

The use of a credibility index in life-cycle assessment of structures

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The use of a credibility index to aid the probabilistic life-cycle assessment of bridges

The behavior of structural systems can change during their service lives due to unexpected loadings, environmental effects, and deterioration processes. In order to optimize maintenance interventions, the life-cycle of a structure has to be properly assessed.

Structural Health Monitoring (SHM) using collected experimental data provides a method for assessing the structural behavior over time. Since the cost related to SHM is substantial, sometime monitoring is limited in space and time. The modeling of the structural behavior based on few experimental data is characterized by uncertainty both in the choice of the appropriate model (epistemic uncertainty) and in parameters estimation (aleatory uncertainty).

This paper provides an original procedure to support decisions in the presence of epistemic uncertainty. The procedure provides the development of a credibility index able to catch, between two possible models, which is the most reliable to describe the evaluation of parameters of interest.

Considering as a case-study the occurrence of a foundation settlement in an arch bridge, the efficacy of the model proposed has been assessed. The approach can be applied to investigate the behavior of other aspects of the life-cycle assessment: the evolution of structural resistance, the failure time of an element or of the whole system.

Keywords: Life-Cycles Performance; Prediction Models; Uncertainty; Bridges; Infrastructure Management; Concrete Structures

Introduction

Several unforeseen causes can lead to a unexpected behavior of the structural systems over time: deterioration processes due to chemical attacks (Bertolini et al. 2004; Biondini et al. 2004; Sietta 2005; Biondini and Frangopol 2008), uncertainty in time-

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3 dependent behavior of concrete (Camossi et al. 2010; Malerba et al. 2011), foundation
4 settlement (Terzaghi and Peck 1948; Das and Sivakugan 2007; Zhao et al. 2011), etc..
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6 Therefore, the service life, aesthetics, and structural proprieties of the system under con-
7 sideration may be compromised (Casciati and Faravelli 2010). Considering the above, it
8 is clear that the structural analysis of existing buildings and constructions must be able
9 to take into account some of these time-dependent phenomena. As a consequence, in the
10 last decade, as a response to this demand, the Structural Life-Cycle Analysis (LCA) was
11 developed and, nowadays, LCA, along with monitoring and planning methods, is play-
12 ing an important role in civil engineering (Furuta et al. 2008; Furuta et al. 2011; Basso
13 N. et al. 2012; Garavaglia et al. 2012, Basso P. et al. 2012, Okasha and Frangopol 2012,
14 Decò and Frangopol 2013).

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16 Any approach to LCA that does not consider time dependent effects could lead
17 to a lack understanding of the assessment itself, and can potentially have as a conse-
18 quence the improper planning of maintenance or repair actions, eventually leading even
19 to the structural collapse of the system, with further expensive rehabilitation or rebuild-
20 ing costs (Woodward 1988; Ciampoli 1998, Goins 2000; Proverbio et al. 2000). For this
21 reason, LCA should not be implemented with a deterministic analysis, but it has to in-
22 volve models and methods able to take into account the uncertainties present in it (Mes-
23 servey et al. 2011, Elnashai and Tsompanakis 2012).

24
25 Over the last decade, different fuzzy or probabilistic approaches have been de-
26 veloped for studying the uncertainties involved in the problem (Biondini et al. 2004,
27 Sgambi 2004, Akgul and Frangopol 2005, Pellissetti and Schüeller 2007, Pradlwarter et
28 al. 2007, Bontempi et al. 2008, Melchers and Frangopol 2008, Möller and Beer 2008,
29 Sgambi et al. 2012).

