

Probabilistic Safety Assessment of Nuclear Power Plants considering Climate Change

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Abstract

Probabilistic Safety Assessment (PSA) of Nuclear Power Plants (NPPs) must take into account the impact of Climate Change (CC). In this paper, to do this, a PSA framework is developed coupling a CC impact assessment model, a source term estimation model, an atmospheric dispersion model and a groundwater contaminant transport model. The impact of CC on aquifer contamination is analyzed in terms of *i*) increase of accident initiating event frequencies due to CC-induced natural events and *ii*) alteration of hydrological conditions due to the CC influence on physical variables (e.g., temperature and precipitation) that affect atmospheric dispersion and groundwater transport of radioactive contaminant. An application of the proposed framework is performed with regards to the estimation of the peak dose following a hypothetical severe accident in a NPP site in South Korea. Under the assumptions made, CC is found to worsen the consequences of such accident in terms of groundwater radioactive contamination.

Keywords: *Probabilistic Safety Assessment (PSA), Nuclear Power Plant (NPP), Climate Change (CC), Atmospheric Dispersion, Groundwater Contamination*

Nomenclature

Acronyms

ADE	Advection Dispersion Equation	N_m	Number of different meteorological data records
AIC	Akaike Information Criterion	C_r	Concentration of r -th radionuclide in the compliance well
CBC	Climatic Boundary Condition	D	Dose from contaminated groundwater ingestion
CC	Climate Change	r	Radionuclide index
CCDF	Complementary Cumulative Distribution Function	R	Total number of radionuclide species
CDF	Core Damage Frequency	\dot{p}	Precipitation flux
CMIP6	Coupled Model Intercomparison Project phase 6	$E\dot{T}$	Evapotranspiration flux
CVaR	Conditional Value at Risk	$I\dot{r}$	Irrigation flux
ETs	Event Trees	\dot{R}	Runoff flux
FTs	Fault Trees	D_{peak}	Peak yearly dose from groundwater ingestion
GCMs	Global Circulation Models	t_{peak}	Breakthrough time
HYSPPLIT	HYbrid Single-Particle Lagrangian Integrated Trajectory	DC_r	r -th radionuclide dose conversion factor
IEs	Initiating Events	V_w	Total volume of water consumed by an adult in one year
LOCA	Loss Of Coolant Accident	N_s	Number of Monte Carlo simulation trials for the deposited ST estimation
NPPs	Nuclear Power Plants	s	Monte Carlo trial index (ST estimation)
PDF	Probability Density function	N_g	Number of Monte Carlo simulation trials for the peak dose estimation
PDSs	Plant Damage States	g	Monte Carlo trial index (peak dose estimation)
PMF	Probability Mass Function	$\mathcal{U}\{\cdot\}$	Uniform PMF
PSA	Probabilistic Safety Assessment	Q_{sat}	Aquifer volumetric flowrate
RF	Release Fraction	K	Hydraulic conductivity
RPV	Reactor Pressure Vessel	∇h	Hydraulic gradient
SB	Station Blackout	$\mathbb{E}[\cdot]$	Expectation operator
SSCs	Structures, Systems and Components (SSCs)	N_{ex}	Number of simulations in which $D_{peak} > \tau$
SSP	Shared Socioeconomic Pathway	τ	Regulatory threshold
ST	Source Term	$CVaR(\cdot)$	Conditional Value at Risk
STC	Source Term Category	P_{ex}	Exceedance probability
SGTR	Steam Generator Tube Rupture	$\Delta CVaR(\cdot)$	Relative difference between CVaR values

Symbols

ε_i	Fragility factor of the i -th IE	α_L	Longitudinal dispersivity
α_i	Factor of change of the external i -th IE frequency	K_d	Distribution coefficient
α_{SB}	Factor of change of the SB frequency	$S_{i,sat}$	Water saturation level (saturated zone)
α_{SGTR}	Factor of change of the SGTR frequency	$S_{i,unsat}$	Water saturation level (unsaturated zone)
α_{LOCA}	Factor of change of the LOCA frequency	x_{sat}	Length of the saturated zone
β	Factor of change of the infiltration flux	x_{unsat}	Length of the unsaturated zone
f_i	External i -th IE frequency	y_{sat}	Thickness of the saturated zone
ψ	Aquifer infiltration flux	y_{unsat}	Thickness of the unsaturated zone
\bar{m}	Database listing climatic data	z_{source}	Depth of the deposited source term
\bar{m}_a	Database listing meteorological data	z_{sat}	Depth of the saturated zone
t	Time	z_{unsat}	Depth of the unsaturated zone
i	IE index	z_{sat}	Depth of the saturated zone
I	Total number of IEs	z_{unsat}	Depth of the unsaturated zone
n	Number of NPP units simultaneously affected by the IE	$\mathcal{P}_m\{\cdot\}$	PMF of \bar{m}_a
N	Total number of units	\bar{m}	Database listing all records of \bar{m}_a
λ	Parameter of the truncated discrete exponential PMF	M	Number of variables listed in of \bar{m}
f^j	Frequency of the j -th STC	f_{SB}	SB frequency
j	STC index	X	Spatial dimension of \bar{m} and \bar{m}_a (x-axis)
J	Total number of STCs	Y	Spatial dimension of \bar{m} and \bar{m}_a (y-axis)
\bar{r}^j	RF vector of the j -th STC	x	Spatial coordinate (x-axis)
t_0	Current time	y	Spatial coordinate (y-axis)
T	Projection reference time for \bar{m}	X	Spatial dimension of \bar{m} and \bar{m}_a (x-axis)
ρ	Pearson correlation coefficient	Y	Spatial dimension of \bar{m} and \bar{m}_a (y-axis)
$\mathcal{F}_i(\cdot)$	Fragility curve of the i -th IE	t_0^a	Starting time of the atmospheric dispersion and deposition process
$\mathcal{T}_r(\cdot)$	Return time	T_a	Ending time of the atmospheric dispersion and deposition process
Λ	Truncated Poisson distribution parameter	T_g	Ending time of the groundwater contaminant transport
p	Truncated Negative Binomial distribution parameter	x^*	Spatial coordinate of the area of interest (x-axis)
k	Truncated Negative Binomial distribution parameter	y^*	Spatial coordinate of the area of interest (y-axis)
η	Truncated Negative Binomial distribution parameter	X^*	Spatial dimension of the area of interest (x-axis)
w	Truncated Negative Binomial distribution parameter	Y^*	Spatial dimension of the area of interest (y-axis)
		$\mathcal{P}_n\{\cdot\}$	PMF of n

1. Introduction

A Probabilistic Safety Assessment (PSA) of a Nuclear Power Plant (NPP) is structured in three levels (IAEA, 2001, 2024): Level 1 (L1) comprises the analysis and screening of potential hazards (internal, i.e., due to failures of components and systems, and external, i.e., due to natural events like flooding and earthquakes), the estimation of the frequency of the accident Initiating Events (IEs) and the evaluation of the accident sequences, in terms of Plant Damage States (PDSs) and Core Damage Frequency (CDF); this is typically done by combining Fault Trees (FTs), Event Trees (ETs) and numerical simulations (Baek and Heo, 2023); Level 2 analyses the accident physical progression in the NPP containment building for each PDS to determine the amount and timing of the Source Term (ST) of radionuclide release outside the NPP, i.e., the Source Term Categories (STCs); Level 3 evaluates the off-site consequences from the evolution of the accidents by considering the short and long-term effects of the release of each STC, evaluating the dose to population (Ali and Kakosimos, 2023; Park *et al.*, 2025), the environmental contamination (Selivanova *et al.*, 2025), the economic losses (Ashley *et al.*, 2017).

The outcomes of PSA are used for risk-informed decision making on NPP design and siting (L1 PSA), severe accident management (L2 PSA) (Roma, Di Maio and Zio, 2024) and evacuation procedures (L3 PSA) (Kim and Heo, 2023). In particular, L3 PSA outcomes provide risk information to regulators, politicians and the population at large, for an objective assessment of the impact of nuclear accidents (Denning and Mubayi, 2017; Selivanova *et al.*, 2025). Inevitably, PSA outcomes are affected by uncertainties due to modelling simplifications, necessary to reduce the complexity of the analysis, and incomplete knowledge of the phenomena involved in the accidents development (Mosleh, 2014; Ilkka, 2018).

Climate Change (CC) can affect the safety of NPPs in various ways (OECD, 2021; Yan, Dunnett and Andrews, 2023). On one hand, it can increase the frequency and magnitude of natural events (Seneviratne *et al.*, 2012; Utsumi and Kim, 2022), e.g., floodings (Tolo, Patelli and Beer, 2017; Kim, Kim, Hahm and Han, 2021a; Kim, Kim, Hahm, Park, *et al.*, 2021), typhoons (Kim, Jang and Lim, 2015; Choun and Kim, 2019; Kim *et al.*, 2024a, 2025) and tsunamis (Kim and Choi, 2012; Kim, Song and Cho, 2022), that can trigger external Initiating Events (IEs) like Station Blackouts (SBs) (Kim, 2022; Ayoub and Sornette, 2023; Yoon, Kim and Han, 2024; Vododokhov, Erlandson and Novog, 2025). On the other hand, it can affect the processes of dispersion, deposition and migration of radionuclides (Kitamura *et al.*, 2015; Biwalkar *et al.*, 2023), e.g., changing the

infiltration fluxes and aquifer recharge magnitudes in the contaminated region (Meray et al. 2024; Libera et al. 2019). To the authors knowledge, PSA frameworks do not comprehensively account for the effects of CC. Meteorological data variability has been accounted for, but only for fallout modelling in (An *et al.*, 2016), for the evaluation of short-term dose to the population (Sinha, Atikler and Mileski, 2024) and for the optimization of evacuation procedures (Kim and Heo, 2023).

Within this paper, a modelling and simulation framework is proposed to evaluate the effects of CC on groundwater radioactive contamination. The effects are considered in terms of modifications of the IE frequencies within L1 PSA, due to the increase of the frequency of extreme natural events and to changes in the hydrological conditions affecting aquifer radioactive contamination (Coscia, Di Maio and Zio, 2025). The PSA modelling and simulation framework integrates:

- i)* a CC impact assessment model based on Global Circulation Models (GCMs) developed within the Coupled Model Intercomparison Project Phase 6 (CMIP6) (Shin *et al.*, 2021) that allows calculating projections in the future of relevant CC variables,
- ii)* L1 and L2 PSA models to estimate the released ST (Lee and Ko, 2008; Oh *et al.*, 2020),
- iii)* an atmospheric dispersion model (Hybrid Single-Particle Lagrangian Integrated Trajectory model (HYSPLIT)) (Rolph, Stein and Stunder, 2017) to assess the contaminant deposition on the ground,
- iv)* a groundwater contaminant transport model (GoldSim) (Lee and Choi, 2016) to evaluate the aquifer contamination.

Coupled Monte Carlo simulation is used for the propagation of the major sources of uncertainties affecting the assessment, including the magnitude of the emitted ST, the meteorological conditions for atmospheric dispersion, and the climatic and physical parameters affecting contaminant transport through groundwater. The developed framework is applied to a case study regarding a hypothetical severe accident in a NPP site located in South Korea, and its consequences are evaluated on two aquifers located nearby the NPP (one confined and one unconfined). The modelling and simulation framework proposed provides also for a bounding analysis of the peak yearly dose from groundwater ingestion, considering a set of baseline accident scenarios that initiate at the current time and in which the groundwater contamination develops under both stationary and CC-modified climatic conditions, and other scenarios representative of the same accident but assumed to be initiated in 2100 and developing under CC-induced climatic conditions. The choice of these

two categories of scenarios is instrumental to assess the effects that CC could have on the results of the PSA of newly built NPPs (with sixty years of design operative license, plus twenty years life extension) considering that accidents may occur at the beginning or towards the end of the NPP design lifetime. The results of the case study show that under the assumptions made for the considered nuclear accident, CC influences groundwater radioactive contamination thus, possibly, worsening the exceedance of the annual dose limit from the ingestion of contaminated groundwater. Clearly, an ad-hoc comprehensive hazard and fragility analysis would be required for evaluating site-specific CC impacts.

The paper is organized as follows: Section 2 presents the proposed PSA framework, Section 3 presents the case study, Section 4 presents the results and in Section 5 conclusions are drawn.

