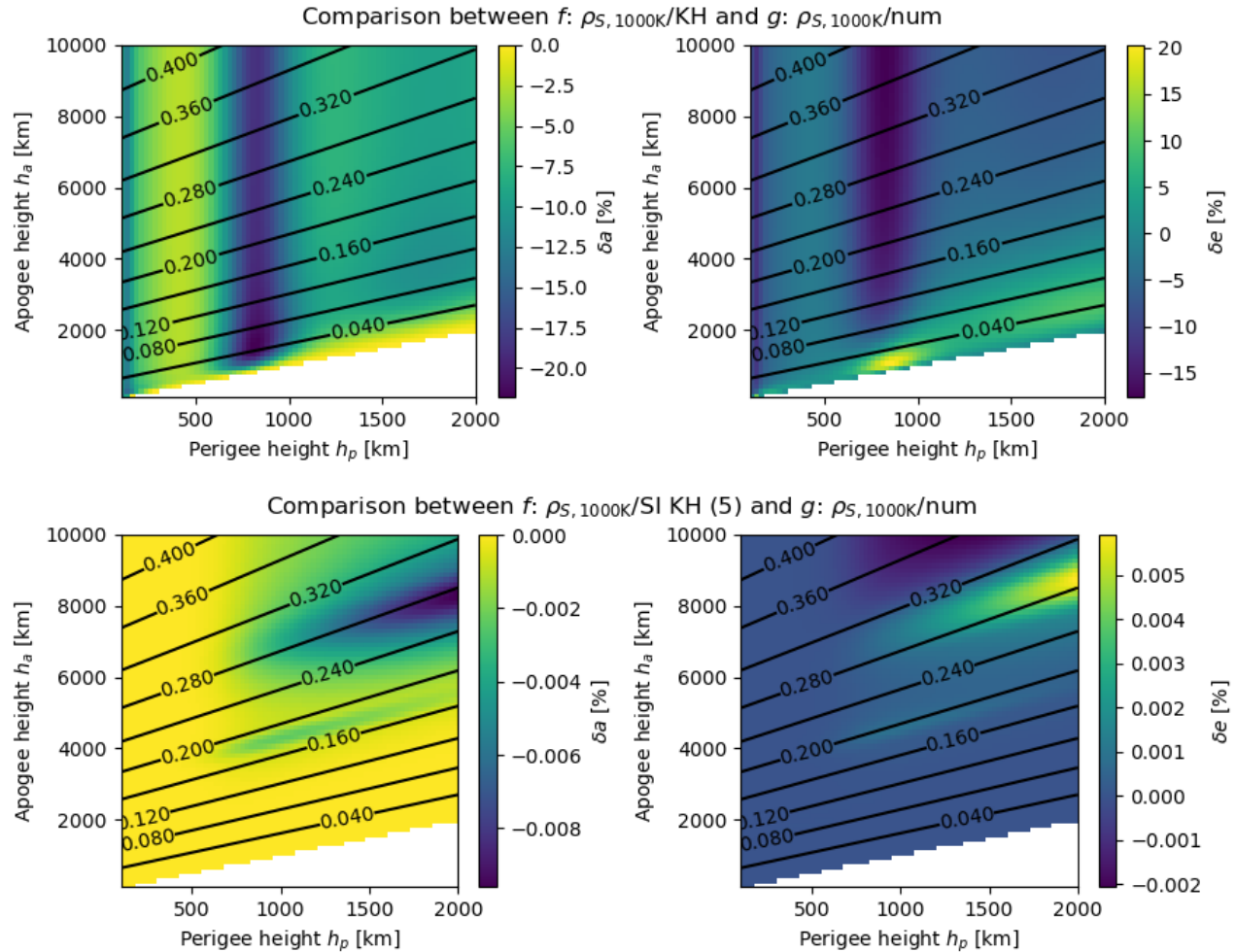
Model	ode45	ode113
Non-smooth	1555	1240
Smooth	781	430
	-50%	-65%