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31 The uncertainty that can compromise a probabilistic modeling can be classified

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3 in: epistemic uncertainty and aleatory uncertainty (Vere – Jones and Ozaki 1982, Vere-
4 Jones et al. 1995, Grandori et al. 1998, Ang 2004, Masri et al. 2009, Sankararaman and
5 Mahadevan 2011, Ciampoli and Petrini 2012). The first one involves uncertainties that
6 can be reduced through the attainment of more information and includes modeling
7 choice and error. The second one involves statistical uncertainties regards the model's
8 parameters estimation. Even if the model is correct it contains parameters that need to
9 be estimated, often on the basis of the available experimental data.
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20 In statistical analysis the choice between different models is usually supported
21 by classic statistical tests, typically: maximum likelihood criterion or least squares
22 method. Considering mainly the physics aspects of the phenomenon, these tests help to
23 define the reliability of one model (or hypothesis), but a model isn't just a statistic con-
24 sequence of a data set. Each distribution contains some physical interpretations and
25 physical information that make the decision – making process easier and more aware
26 (Guagenti et al. 2003, Blasone et al. 2008, Biondini et al. 2010, Goulet and Smith 2011,
27 Garavaglia 2012).
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37 Even if a model involves a subjective choice due to data interpretation, a careful
38 analysis makes this choice reasonable and confident. Considering problems using small
39 samples, a residual uncertainty range remains, in fact if few experimental data are avail-
40 able parameters estimation can be compromised.
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46 In structural analysis, the evolution history of certain quantities can be modeled
47 on the basis of monitoring data. However, only long-term and preferably continuous
48 monitoring enables the best possible characterization of the parameter's variability over
49 time. Because of the costs related to SHM are rather important, sometimes they are car-
50 ried out within limited spatial and temporal bases and the data are recorded in a discrete
51 way (only in some instants of the structural life span). In this case the estimation of the
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3 parameters involved in the modeling will be based on few available monitoring data and
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5 it could suffer from statistical uncertainty.
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8 In this study, in order to investigate the error made in the modeling of a given
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10 structural quantity C in presence of few data, following the method proposed by Gran-
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12 dori (Grandori et al. 1998, 2003), a suitable credibility index has been developed. Ob-
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14 jective of this index is to identify the most reliable model among some possible compet-
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16 itor models to foresee the behavior of a given parameter over the structure lifespan,
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18 even if the monitoring campaign is already terminated.
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21 The developed methodology cannot solve the problem of the aleatory uncertain-
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23 ty affecting the estimation of parameters but it can be considered a valid supporting tool
24
25 for dealing with decisions affected by epistemic uncertainty (e.g. the choice of the most
26
27 reliable modeling for describing the evolution of a physical phenomenon).
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30 This paper wants to point out the credibility index's effectiveness and potential
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32 with respect its possible engineering applications. The proposed methodology is applied
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34 to assess the service life of an arch bridge affected by unexpected foundation settlement
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36 C . Considering the structure of a Maillart's bridge, the beginning of foundation settle-
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38 ment is assumed to occur during its structural life. Since currently real monitoring data
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40 aren't available, it will be here assumed that the settlement varies following a known
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42 polynomial law. Applying a random procedure a possible dataset, simulating monitoring
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44 data, will be drawn and, on it, two evolution laws (r and s) will allow to foresee the
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46 structural behavior over the first decade of the bridge's service life, and in the following
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48 ones. Using the credibility index, it will be possible to point out which of the two mod-
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50 els is closer to the actual behavior of the structure. Assuming two different trends of the
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52 settlement over time, the goal of this study is to verify the reliability of the index intro-
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The credibility index

Starting from a single data set concerning a given quantity C , the question is how to estimate the evolution of this quantity over time. The attention is focused on the error in estimating the quantity C . More generally, considering various and reasonable models, the goal is distinguishing the most reliable approach in order to estimate the quantity C studied. Following this objective and comparing two models a time, the procedure here presented is able to give an opinion on which, between the two model investigated, is the most reliable in the evaluation of C .

Uncertainty in the evaluation of C in presence of few data and known evolution law F° .