2. The proposed PSA framework

A sketch of the proposed simulation-based PSA framework is presented in Figure 1.

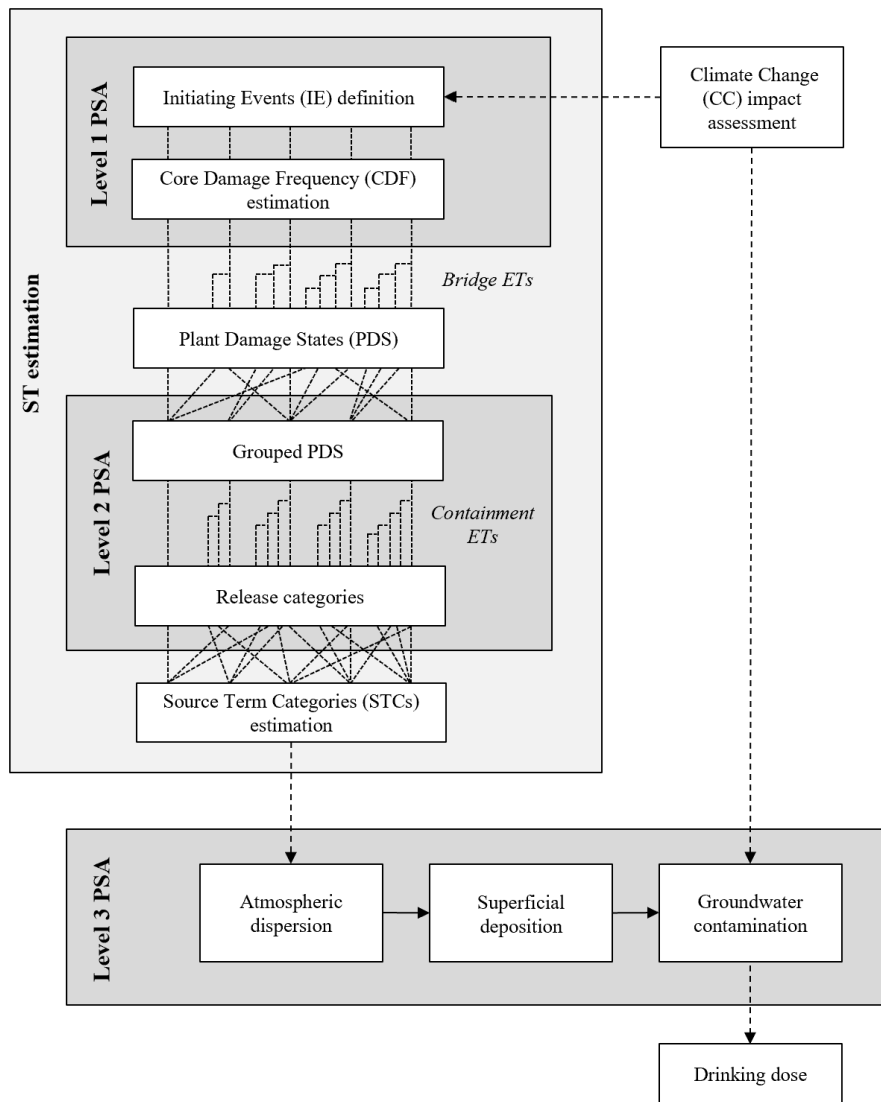


Figure 1. Simulation-based PSA framework.

The framework allows calculating the peak yearly drinking dose from contaminated groundwater ingestion by combining four models: *i*) a CC impact assessment model (Section 2.1), *ii*) a ST estimation model comprising L1-L2 PSA models (Section 2.2), *iii*) an atmospheric dispersion and deposition model (Section 2.3), and *iv*) a groundwater contaminant transport model (Section 2.4). The coupling between the four models is performed through a Monte Carlo simulation scheme for propagating uncertainty (Section 2.5). The overall framework can allow accounting for CC effects within a standard PSA framework (IAEA, 2001, 2024).

2.1 CC impact assessment model

For the projections of future climatic conditions due to CC in a region of interest, models are developed and the corresponding numerical codes are built to simulate the future dynamics of M climatic variables, such as temperature, precipitation and sea level. Let $\bar{m}(x, y, t)$ denote the vector of values of the M climatic variables at time t in the location of spatial coordinates (x, y) , with $x = 1, 2, \dots, X$, $y = 1, 2, \dots, Y$, and $t = t_0, \dots, T$, t_0 being the current time and T the time of interest for the projection. The climate dynamics can be simulated under different assumptions regarding anthropogenic and natural forcings, such as greenhouse gas emissions, land use changes and solar activity that, in turn, are linked to economic growth, demography and policy interventions (O'Neill *et al.*, 2016), collectively named Shared Socioeconomic Pathways (SSPs). Among others (McGuffie and Henderson-Sellers, 2001; Edwards, 2011), GCMs are those considered by the international initiative Coupled Model Intercomparison Project Phase 6 (CMIP6) (Shin *et al.* 2021; Tebaldi *et al.* 2021) which organises different GCMs, input data, documentation and evaluation metrics in a common experimental framework to derive a multi-models ensemble of GCMs useful to compare the effects of the different SSPs on variables such as temperature, precipitation, sea-level rise projections, which ultimately affect the frequency of natural extreme events, e.g., floodings due to extreme precipitation (B. J. Kim, Kim, Hahm, and Han 2021), tsunamis due to sea level rise (Yavuz, 2023), forest fires due to heat waves (Lim *et al.* 2024) and tropical cyclones due to the combined effect of wind speed and precipitation intensification (Gungyu Kim *et al.* 2024). Then, a CC-induced increase can be expected also of the frequencies $f_i(T)$ of the external IEs, $i = 1, 2, \dots, I$, at the future time T (OECD, 2021; Di Maio, Tonicello and Zio, 2022):

$$f_i(T) = \alpha_i f_i(t_0) \quad (1)$$

where, under the hypotheses that *i*) the i -th IE is affected by the variation of a single climatic variable $m(x, y, t)$ and that *ii*) the fragility of the NPP Structures, Systems and Components (SSCs) is time invariant, the increase multiplication factor α_i is:

$$\alpha_i = 1 + \varepsilon_i (m(x, y, T) - m(x, y, t_0)) \quad (2)$$

where ε_i depends on the fragility curve related with the i -th IE and on $m(x, y, t_0)$ (further details can be found in Appendix A).

CC may also alter the hydrological balance of the region of interest, i.e., the infiltration (or recharge) flux of the contaminated aquifers, which is hereafter denoted as the aquifer Climatic Boundary Condition (CBC) (Kim *et al.*, 2020; Song *et al.*, 2021; Song, Chung and Shahid, 2022). Changes in aquifer CBC may increase or decrease the mobility of the radionuclides released in groundwater and, therefore, the magnitude of the environmental consequences of the accident, depending on whether precipitation or evapotranspiration dominates (wet and dry scenarios, respectively). To account for this, an additive factor of change β for the aquifer CBC is considered, as in (Libera *et al.*, 2019; la Cecilia *et al.*, 2020):

$$\beta = \frac{\dot{\psi}(T) - \dot{\psi}(t_0)}{\dot{\psi}(t_0)} \quad (3)$$

where the infiltration flux in the future $\dot{\psi}(T)$ and the current infiltration flux $\dot{\psi}(t_0)$ are estimated assuming that the climatic variables (e.g., precipitation and temperature) at time T and t_0 for the location (x, y) are equal to $\bar{m}(x, y, T)$ and $\bar{m}(x, y, t_0)$, respectively.

Note that since the magnitude of α_i , $i = 1, 2, \dots, I$ and β are related to the climatology and topography of the region where the NPP is located, they depend on the considered SSP and GCMs.

2.2 ST estimation model (L1-L2 PSA)

L1 and L2 PSA are, then, performed to estimate J STCs, their frequencies of release f^j , $j = 1, 2, \dots, J$ and the corresponding Release Fraction (RF) $\bar{R}^j = [R_1^j, \dots, R_r^j, \dots, R_R^j]$, where $r = 1, 2, \dots, R$ are the different radionuclide species considered. The released ST is obtained by the product of the RF and the core inventory at the time of the accident occurrence t_0^a .

2.3 Atmospheric dispersion and deposition model (L3 PSA)

An atmospheric dispersion and deposition model is used to estimate the concentration of radionuclides deposited at a given distance from the ST release. To do this, different models are available in literature: to name a few, under the simplifying assumptions of stationarity, e.g., time invariant wind fields and constant ST emission rate, the analytical gaussian plume can be adopted (Lotrecchiano *et al.*, 2020); when non-stationary meteorological variables and ST sources are instead considered, the Advection Dispersion Equation (ADE) model can be used, following a Eulerian or a Lagrangian approach (Challa *et al.*, 2008). In this work, an ADE model is employed to consider the effect of non-stationary meteorological variables $\bar{m}_a(x, y, t)$ in a time interval $t \in [t_0^a, T_a]$.

It is worth mentioning that since $[t_0^a, T_a] \ll [t_0, T]$, the meteorological variables values $\bar{m}_a(x, y, t)$ required for the simulation of the atmospheric dispersion and deposition processes, e.g., wind speed, wind direction, atmospheric pressure, relative humidity, temperature and precipitation, are not considered to be exposed to CC-induced variations; rather aleatory uncertainty becomes important. To quantify this, as in (Lim *et al.*, 2024), N_m stochastic realizations of $\bar{m}_a(x, y, t)$ are collected, i.e., $\hat{\bar{m}}(x, y, t) = [\bar{m}_a^1(\cdot), \dots, \bar{m}_a^{N_m}(\cdot)]$, and propagated through the model by assuming a site-specific Probability Mass Function (PMF) \mathcal{P}_m (An *et al.*, 2016), e.g., a uniform PMF $\bar{m}_a(\cdot) \sim \mathcal{U}\{1, N_m\}$.

2.4 Groundwater contaminant transport model (L3 PSA)

A groundwater contaminant transport model is used to compute the concentration $C_r(t)$ of each r -th radionuclide at the end of the migration pathway ($t > T_a$). The CBC of the model is an imposed infiltration flux $\dot{\psi}(t)$:

$$\dot{\psi}(t) = \dot{\psi}(t_0) + (\beta \dot{\psi}(t_0)) \quad (4)$$

where $\dot{\psi}(t_0)$ is defined as:

$$\dot{\psi}(t_0) = \dot{P}(t_0) + \dot{I}r(t_0) - \dot{E}T(t_0) - \dot{R}(t_0) \quad (5)$$

and $\dot{P}(t_0)$, $\dot{I}r(t_0)$, $\dot{E}T(t_0)$, $\dot{R}(t_0)$ are a random realization of precipitation, irrigation, evapotranspiration and runoff fluxes estimated under the current climatic conditions $\bar{m}(x, y, t_0)$.

Then, the total dose $D(t)$ is calculated as:

$$D(t) = \sum_{r=1}^R C_r(t) DC_r V_w \quad (6)$$

where DC_r is the dose conversion factor of each r -th radionuclide species and V_w the total volume of water consumed by an adult in one year. The total peak dose D_{peak} is obtained as in Eq. 7:

$$D_{peak} = \max_{t \in [T_a, T_g]} D(t) \quad (7)$$

Then, the breakthrough time t_{peak} , i.e., the time corresponding to D_{peak} , is:

$$t_{peak} = \operatorname{argmax}_{t \in [T_a, T_g]} D(t) \quad (8)$$

where $t \in [T_a, T_g]$ refers to the time interval considered for the groundwater contaminant transport.