$h_p = 750$  km  
 $h_a = 2000$  km

## Classical vs Superimposed King-Hele

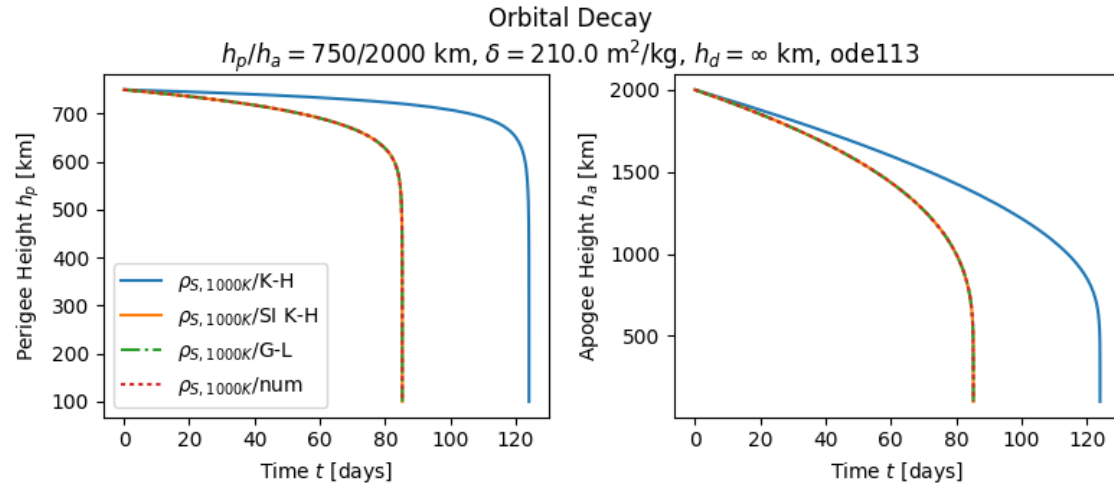
$$\delta a = \frac{\Delta a^{KH} - \Delta a^n}{\Delta a^n}$$

$$\delta e = \frac{\Delta e^{KH} - \Delta e^n}{\Delta e^n}$$



## Propagation with Different Approximations

$h_p = 750$  km  
 $h_a = 2000$  km  
 Smooth atmosphere



Model	$\Delta t$	$N_f$
Classical King-Hele	124.1	571
Superimposed King-Hele	85.3	552
Gauss-Legendre	85.3	536
Full numerical	85.3	2607424

## And future work

- The two major problem of the King-Hele + non-smooth atmospheric model have been addressed
- The smooth atmosphere cuts the number of function evaluations in half
- The superimposed King-Hele method is very exact and as fast as quadrature
- Semi-analytical propagation with air-drag shown to be as exact as numerical
  
- Future work
  - find analytical solution for lifetime
  - compare method to real observations

- Questions?

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- Circular

$$\Delta a = -2\pi\delta a^2 \rho(h)$$

$$\Delta e = 0$$

- Low eccentric

$$k = -2\pi\delta\rho(h_p) \exp(-z)$$

$$\vec{e} = \begin{pmatrix} 1 & e & e^2 & e^3 & e^4 & e^5 \end{pmatrix}$$

$$\vec{I} = \begin{pmatrix} I_0 & I_1 & I_2 & I_3 & I_4 & I_5 & I_6 \end{pmatrix}^T$$

$$\Delta a = ka^2[\vec{e}K_a\vec{I} + \mathcal{O}(e^6)]$$

$$\Delta e = ka[\vec{e}K_e\vec{I} + \mathcal{O}(e^6)]$$

- High eccentric

$$k = -2\delta\left(\frac{2\pi}{z}\right)^{\frac{1}{2}}\rho(h_p)$$

$$l = z(1 - e^2)$$

$$\vec{e} = \begin{pmatrix} 1 & e & e^2 & e^3 & e^4 & e^5 & e^6 & e^7 & e^8 & e^9 & e^{10} \end{pmatrix}^T$$

$$\vec{r} = \begin{pmatrix} \frac{1}{2} & \frac{1}{4} \frac{1}{4l} & \frac{3}{8} \frac{1}{32l^2} & \frac{15}{16} \frac{1}{128l^3} & \frac{105}{32} \frac{1}{2048l^4} & \frac{945}{64} \frac{1}{8192l^5} \end{pmatrix}$$

$$\Delta a = ka^2 \frac{(1+e)^{\frac{3}{2}}}{(1-e)^{\frac{1}{2}}} [\vec{e}K_a\vec{r} + \mathcal{O}\left(\frac{1}{z^6}\right)]$$

$$\Delta e = ka \left(\frac{1+e}{1-e}\right)^{\frac{1}{2}} (1-e^2) [\vec{e}K_e\vec{r} + \mathcal{O}\left(\frac{1}{z^6}\right)]$$

- Boundary

$$e_b = \left(\frac{H}{a}\right)^{\frac{1}{2}}$$

- Only necessary for high  $H$
- Bridge function: 3<sup>rd</sup> order polynomial
- Idea
  - keep all variables constant, except  $e$
  - evaluate low eccentric approximation at  $e_L = (1 + \Delta y_L) e_L$
  - evaluate high eccentric approximation at  $e_H = (1 + \Delta y_H) e_H$
  - solve linear problem for 4 variables, 4 unknowns, with boundary functions to ensure continuous and smooth transition