If the evolution law F_C° of a given parameter C is completely defined over time (i.e. a probabilistic cumulative distribution), in each instant t^* the quantity C assumes the “true value” C° and it can be considered as the *statistical truth*. When the real process F_C° is well known but only samples of few data are available, an adequate modeling of them is necessary but, sometime, not simple. The measure of the error made using a wrong modeling can be investigated through the building of the credibility index Δ . Using a Monte Carlo simulation and following a random drawing procedure, several size v samples can be drawn from the evolution law F_C° ; they set up different conjectural realities, which the modeling must be based on. Assuming a plausible r – model, defined by its F_r law, each sample will be modeled with the r – model, and the value C_r will be evaluated for each instant t^* . Thus the random variable \hat{C}_r is defined as the set of all C_r values obtained for each sample at every t^* time. The random variable’s distribution is the sampling distribution of the parameter C .

The index:

$$\Delta_r^\circ = \Pr \left\{ C^\circ - h < \hat{C}_r \leq C^\circ + h \right\} \quad (1)$$

shows the probability the value \hat{C}_r , estimated with the r – model, is within a given range around the *true* value C° (h defines a conventional range around C°).

Considering a random size v sample drawn from F_C° , Δ_r° indicates the probability that the model F_r leads to the C° value, with an error $\varepsilon_r^\circ \leq h$ (as absolute value)

$$\Delta_r^\circ = \Pr \left\{ \left| \varepsilon_r^\circ \right| \leq h \right\}. \quad (2)$$

Assuming a second plausible model, s – model (with law F_s), the same method can be applied and the index can be defined as:

$$\Delta_s^\circ = \Pr \left\{ C^\circ - h < \hat{C}_s \leq C^\circ + h \right\} \quad (3)$$

The difference

$$\Delta_{rs}^\circ = \Delta_r^\circ - \Delta_s^\circ \quad (4)$$

describes the *relative credibility* of the two models (Grandori et al. 1998, 2003). Evaluating C , if r – model is more reliable than s – model, the index Δ_{rs}° will be greater than zero, while if the s – model is the most reliable, Δ_{rs}° will be negative. Therefore, modeling a given quantity C , the sign of Δ_{rs}° is essential because it decides which model is the most reliable. The last statement underlines another property of the credibility index Δ . In Figure 1 the whole procedure is depicted.

[FIGURE 1 – HERE]

When C is the estimable quantity, starting from a small data set and considering *epistemic* uncertainty, the index Δ_{rs}° assesses the *credibility* of r – model in respect to F_C° ; furthermore the index Δ_{rs}° enables to choose the most reliable model among two possible paths for modeling the given parameter C .

The index Δ_{rs}° cannot be considered as a complete validation of the model but instead an indicator of the goodness of the model chosen.

Uncertainty in the evaluation of C in presence of few data and unknown evolution law F°

When the real process F_C° is unknown and the modeling is only based on few monitoring data, investigating its credibility becomes very useful (Guagenti et al. 2003, and Garavaglia et al. 2010).). The procedure must be applied to the only available object: the data set, limited over space and time, and obtained by a monitoring action, operating on a given structure. Starting from the collected data, an experimental law F_C^* can be set up (e.g. a polyline); within this law, the monitoring instants are the points where the C^* values are estimated. Following the above-mentioned method, the empirical index Δ_{rs}^* can be assessed. This index is defined using a limited time of analysis; furthermore if no physical knowledge is available, the real behavior of the parameter in the future seems to be unpredictable. Therefore, it is necessary to investigate how much the index Δ_{rs}^* is *representative* of the real unknown Δ_{rs}° . Starting from the observed data, the conditional probability:

$$\Omega = \Pr\left\{\Delta_{rs}^{\circ} > 0 \mid \Delta_{rs}^* > 0\right\} \quad (5)$$

evaluates the posterior probability of hypothesis (Figure 2).