2.5 Monte Carlo simulation

The coupling of the ST estimation model (Section 2.2), the atmospheric dispersion model (Section 2.3) and the groundwater contaminant transport model (Section 2.4) is performed through the Monte Carlo simulation scheme sketched in Figure 2. The framework is composed by two loops: one to estimate with N_s trials (indexed by s) the deposited ST and the other to estimate with N_g trials (indexed by g) the peak dose from groundwater ingestion. The simulation starts by setting the CC impact parameters α_i , $i = 1, 2, \dots, I$, and β , for each s -th trial of the first loop the released ST is estimated as customary done by L1-L2 PSA, also, the case of a multi-unit NPP can be addressed by modelling the number of units $n = 1, 2, \dots, N$, that are simultaneously affected by the accident with a Probability Mass Function (PMF) P_n (for the sake of simplicity here assumed the same for all the IEs) (Lim, Han and Yang, 2016; Yang, 2018). The atmospheric dispersion model is run with the random

meteorological variables $\bar{m}_a(x, y, t)$ sampled from $\mathcal{P}_m\{\widehat{m}(\cdot)\}$, to calculate the deposited ST. After N_s trials, a Probability Density Function (PDF) of the deposited ST can be obtained (GoldSim 2021b; Iman and Conover 1982). At this point, for each g -th trial of the second loop, the groundwater contaminant transport model is to be run, fed with a value of random CBC. After N_g trials, the PDFs c are estimated.

It is worth noting that, the two loop Monte Carlo simulation scheme allows setting $N_s \gg N_g$, so as to address the issue of the estimation of the peak dose for which the physical model of groundwater contaminant transport is more computationally expensive than the atmospheric dispersion model used to estimate the deposited ST. The representativeness of the estimated D_{peak} and t_{peak} PDFs is ensured by implementing an importance-sampling algorithm, which enables the simulation of physically consistent scenarios of large deposited ST. Indeed, the induced rank-correlation method (Iman and Conover 1982) has been applied to preserve the correlation coefficients among the marginal samples of the various deposited radionuclide species.

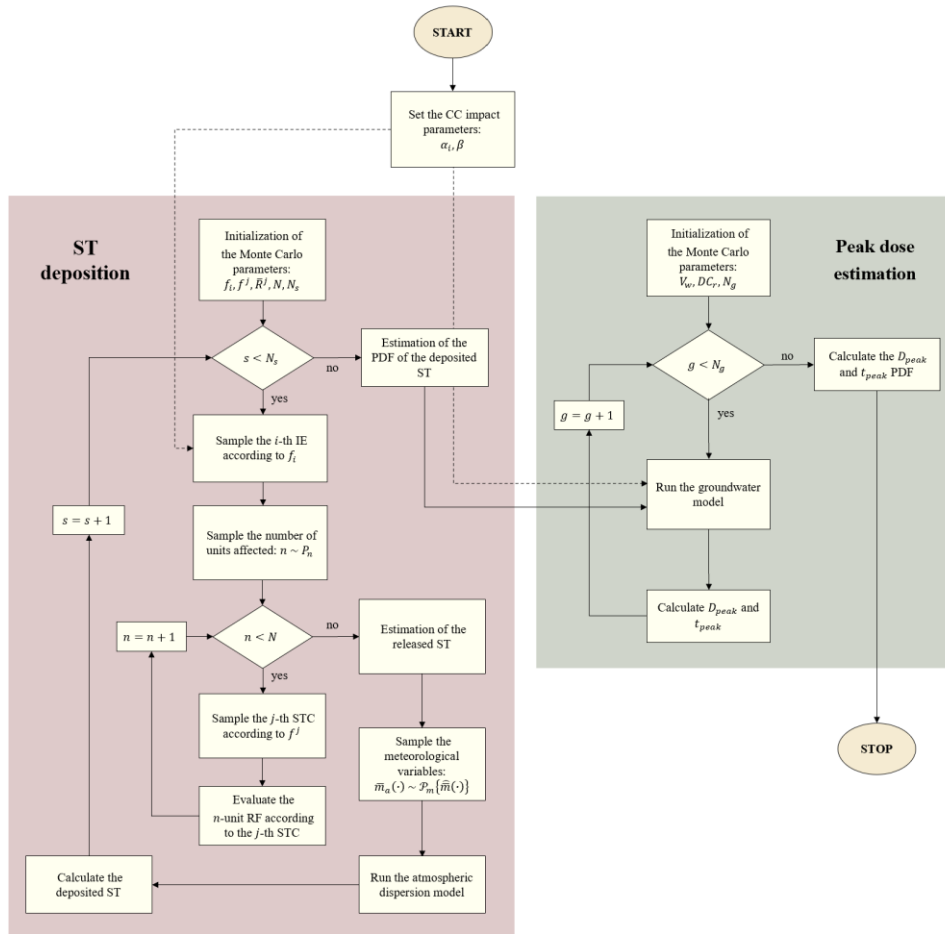


Figure 2. Flowchart of the proposed Monte Carlo simulation scheme, that couples: i) CC projections for the determination of α_i and β ii) L1-L2 PSA for the determination of f_i and STCs iii) an atmospheric dispersion

model for the deposited ST estimation *iv*) a contaminant transport model for the estimation of the peak dose from the ingestion of contaminated groundwater.

3. Case Study: CC-impact on the groundwater radioactive contamination from a multi-unit NPP

The PSA framework is applied to a $N = 6$ units NPP located in a hypothetical region in South Korea ($x^* = x_0^*, x_1^*, \dots, X^*, y^* = y_0^*, y_1^*, \dots, Y^*$), shown in Figure 3 (square marker). The aquifers whose groundwater ingestion dose peak is calculated are A_1 and A_2 (circle and triangle, respectively). The aquifers have different hydrogeological characteristics, i.e., A_1 is a confined aquifer underlaying reclaimed floodplains (Kim *et al.*, 2006) whereas A_2 is a shallow costal unconfined aquifer (Lee and Song, 2007). For both aquifers the same principal groundwater direction remains east-west, extending from the inland mountains towards the seashore (Kim *et al.*, 2019) (more details can be found in Section 3.4.1 and Section 3.4.2, respectively).

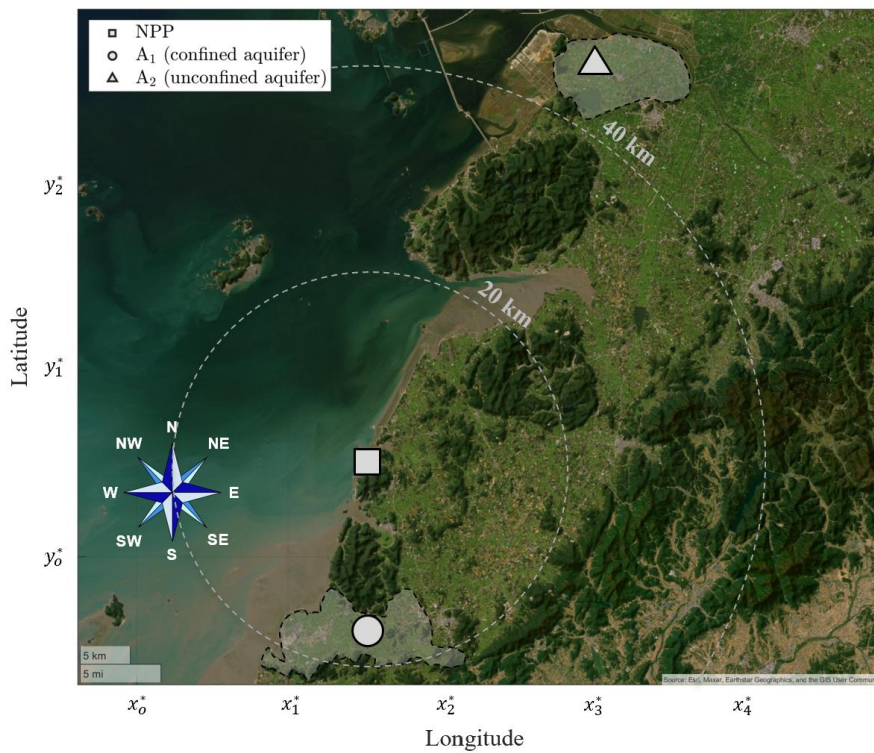


Figure 3. Case study aerial view.

3.1 CC impact assessment model

CMIP6 simulations, under different SSPs, predict an increase of mean, variance and extreme values of climatic variables, especially temperature and precipitation, due to CC in South Korea (Y. H. Kim et al. 2020; Song, Chung, and Shahid 2022). This is expected to lead to increased frequency and intensity of heavy rainfall and prolonged droughts (Shin et al. 2021; CCKP 2025), so that is not sure whether South Korea will predominantly face wetter or drier conditions. For this reason, we consider two scenarios sets:

- i) *Baseline*: the accident is supposed to occur at the beginning of the lifetime of a newly built NPP, thus with no CC-induced increase of the frequency of extreme natural events. On the other hand, the groundwater contamination process could still be affected by CC-driven alterations of CBCs, e.g., decrease, stationary or increase of the aquifer infiltration rate. Then, we consider the scenarios *Baseline_{Dry}*, *Baseline_{Stationary}*, and *Baseline_{Wet}*, respectively.
- ii) *CC-induced*: the accident is supposed to occur towards the end of the lifetime of a newly built NPP, therefore a CC-induced increase of the frequency of extreme precipitation events is expected to occur and lead to an increase of the IEs frequencies. Also in this case, drier, stationary or wetter CBC are considered, namely *CC-induced_{Dry}*, *CC-induced_{Stationary}*, and *CC-induced_{Wet}*, scenarios.

The IEs considered in the analysis are Steam Generator Tube Rupture (SGTR), Loss of Coolant Accident (LOCA) and Station Blackout (SB). Among these, we consider that only SB might be impacted by an intensification of extreme precipitation events due to CC, so that $\alpha_{SGTR} = \alpha_{LOCA} = 1$ for all the CC scenarios. In particular, a SB resulting from the simultaneous loss of off-site power and failure of emergency core-cooling systems can be triggered by a flooding that disables both the external grid supplying the NPP and the on-site diesel generators and auxiliary battery packs (Yoon, Kim and Han, 2024), whereas SGTR and LOCA, although initiated by natural hazards, are not further aggravated by CC-induced variations of climatic variables. The CC scenarios are outlined in Table 1 and their effects on L1 and L3 PSA are operationalized as follows:

- L1 PSA:
 - *Baseline*: no increase of the baseline SB frequency f_{SB} is assumed, i.e., $\alpha_{SB} = 1$.

- *CC-induced*: a ten-fold increase of f_{SB} is assumed, i.e., $\alpha_{SB} = 10$ at $T = 2100$. This value results from the variation of extreme daily precipitation (with a 50 yr return period) taken from the CMIP6 SSP5-8.5 projections for the years 2071-2100 with respect to the historical records relative to the years 1973-2010 (Shin et al. 2021), i.e., 44 %, and from the multiplication by $\varepsilon_{SB} = 0.095$ (see Appendix B for details).
- L3 PSA:
- *Dry*: a maximum 25 % decrease ($\beta = -25\%$) of aquifer infiltration flux $\dot{\psi}(t)$ is assumed to reflect the reduction of \dot{P} and the increase of $\dot{E}T$ according to CMIP6 SSP5-8.5 projections for the region of interest in the years 2080-2100 (Kim et al., 2020; Shin et al., 2021; Song et al., 2021; Song, Chung and Shahid, 2022; CCKP, 2025) with respect to the historical records relative to the 1960-2020 years (KMA, 2025). For the sake of simplicity, variations of irrigation and runoff fluxes of Eq. 5 are neglected.
 - *Stationary*: no variation of the aquifer infiltration flux is considered, assuming that changes in \dot{P} and $\dot{E}T$ balance each other.
 - *Wet*: a maximum 25 % increase ($\beta = +25\%$) of aquifer infiltration flux $\dot{\psi}(t)$ is assumed to reflect the increase of \dot{P} and the decrease of $\dot{E}T$ according to CMIP6 SSP5-8.5 projections for the region of interest for the years 2080-2100 (Kim et al., 2020; Shin et al., 2021; Song et al., 2021; Song, Chung and Shahid, 2022; CCKP, 2025) with respect to the historical records relative to the 1960-2020 years (KMA, 2025). Also in this case, variations of irrigation and runoff fluxes are neglected (Eq. 5).

Scenario	Explanation	Label	CC assumptions	Effect on L1	Effect on L3
Baseline	Accident occurring at t_0	<i>Baseline_{Dry}</i>	No modifications of f_{SB}^{hist} ; drier climatic conditions ($\dot{P} < \dot{E}T$)	$\alpha_{SB} = 1$	$\beta = -25\%$
		<i>Baseline_{Stationary}</i>	No CC-induced effects	$\alpha_{SB} = 1$	$\beta = 0$

CC-induced	Accident occurring at the end of the NPP lifetime T	<i>Baseline_{wet}</i>	No modifications of f_{SB}^{hist} ; wetter climatic conditions ($\dot{P} > \dot{E}T$)	$\alpha_{SB} = 1$	$\beta = +25\%$
		<i>CC-induced_{Dry}</i>	Increase of f_{SB}^{hist} ; drier climatic conditions ($\dot{P} < \dot{E}T$)	$\alpha_{SB} = 10$	$\beta = -25\%$
		<i>CC-induced_{Stationary}</i>	Increase of f_{SB}^{hist} ; stationary climatic conditions	$\alpha_{SB} = 10$	$\beta = 0$
		<i>CC-induced_{wet}</i>	Increase of f_{SB}^{hist} ; wetter climatic conditions ($\dot{P} > \dot{E}T$)	$\alpha_{SB} = 10$	$\beta = +25\%$

Table 1. List of the considered CC scenarios.

3.2 ST estimation model

The IEs frequencies $f_i(t_0)$ are listed in Table 2 (U.S. Nuclear Regulatory Commission, 1996). Among the N NPP units, the probability that n of them are simultaneously affected by the accident is modelled by a truncated discrete exponential PMF (Berber, 2017):

$$P_n = \frac{e^\lambda - 1}{1 - e^{-\lambda N}} e^{-\lambda n} \quad (9)$$

with $\lambda = 0.2$ for all IEs (Lim, Han and Yang, 2016; Yang, 2018). This assumption is instrumental to the exemplification of the framework on a multi-unit NPP: clearly, this can be replaced by site and IEs specific PMFs (see Appendix C for further details). A total of $J = 14$ STCs are considered (Lee and Ko, 2008); for each generic j -th STC, Table 3 lists the possible IEs that might cause it, the corresponding frequency of release f^j , and the RFs $R^j(^{90}\text{Sr})$ and $R^j(^{137}\text{Cs})$ of the two radionuclides ^{137}Cs and ^{90}Sr considered responsible for groundwater contamination. The considered inventory of these radionuclides at the release time refers to that of a generic 1000 MWe light water reactor with 33% thermal efficiency at the end of the irradiation cycle, a core capacity of 70 metric tonnes of fresh fuel (tonU) and a burnup level of 45 GWd/tonU (U.S. Nuclear Regulatory Commission, 2016).

IE	$f_i(t_0)$ [yr^{-1}]	Source
SGTR	$7 \cdot 10^{-4}$	(U.S. Nuclear Regulatory Commission, 1996)
LOCA	$1 \cdot 10^{-6}$	(U.S. Nuclear Regulatory Commission, 2005)

Table 2. List of IEs and of the frequencies of occurrence f_i .

STC	IE	Characteristics of the accident	f^j [yr ⁻¹]	$R^j(^{90}\text{Sr})$ [-]	$R^j(^{137}\text{Cs})$ [-]
STC_1	SB/LOCA	RPV intact and functioning containment isolation	$1 \cdot 10^{-6}$	$4.7 \cdot 10^{-6}$	$1.8 \cdot 10^{-5}$
STC_2	SB/LOCA	RPV intact and loss of containment isolation	$1 \cdot 10^{-12}$	$6.7 \cdot 10^{-3}$	$2.9 \cdot 10^{-1}$
STC_3	LOCA	Containment failure before RPV breach	$8.2 \cdot 10^{-8}$	$7.5 \cdot 10^{-5}$	$1 \cdot 10^{-5}$
STC_4	SB	Containment early failure (RPV breaches under high pressure with sprays available)	$3.7 \cdot 10^{-9}$	$2.2 \cdot 10^{-3}$	$1.1 \cdot 10^{-2}$
STC_5	SB	Containment early failure (RPV breaches under high pressure with sprays unavailable)	$1.6 \cdot 10^{-8}$	$6.2 \cdot 10^{-4}$	$1.5 \cdot 10^{-2}$
STC_6	SB/LOCA	Containment early failure (RPV breaches under low pressure with sprays unavailable)	$7.2 \cdot 10^{-8}$	$8.6 \cdot 10^{-3}$	$1.6 \cdot 10^{-1}$
STC_7	LOCA	Containment late failure (sprays available)	$8 \cdot 10^{-7}$	$5.3 \cdot 10^{-6}$	$2.2 \cdot 10^{-5}$
STC_8	SB	Containment late failure (sprays unavailable)	$1.4 \cdot 10^{-6}$	$2.9 \cdot 10^{-5}$	$4.1 \cdot 10^{-4}$
STC_9	SB/LOCA	Basement melt-through (sprays unavailable)	$2.2 \cdot 10^{-6}$	$3 \cdot 10^{-6}$	$4.6 \cdot 10^{-5}$
STC_{10}	SB/LOCA	Containment intact	$3.3 \cdot 10^{-7}$	$3 \cdot 10^{-6}$	$4.6 \cdot 10^{-5}$
STC_{11}	SB/LOCA	RPV breaches (sprays available)	$1 \cdot 10^{-12}$	$7.7 \cdot 10^{-3}$	$1.8 \cdot 10^{-2}$
STC_{12}	SB/LOCA	RPV breaches (sprays unavailable)	$1 \cdot 10^{-12}$	$8.1 \cdot 10^{-3}$	$2.1 \cdot 10^{-1}$
STC_{13}	SGTR	Steam Generator Tube Rupture	$1.3 \cdot 10^{-6}$	$8.6 \cdot 10^{-5}$	$1.2 \cdot 10^{-2}$
STC_{14}	LOCA	Interface LOCA	$2.5 \cdot 10^{-8}$	$1.1 \cdot 10^{-1}$	$9.9 \cdot 10^{-1}$

Table 3. STCs with corresponding IE, characteristics, frequency, RF of ⁹⁰Sr and ¹³⁷Cs (Lee and Ko, 2008) (SB: Station Blackout; LOCA: Loss of Coolant Accident; SGTR: Steam Generator Tube Rupture; RPV: Reactor Pressure Vessel).

3.3 Atmospheric dispersion and deposition model

The HYbrid Single-Particle Lagrangian Integrated Trajectory (HYSPLIT) model is used for describing radionuclides atmospheric dispersion and deposition following an accident (Draxler and Hess 1997; Rolph, Stein, and Stunder 2017). HYSPLIT uses the parameters listed in Table 4 and the dispersion-relevant meteorological parameters $\bar{m}_a(x, y, t)$ (wind speed, wind direction, atmospheric pressure, relative humidity, temperature, precipitation) to model the contaminant dispersion and deposition. In this work, the month of July is chosen as conservatively representative of the regional meteorology, since the prevalent wind directions are from south-west to north-east: considering the region topography (Figure 3), under these meteorological conditions the inland transport of radionuclides is maximum. The time interval $[t_0^a, T_a]$ considered for the dispersion and deposition processes is 72 hours. To account for the uncertainty related to $\bar{m}_a(x, y, t)$, all the available $N_m = 104$ different realizations of the meteorological variables over the 72 hours length records are retrieved from the GDAS-0.5° database $\hat{m}(\cdot)$ relative to the month of July in the years 2007-2019 (NOAA, 2024) ($\bar{m}_a(\cdot) \sim \mathcal{U}\{1, N_m\}$).

Parameter	Value	Unit	Source
Emission height	50	<i>m</i>	Engineering judgement
Dry deposition velocity	$2 \cdot 10^{-3}$	<i>m s⁻¹</i>	(An <i>et al.</i> , 2016)
In-cloud scavenging coefficient	$3 \cdot 10^{-5}$	<i>s⁻¹</i>	(Kinser, 2001)
Below-cloud scavenging coefficient	$5 \cdot 10^{-5}$	<i>s⁻¹</i>	(An <i>et al.</i> , 2016)
Release duration	8	<i>hours</i>	Engineering judgement
Simulation duration	72	<i>hours</i>	Engineering judgement

Table 4. List of the parameters of the HYSPLIT model.

3.4 Groundwater contaminant transport model

GoldSim is used to model groundwater contaminant transport, adopting a one-dimensional ADE to describe the most representative migration pathway for evaluating the peak dose D_{peak} (Kowe and Norris 2012; GoldSim 2021a). This allows performing a large number of simulations in a reasonable computational time while considering the most influential phenomena affecting the contaminant migration through groundwater,

specifically, the retarding effect of sorption reactions between the radionuclides and the porous matrix, the radioactive decay and the effect of the time-dependent CBC $\psi(t)$. The concentrations at the end of the pathway, i.e., the spatial position chosen as representative of a compliance well, are calculated with a daily time step, and D_{peak} is calculated in the time interval $[T_a, T_g] = 100$ years through a user-defined receptor element (Lee and Choi, 2016). Details on the GoldSim models of the aquifers located in A₁ and A₂ are hereafter presented in Section 3.4.1 and Section 3.4.2, respectively.

3.4.1 A₁ groundwater contaminant transport model

A₁ is a floodplain region resulting from an anthropogenic process of land reclamation from the seashore to increase the surface of exploitable land for agricultural activities (Kim *et al.*, 2006). The reclamation process has caused the accumulation of a thick layer of muddy soil on the original sandy shore, creating a confined aquifer structure. A conceptual model of the aquifer structure is presented in Figure 4.

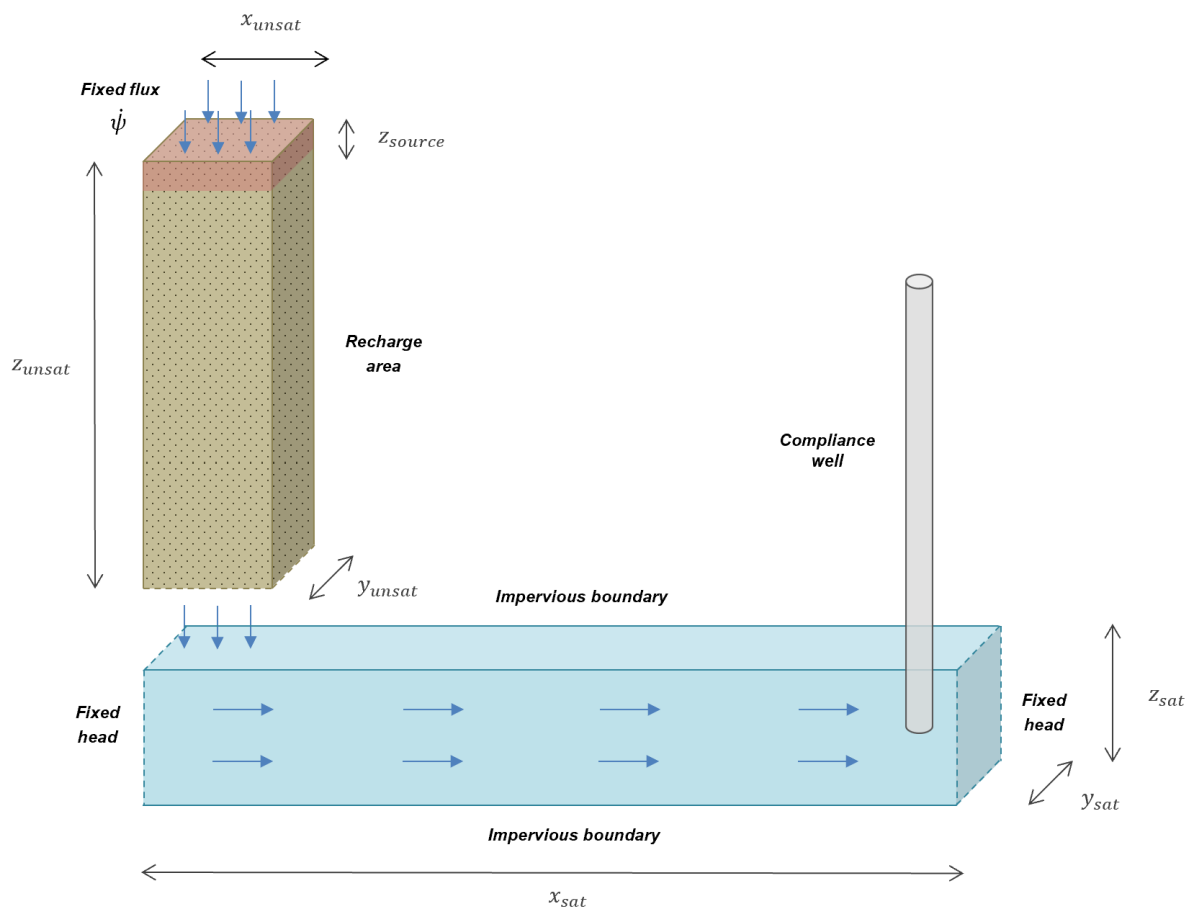


Figure 4. Conceptual model of the aquifer structure of A₁.

A representative radionuclide migration pathway for modelling the A₁ aquifer structure is built by connecting a vertical pipe element, representing a sandy unsaturated recharge area at the foothills of the north-eastern mountains (Figure 3), with a horizontal aquifer element representing the confined aquifer underlying the floodplain. The contaminant source and the CBC $\dot{\psi}(t)$ are placed at the upper boundary of the recharge area due to the confined structure of the aquifer, and the compliance well is hypothesized to be at a x_{sat} distance downgradient with respect to the recharge area. The flow in the horizontal aquifer is assumed to remain in steady state conditions for the whole duration of the process of groundwater contaminant transport and it is obtained through Darcy law as:

$$Q_{sat} = -K_{sat} A_{sat} \nabla h \quad (10)$$

where K_{sat} is the saturated hydraulic conductivity, $A_{sat} = y_{sat} z_{sat}$ is the cross section of the pathway and ∇h is the hydraulic gradient. The geometrical and physical parameters of the developed groundwater model for A₁ are listed in Table 5. In particular, the distributions of K_d and $\dot{\psi}(t_0)$ used in the g -th loop of Monte Carlo simulation are provided; specifically, for each g -th trial, $\dot{\psi}(t_0)$ is resampled at each simulation time step to describe the daily fluctuations of the CBC $\dot{\psi}(t)$.

Parameter	Symbol	Value	Unit	PDF	Source
Infiltration flux	$\dot{\psi}(t_0)$	2	$mm\ day^{-1}\ m^{-2}$	Exponential	(KIGAM, 1997; Kim <i>et al.</i> , 2006), (GIMS, 2025), Engineering judgement
Source depth	z_{source}	0.02	m	[-]	Engineering judgement
Unsaturated zone length	x_{unsat}	10	m	[-]	Engineering judgement
Unsaturated zone thickness	y_{unsat}	1	m	[-]	Engineering judgement
Unsaturated zone depth	z_{unsat}	5	m	[-]	Engineering judgement
Unsaturated zone longitudinal dispersivity	$\alpha_{L,unsat}$	0.5	m	[-]	Engineering judgement
Unsaturated zone saturation level	$S_{l,unsat}$	0.6	[-]	[-]	Engineering judgement
Saturated zone length	x_{sat}	100	m	[-]	Engineering judgement
Saturated zone thickness	y_{sat}	1	m	[-]	Engineering judgement
Saturated zone depth	z_{sat}	3	m	[-]	Engineering judgement
Distribution coefficient of ¹³⁷ Cs (sand)	$K_{d,^{137}Cs}^{sand}$	530 ± 6	$l\ kg^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)

Distribution coefficient of ^{90}Sr (sand)	$K_{d,^{90}\text{Sr}}^{\text{sand}}$	22 ± 6	$l\text{ kg}^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)
Saturated zone longitudinal dispersivity	$\alpha_{L,\text{sat}}$	10	m	[-]	Engineering judgement
Saturated zone saturation level	$S_{l,\text{sat}}$	1	[-]	[-]	Engineering judgement
Saturated zone hydraulic conductivity	K_{sat}	10^{-4}	$m\text{ s}^{-1}$	[-]	(Kim <i>et al.</i> , 2006)
Hydraulic gradient	∇h	0.02	[-]	[-]	(KIGAM, 1997)
^{137}Cs dose conversion factor (adult)	$DC_{^{137}\text{Cs}}$	$1.3 \cdot 10^{-8}$	$Sv\text{ Bq}^{-1}$	[-]	(ICRP, 2012)
^{90}Sr dose conversion factor (adult)	$DC_{^{90}\text{Sr}}$	$2.8 \cdot 10^{-8}$	$Sv\text{ Bq}^{-1}$	[-]	(ICRP, 2012)
Water consumption	V_W	730	$l\text{ year}^{-1}$	[-]	(Cadini, Tosoni and Zio, 2016)

Table 5. List of the parameters used for the GoldSim model of A₁.

3.4.2. A₂ groundwater contaminant transport model

A₂ is characterized by the presence of a shallow costal unconfined aquifer and presents a three-layered stratigraphy: a superficial loamy-sandy (70 % loam and 30 % sand) unsaturated layer which constitute the substrate for rice cultivations, an intermediate saturated sandy layer (the proper aquifer) and a semi-impermeable weathered granite bedrock (Lee and Song, 2007). Also in this case, the aquifer is modelled with GoldSim by connecting an unsaturated vertical pipe element with a horizontal aquifer element. To represent the unconfined structure, the deposited source and the infiltration flux $\dot{\psi}(t)$ is applied along the whole extension of the pathway. A conceptual model of the A₂ aquifer structure is presented in Figure 5 and the related parameters and $\dot{\psi}(t_0)$ are listed in Table 6.

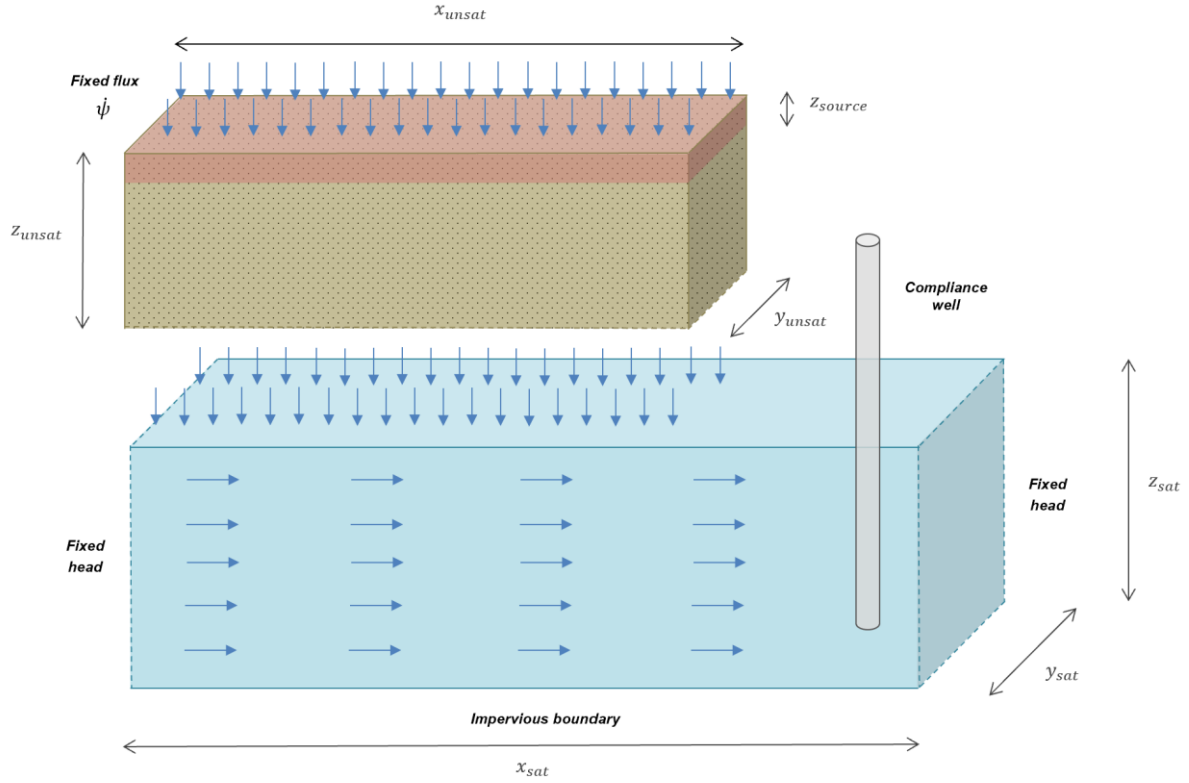


Figure 5. Conceptual model of the aquifer structure of A₂.

Parameter	Symbol	Value	Unit	PDF	Source
Infiltration flux	$\psi(t_0)$	3	$mm\ day^{-1}\ m^{-2}$	Exponential	(KIGAM, 1997; Lee and Song, 2007), (GIMS, 2025), Engineering judgement
Source depth	z_{source}	0.02	m	[-]	Engineering judgement
Unsaturated zone length	x_{unsat}	100	m	[-]	Engineering judgement
Unsaturated zone thickness	y_{unsat}	1	m	[-]	Engineering judgement
Unsaturated zone depth	z_{unsat}	2	m	[-]	Engineering judgement
Unsaturated zone longitudinal dispersivity	$\alpha_{L,unsat}$	0.2	m	[-]	Engineering judgement
Unsaturated zone saturation level	$S_{l,unsat}$	0.9	[-]	[-]	Engineering judgement
Saturated zone length	x_{sat}	100	m	[-]	Engineering judgement
Saturated zone thickness	y_{sat}	1	m	[-]	Engineering judgement
Saturated zone depth	z_{sat}	5	m	[-]	Engineering judgement
Distribution coefficient of ¹³⁷ Cs (sand)	$K_{d,^{137}Cs}^{sand}$	530 ± 6	$l\ kg^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)
Distribution coefficient of ⁹⁰ Sr (sand)	$K_{d,^{90}Sr}^{sand}$	22 ± 6	$l\ kg^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)
Distribution coefficient of ¹³⁷ Cs (loam)	$K_{d,^{137}Cs}^{loam}$	3500 ± 4	$l\ kg^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)
Distribution coefficient of ⁹⁰ Sr (loam)	$K_{d,^{90}Sr}^{loam}$	57 ± 6	$l\ kg^{-1}$	Gaussian	(Gil-García, Rigol and Vidal, 2009)

Saturated zone longitudinal dispersivity	$\alpha_{L,sat}$	10	m	[-]	Engineering judgement
Saturated zone saturation level	$S_{l,sat}$	1	[-]	[-]	Engineering judgement
Saturated zone hydraulic conductivity	K_{sat}	10^{-5}	$m s^{-1}$	[-]	(Lee and Song, 2007)
Hydraulic gradient	∇h	0.01	[-]	[-]	(KIGAM, 1997)
^{137}Cs dose conversion factor (adult)	$DC_{^{137}\text{Cs}}$	$1.3 \cdot 10^{-8}$	$Sv Bq^{-1}$	[-]	(ICRP, 2012)
^{90}Sr dose conversion factor (adult)	$DC_{^{90}\text{Sr}}$	$2.8 \cdot 10^{-8}$	$Sv Bq^{-1}$	[-]	(ICRP, 2012)
Water consumption	V_w	730	$l year^{-1}$	[-]	(Cadini, Tosoni and Zio, 2016)

Table 6. List of parameters used for the GoldSim model of A₂.

3.5 Monte Carlo simulation

The following assumptions are undertaken to operationalize the Monte Carlo simulation (Figure 2):

- A set of $N_s = 10^6$ Monte Carlo trials are run for the evaluation of the dispersion model. To model the marginal PDFs of the deposited concentrations of ^{90}Sr and ^{137}Cs , a truncated Gamma PDF is chosen from a pool of candidate distributions through model selection testing by employing Akaike Information Criterion (AIC) (Mutua, 1994).
- A set of $N_g = 10^3$ Monte Carlo trials are run for the evaluation of the groundwater contaminant transport model and the estimation of the D_{peak} distribution.
- An importance sampling algorithm (GoldSim, 2021b) is adopted to characterize the right tail of the deposited ST PDFs, to ensure its representativeness using a limited number N_g of Monte Carlo trials and to limit the computational effort required by the analysis.
- An empirically estimated Pearson correlation coefficient $\rho(^{137}\text{Cs}, ^{90}\text{Sr})$ is imposed between the samples drawn from the fitted PDFs of ^{137}Cs and ^{90}Sr (Iman and Conover, 1982).
- The analysis of the scenarios listed in Table 1 are conducted with the same seeds of the random number generators adopted throughout the sampling of the parameters used to feed the atmospheric dispersion and the groundwater contaminant transport models, to guarantee that the scenarios outcomes are fairly compared.

4. Results and discussion

The effect of CC on the PSA outcomes are discussed in terms of Conditional Value at Risk (CVaR) (Dixit, Verma and Tiwari, 2020; Di Maio, Tonicello and Zio, 2022):

$$CVaR(D_{peak}) = \mathbb{E}[D_{peak} | D_{peak} > \tau] \quad (11)$$

and exceedance probability P_{ex} (Chang and Shinozuka, 2004; Di Maio, Tonicello and Zio, 2022):

$$P_{ex} = \frac{N_{ex}}{N_g} \quad (12)$$

where τ is the regulatory threshold corresponding to the dose limit for drinking water, in this work conservatively assumed equal to 10^{-4} Sv/year (Park *et al.*, 2021), and N_{ex} is the number of simulations in which $D_{peak} > \tau$.

4.1 Results for the aquifer located in A₁

The Complementary Cumulative Density Function (CCDF) of D_{peak} for the aquifer located in A₁ is presented in Figure 6 for each CC impact scenario listed in Table 1. As it can be seen, the CCDFs shift to the right, i.e., to high dose levels, as the SB IE frequency variation α_{SB} due to CC increases with respect to the *Baseline* scenarios and β increases. In other words, wetter CBCs lead to larger D_{peak} , whereas drier CBCs lead to lower D_{peak} . In the end, the worst scenario is due to the combination of SB frequency increase and wetter CBCs, i.e., *CC-induced_{wet}*, whereas the scenario with the lowest D_{peak} results from the combination of no SB frequency increase and drier CBC, i.e., *Baseline_{Dry}*. Nevertheless, D_{peak} CCDFs span in a range from 10^{-9} to 10^{-4} Sv/yr, meaning that the probability of exceeding τ is extremely small.

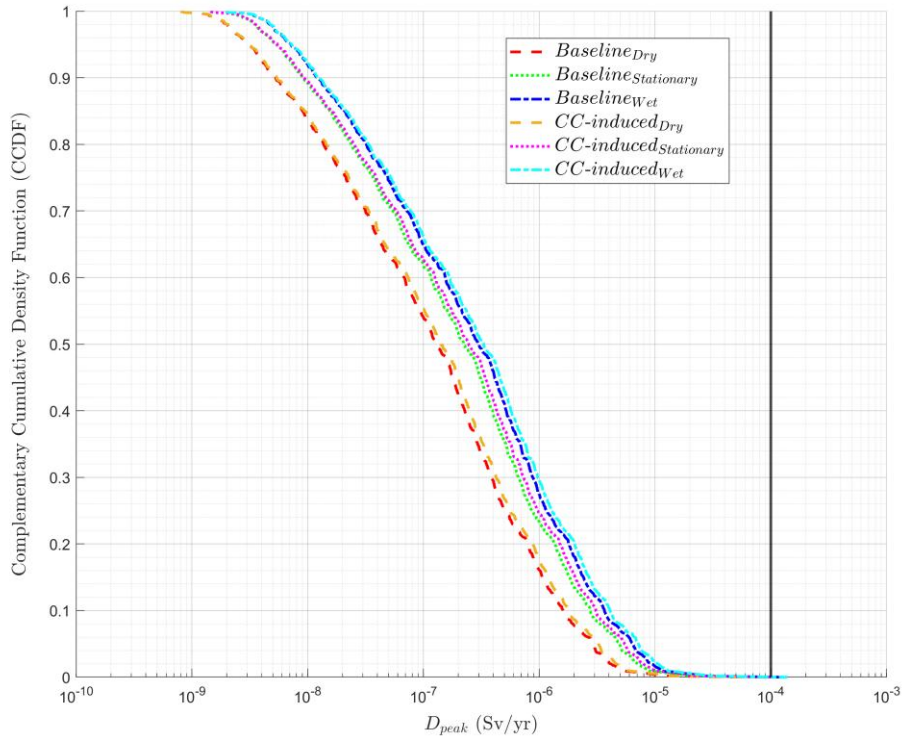


Figure 6. Peak dose CCDFs for the aquifer located in A_1 .

The PDF of the breakthrough time t_{peak} is presented for each scenario in Figure 7. In this case, only CBCs variations lead to a notable difference with respect to the *Baseline* case since the variation of t_{peak} is only induced by the imposed CBC (i.e., the hydraulic boundary condition). Moreover, the effect of the CC-related assumptions is opposite to that for D_{peak} (wetter scenarios lead to higher D_{peak} whereas drier scenarios lead to lower D_{peak} with respect to *Baseline*), namely, wetter CBCs lead to a lower t_{peak} whereas drier CBCs lead to a higher t_{peak} , as physically expected (Govindaraju and Das, 2007).

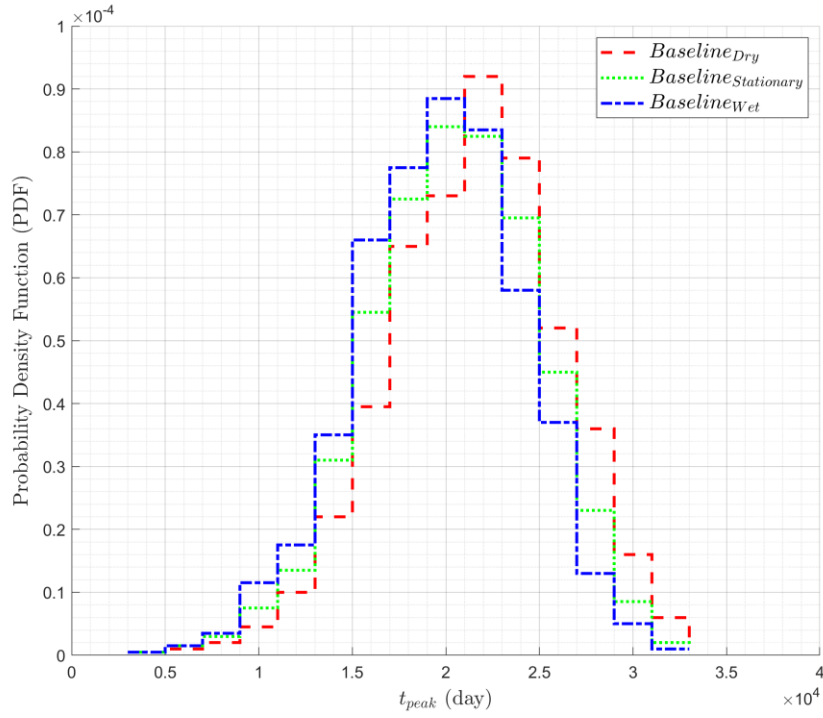


Figure 7. Breakthrough time PDFs for the aquifer located in A₁.

The CVaR and P_{ex} of D_{peak} are shown in Figure 8 to highlight the risk relevance of the results.

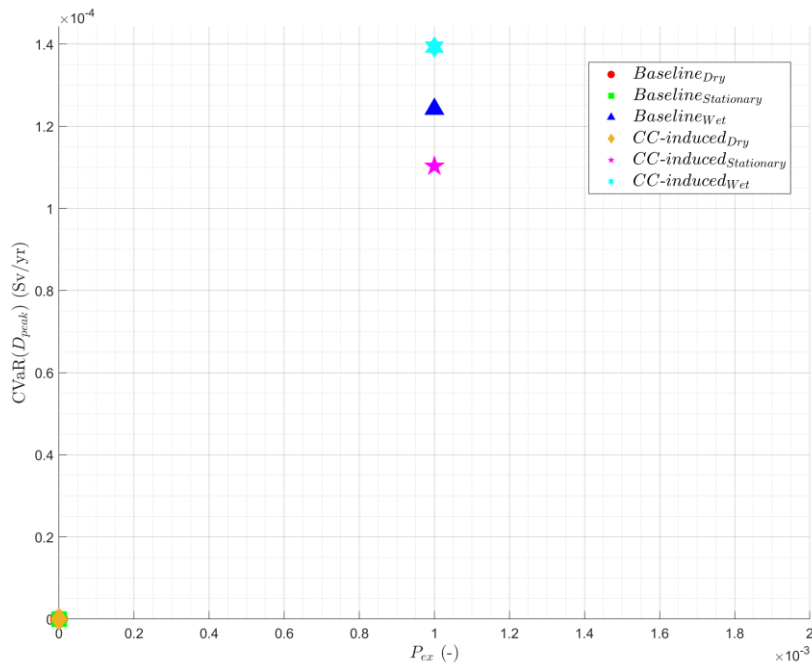


Figure 8. Scatter plot of CVaR (y-axis) versus P_{ex} (x-axis) for the aquifer located in A₁. Both metrics are referring to values of D_{peak} exceeding the regulatory threshold of $\tau = 10^{-4}$ Sv/yr (Park *et al.*, 2021).

It can be seen that only some CC-related scenarios lead to $P_{ex} > 0$, meaning that CC plays a relevant role for exceeding τ in the future. Also, CVaR shows that extreme wetter CBCs are more important than the increase of frequency of the SB IE (CVaR associated to *Baseline_{Wet}* scenario (blue triangle) is higher than the one related to *CC-induced_{Stationary}* scenario (magenta star)). In summary, CC effects need to be considered in the PSA to avoid underestimating the environmental consequences of a NPP severe accident in terms of groundwater contamination.

4.2 Results for the aquifer located in A₂

The D_{peak} CCDFs for the aquifer located in A₂ are presented in Figure 9. Also in this case, the same considerations drawn from the results of A₁ hold true. Nevertheless, in this case, the CCDFs are shifted on higher average dose levels for all scenarios (including *Baseline*) and span in a range from 10^{-8} to 10^{-4} Sv/yr. Moreover, a clear overlapping between τ and the CCDFs right tails is observable.

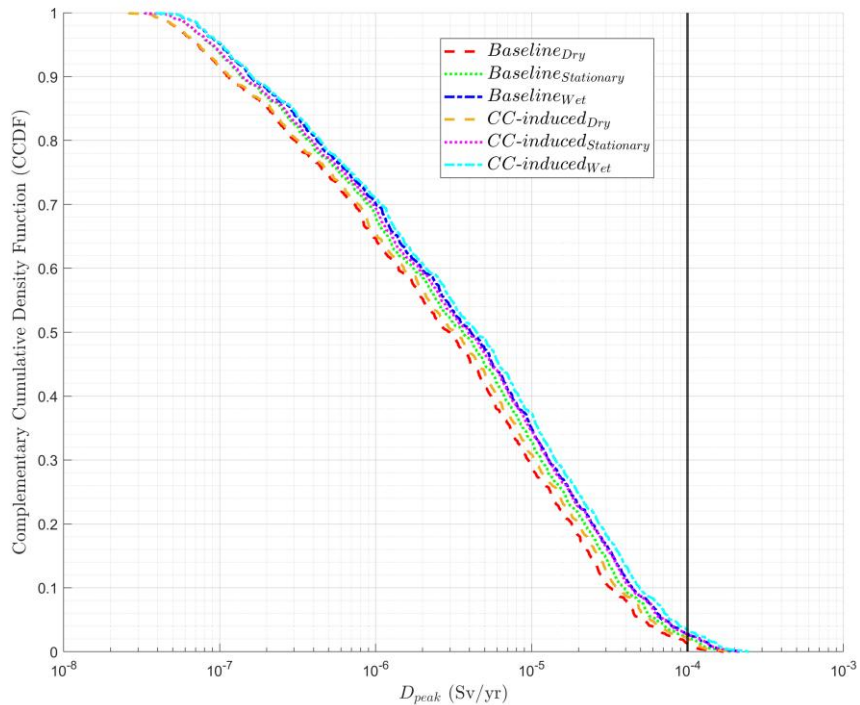


Figure 9. Peak dose CCDFs for the aquifer located in A₂.

The PDFs of t_{peak} for the aquifer located in A_2 are presented in Figure 10. Also in this case, the same considerations regarding the role of wetter or drier CBCs hold true. Nevertheless, in this specific case a greater difference between the different β -related assumptions is evident, i.e., the PDFs of the different scenarios exhibit less overlap and more pronounced skewness with respect to the ones plotted in Figure 7, indicating that the aquifer located in A_2 is more sensitive to CBCs variations than the aquifer located in A_1 (possibly due to the unconfined structure of A_2). Specifically, the PDFs of the t_{peak} for the *Baseline_{Dry}* and *Baseline_{Wet}* cases are more negatively skewed than the PDF of t_{peak} for the *Baseline_{Stationary}* case.

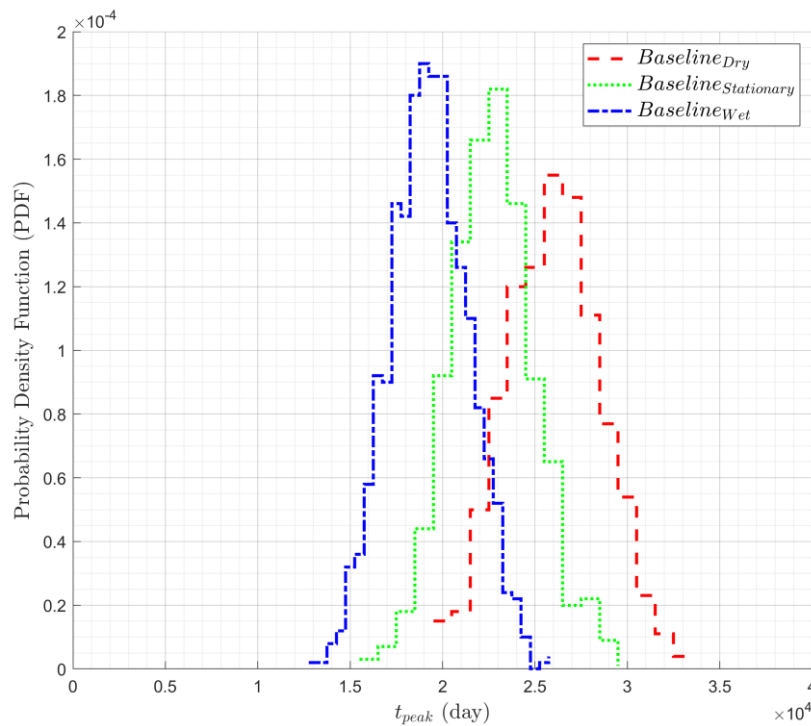


Figure 10. Breakthrough time PDFs for the aquifer located in A_2 .

The CVaR and P_{ex} for the aquifer located in A_2 are shown in Figure 11. In this case, for every CC impact scenario $P_{ex} > 0$, and it is an order of magnitude higher than the values previously calculated for the aquifer located in A_1 . Moreover, in this case, it can be observed that the maximum spread of the risk metrics, i.e., the interval between the best and worst outcomes across all scenarios, is in the range $[0.013, 0.035]$ for P_{ex} and $[1.23 \cdot 10^{-4}, 1.45 \cdot 10^{-4}]$ Sv/yr for CVaR. In addition, the comparison of Figure 11 and Figure 8 highlights that the introduction of CC effects can have an important impact on the calculation of risk metrics related to the D_{peak} from contaminated groundwater ingestion, even if the magnitude of such effects is strictly controlled

by the aquifer hydrogeological structure i.e., unconfined aquifers are more susceptible to fallout contamination, resulting in higher peak doses under otherwise identical conditions. This highlights that the vulnerability and risks associated with CC are spatially heterogeneous and require a tailored methodology, i.e., case study-dependent, to be properly evaluated. For the sake of comparison, in Table 7, the numerical results of the CVaR and P_{ex} for A_1 and A_2 are reported.

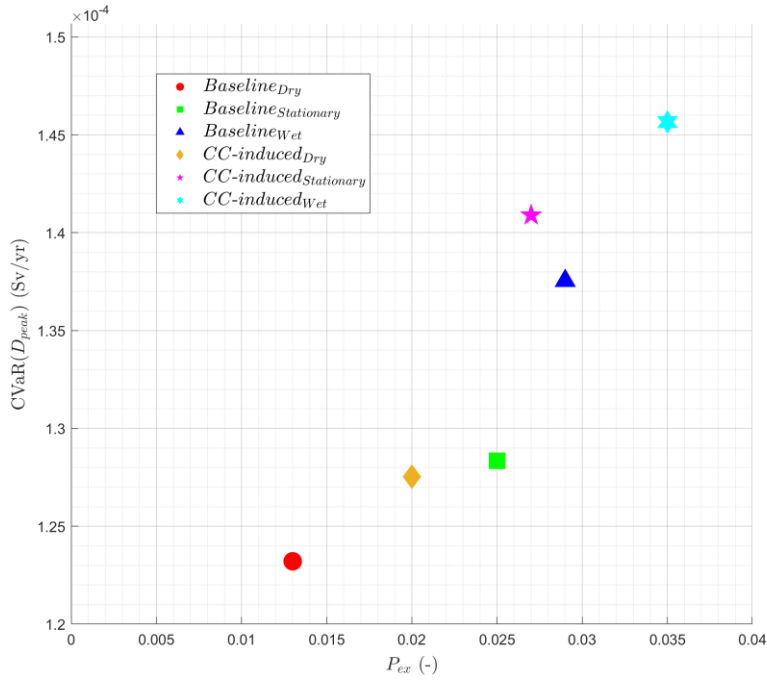


Figure 11. Scatter plot of CVaR (y-axis) versus P_{ex} (x-axis) for the aquifer located in A_2 . Both metrics are referring to values of D_{peak} exceeding the regulatory threshold of $\tau = 10^{-4}$ Sv/yr (Park *et al.*, 2021).

Scenario	A_1		A_2	
	P_{ex}	CVaR	P_{ex}	CVaR
<i>Baseline_{Dry}</i>	$P_{ex} = 0$	CVaR = 0	$P_{ex} = 1.3 \cdot 10^{-2}$	CVaR = $1.23 \cdot 10^{-4}$
<i>Baseline_{Stationary}</i>	$P_{ex} = 0$	CVaR = 0	$P_{ex} = 2.8 \cdot 10^{-2}$	CVaR = $1.28 \cdot 10^{-4}$
<i>Baseline_{Wet}</i>	$P_{ex} = 10^{-3}$	CVaR = $1.22 \cdot 10^{-4}$	$P_{ex} = 2.9 \cdot 10^{-2}$	CVaR = $1.37 \cdot 10^{-4}$
<i>CC-induced_{Dry}</i>	$P_{ex} = 0$	CVaR = 0	$P_{ex} = 2.0 \cdot 10^{-2}$	CVaR = $1.27 \cdot 10^{-4}$
<i>CC-induced_{Stationary}</i>	$P_{ex} = 10^{-3}$	CVaR = $1.15 \cdot 10^{-4}$	$P_{ex} = 2.7 \cdot 10^{-2}$	CVaR = $1.41 \cdot 10^{-4}$
<i>CC-induced_{Wet}</i>	$P_{ex} = 10^{-3}$	CVaR = $1.39 \cdot 10^{-4}$	$P_{ex} = 3.5 \cdot 10^{-2}$	CVaR = $1.46 \cdot 10^{-4}$

Table 7. CVaR and P_{ex} values calculated for A_1 and A_2 .

4.3 Implications for risk-informed decision making

The results presented in Section 4.1 and Section 4.2 highlight the added value of performing a bounding analysis with the proposed simulation-based PSA framework; the evaluation of multiple CC scenarios enables the assessment of the possible high-level consequences of CC on PSA outputs even in the case of substantial uncertainty on the magnitude of such effects. Specifically, in Figure 12 the relative differences $\Delta CVaR$ and ΔP_{ex} between each CC scenario and the $Baseline_{Stationary}$ values of CVaR and P_{ex} are reported for the aquifer located in A_2 , which has resulted more exposed to fallout contamination. The results of the $Baseline_{Stationary}$ scenario are taken as the reference values representative of the PSA outcome when CC-related effects are not considered. As shown in Figure 12, $\Delta CVaR$ and ΔP_{ex} increase more in the upper right quadrant of the $\Delta CVaR-\Delta P_{ex}$ plane with respect to the lower left quadrant of the $\Delta CVaR-\Delta P_{ex}$ plane, showing the non-linear response between CC-related assumptions and PSA outcomes. In this specific case, the assumptions related to the realization of wetter future conditions, i.e., $Baseline_{Wet}$ and $CC-induced_{Wet}$, increase substantially the risk associated to aquifer contamination and this, underlines the relevance of considering CC-related effects in the risk assessment of the environmental consequences of NPP severe accidents.

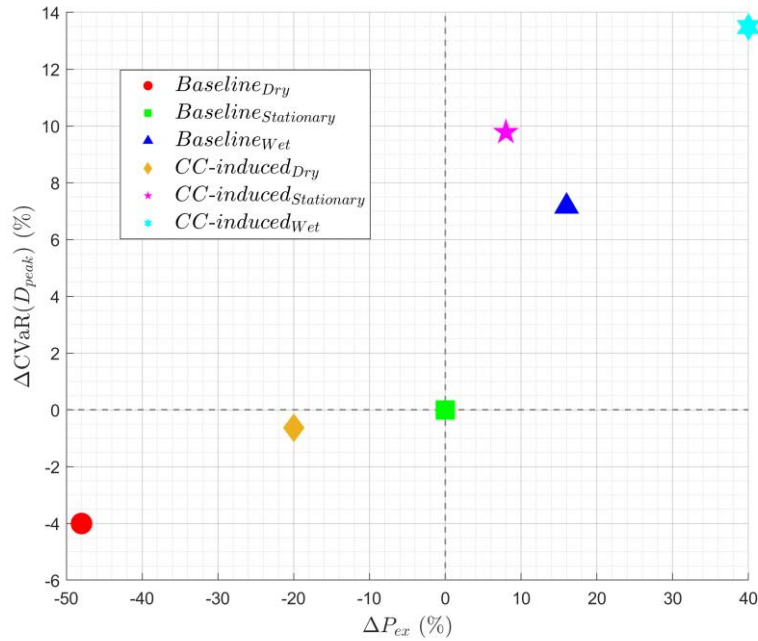


Figure 12. Scatter plot of $\Delta CVaR$ (x-axis) versus ΔP_{ex} (y-axis) for the aquifer located in A_2 . For both metrics the reference scenario for the calculation of the relative differences is $Baseline_{Stationary}$.

Indeed, by assuming the perspective of a highly risk-averse decision maker, quantitative metrics like P_{ex} and CVaR enable the calculation of the expected maximum loss in the case of the worst-case CC scenario. Instead, by assuming the perspective of a moderately risk-averse decision maker, these metrics could guide the risk-constrained optimization of possible NPP CC resilience strategies by comparing the maximum expected loss incurred when these strategies are not implemented.

5. Conclusions

In this paper, a computational framework for PSA of NPPs has been presented, capable of accounting for the CC-induced effects on long-term dose due to contaminated groundwater ingestion. The framework couples *i*) a CC impact assessment model, *ii*) a ST estimation model, *iii*) an atmospheric dispersion model, *iv*) a groundwater contaminant transport model, to quantify and propagate the uncertainties arising from CC related variables during the accident development, i.e., starting from the ST release (L1-L2 PSA), through the atmospheric dispersion and fallout deposition processes (L3 PSA), until the aquifer contamination (L3 PSA). The impacts of CC are introduced both at the L1 PSA interface, i.e., in terms of IEs frequency increase and at the L3 PSA interface, i.e., wetter or drier aquifer CBCs. The framework is exemplified on a case study related to a multi-unit NPP located in South Korea to evaluate the environmental impact of a hypothetical severe accident on two nearby aquifers. The results, provided in terms of CVaR and probability of exceedance of the regulatory dose limit, highlight that CC can be relevant for safety-related decision-making. Specifically, under the assumptions made in the considered case study, due to CC both the CVaR and the probability of exceedance of the regulatory dose limit are increased, so that, NPPs safety barriers should be designed considering also the CC contribution to dose exceedance.

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Appendix A

The multiplicative factor α_i of Eq. 1 is defined as:

$$\alpha_i = \frac{f_i(T)}{f_i(t_0)} = \frac{\mathcal{F}_i(m(T)) \mathcal{T}_r(m(T))^{-1}}{\mathcal{F}_i(m(t_0)) \mathcal{T}_r(m(t_0))^{-1}} \quad (\text{A.1})$$

where at a generic time t , the frequency of occurrence of the i -th IE f_i , $i = 1, 2, \dots, I$, is equal to (IAEA, 1993; Kumar *et al.*, 2017):

$$f_i(t) = \mathcal{F}_i(m(t)) \mathcal{T}_r(m(t))^{-1} \quad (\text{A.2})$$

where $\mathcal{F}_i(m(t))$ is the fragility curve that maps the probability of the i -th IE occurring conditional to the hazard induced by a climatic variable $m(t)$ and $\mathcal{T}_r(m(t))$ is the return time of the hazard intensity induced by $m(t)$, which typically is defined by regulation (it is worth mentioning that Eq. A.2 is applicable in the context of a bounding analysis of external IEs (U.S. Nuclear Regulatory Commission, 2020)).

If $m(\cdot)|\mathcal{T}_r$ are evaluated for the same return period, i.e., $\mathcal{T}_r(m(T)) = \mathcal{T}_r(m(t_0)) = \mathcal{T}_r$, Eq. A.1 simplifies to:

$$\alpha_i = \frac{\mathcal{F}_i(m(T)|\mathcal{T}_r)}{\mathcal{F}_i(m(t_0)|\mathcal{T}_r)} \quad (\text{A.3})$$

Under the assumptions that the fragility curve $\mathcal{F}_i(\cdot)$ is time invariant and differentiable, the numerator of Eq. A.3 can be expanded in a Taylor series truncated to the first order:

$$\alpha_i \cong \frac{\mathcal{F}_i(m(t_0)|\mathcal{T}_r) + \mathcal{F}'_i(m(t_0)|\mathcal{T}_r)(m(T)|\mathcal{T}_r - m(t_0)|\mathcal{T}_r)}{\mathcal{F}_i(m(t_0)|\mathcal{T}_r)} \quad (\text{A.4})$$

if $\varepsilon_i = \frac{\mathcal{F}'_i(m(t_0)|\mathcal{T}_r)}{\mathcal{F}_i(m(t_0)|\mathcal{T}_r)}$, Eq. A.4 reduces to Eq. A.5, that corresponds to Eq. 2 of Section 2.1:

$$\alpha_i \cong 1 + \varepsilon_i (m(T)|\mathcal{T}_r - m(t_0)|\mathcal{T}_r) \quad (\text{A.5})$$

Appendix B

For the case study presented in Section 3, the i -th IE considered is the SB caused by flooding due to an extreme precipitation event. Therefore, $m(x, y, t)$ is the maximum annual daily cumulative precipitation level in the location (x, y) . For $\mathcal{T}_r = 50$ yr, $m(t_0)|_{\mathcal{T}_r} = 220$ mm and $m(T)|_{\mathcal{T}_r} = 315.2$ mm (Shin et al. 2021). To model the NPP SSCs fragility to flooding the log-normal fragility curve plotted in Figure B.1 has been employed (B. J. Kim, Kim, Hahm, and Han 2021): $m(t_0)|_{\mathcal{T}_r}$ returns $\varepsilon_i = 0.095$.

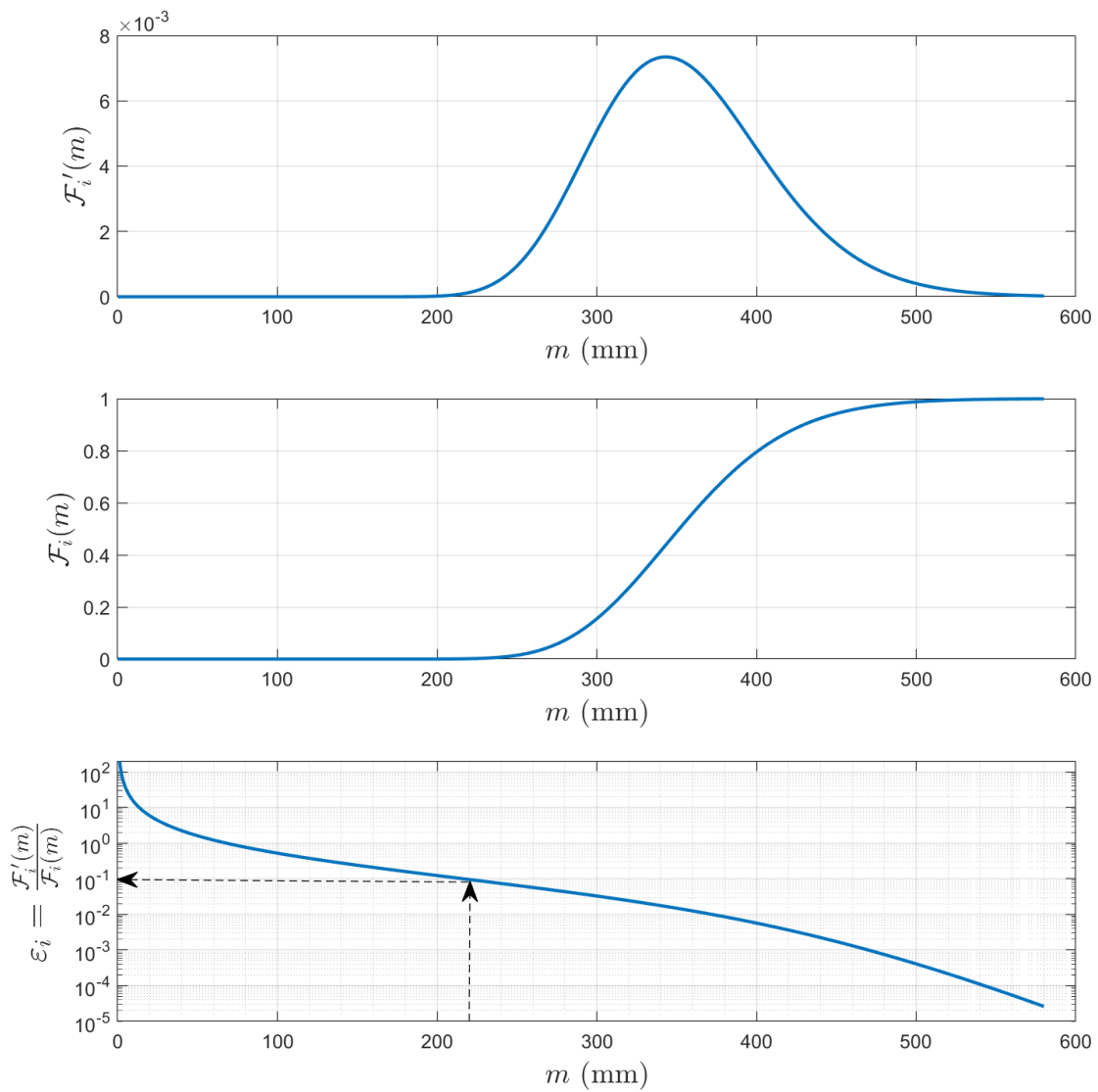


Figure B.1. Log-normal flooding fragility curve $\mathcal{F}_i(m)$, its derivative $\mathcal{F}'_i(m)$ and $\varepsilon_i(m)$.

Appendix C

The PMF P_n of Eq. 9 is motivated by the results provided in (Marchetti, Di Maio and Zio, 2025). Figure C.1 shows the fitting of the PMFs listed in Table C.1 to the probability that $n = 1, 2, 3, 4$ units of a multi-unit NPP fail due to the same IE. The lowest Akaike Information Criterion (AIC) is provided by the Truncated Poisson, then by the Truncated Negative Binomial, finally by the Truncated Discrete Exponential that is the only distribution that does not underestimate the probability of $n = 4$ units failure. Thus, in this work a Truncated Discrete Exponential is conservatively adopted in Eq. 9.

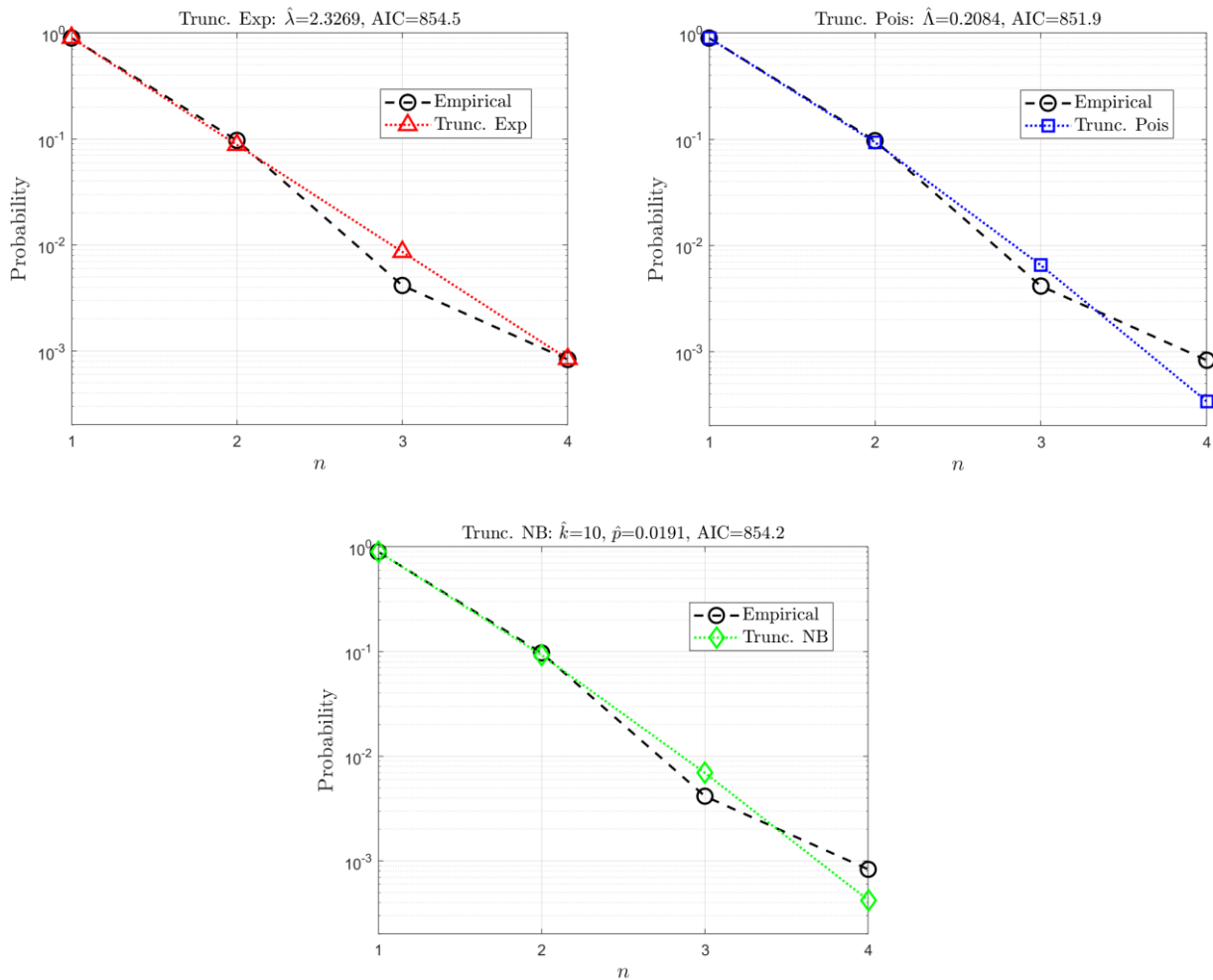


Figure C.1. Comparison between the fitted PMFs and the empirical PMF.

Distribution	Shape	Parameters	Source
Truncated Discrete Exponential	$P_n = \frac{e^\lambda - 1}{1 - e^{-\lambda N}} e^{-\lambda n}$	$\lambda > 0$	(Berber, 2017)
Truncated Poisson	$P_n = \frac{\Lambda^n e^{-\Lambda}}{n!} (1 - e^{-\Lambda})$	$\Lambda > 0$	(Plackett, 1953)
Truncated Negative Binomial	$P_n = \frac{w^k (k + n - 1)!}{1 - w^k (k - 1)! n!} \eta^n$ $\begin{cases} w = 1/(1 + p) \\ \eta = (1 - w) \end{cases}$	$p \in [0,1]$ $k \in \mathbb{N}$	(Sampford, 1955; Brass, 1958)

Table C.1. The employed truncated discrete distributions.

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