[FIGURE 2 – HERE]

Quantity Ω describes the probability that the unknown real Δ_{rs}° can be greater of zero if the experimental Δ_{rs}^* is greater of zero. In other words, Ω describes the probability that the more reliable model, actually, will be the r -model if $\Delta_{rs}^* > 0$, and vice versa. Assessing Ω , all the possible realities must be pointed out, even if Ω cannot be exactly defined. However, it is possible to study several plausible realities (Guagenti et al. 2003). The above-mentioned simulation and estimation must be repeated for each of the studied realities. Therefore, the observed value Δ^* becomes much more than an indicator of goodness: it measures the winning probability of a model over another one.

Application to a case study

To evaluate the efficacy and the applicability of the procedure to a real structural problem, the authors proposed its application on an existing structure. The application is the first test of this procedure. Even if the case-study is a real structural system, with regard to the dangerous phenomenon studied, the foundation settlement, some assumptions in data and evolution laws must be made, since currently there are no real data which are completely available. The case-study chosen is the existing arch bridge over the Corace river (Calabria, Italy), built in 1955 (Galli and Franciosi 1955).

The bridge has suffered from foundation problems such as a recent landslide that occurred in 2010. For this reason, it is currently subject to a monitoring activity by the “Regione Calabria”, but, currently, such data is not available.

Figure 3 shows bridge’s dimensions (Franciosi 1971, Ronca and Cohn 1979,

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3 Biondini and Frangopol 2008b); the arch span is 80.7 m. Table 1 presents the distribu-
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5 tion of steel reinforcement into different sections of the bridge.
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10 [FIGURE 3 – HERE]
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13 [TABLE 1 – HERE]
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18 The bridge is expected to be affected by a variable foundation settlement over
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20 time. Assuming that during the first 10 years following the construction, few monitoring
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22 data concerning the foundation settlement can be made, it becomes relevant to investi-
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24 gate its evolution law over time starting from the few monitoring data collected. Refer-
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26 ring to the methodology introduced above, the model to be judged consists in the evolu-
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28 tion law F_C° of the foundation settlement $C(t)$ of the bridge analyzed, obtained
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30 throughout a small data set. Therefore, to extend the index Δ to the present case the
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32 quantity to estimate here is a “value”: precisely the foundation settlement $C_s(t)$ at a giv-
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34 en time t , assumed as a critical instant during the lifetime of the bridge.
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39 Settlement is assumed to vary according to a known polynomial law. Two par-
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41 ticular cases will be analyzed: the first one represents a stable settlement over time (con-
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43 solidation of clay soil) while the second one represents a sinking increasing over time
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45 (unstable slope). Figure 4a shows the considered settlement trends over time.
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48 These two different trends are very similar to each other within the first 20
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50 years. However, these different models, each of them with different evolution laws, can
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52 provide results much similar in value over the first 20 years, but if a long term predic-
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54 tion must be conducted, different and potentially incorrect results might be attained by
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56 each single law used.
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3 In the following, considering two evolution laws (r and s), the method validity
4 and the bridge performance are investigated. In Figure 4b, two different parabolic laws
5 are assumed to be representative of these models. Referring to a short-term, the r -model
6 is closer to a soil stable behavior, while the s -model simulates an unstable behavior
7 (Figure 4b).
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16 [FIGURE 4 – HERE]
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21 To assess the influence of the settlement on the bearing capacity of the bridge
22 non-linear analyses were developed using ADINA software. For the assessment of the
23 collapse multiplier λ_p , a numerical model with beam elements was developed on the ba-
24 sis of the geometrical characteristics showed in Figure 3. The bridge deck and the arch
25 were modeled using beam elements, whereas the columns were modeled with truss ele-
26 ments. Material nonlinearity was introduced in beam elements through an appropriate
27 moment-curvature relationship (Ballard and Sedarat 1999; Jones et al. 2004, Garavaglia
28 et al. 2013). For each different section of beam elements (considering both the geometry
29 and the reinforcement, like reported in Table 1) the authors assessed bending moment-
30 curvature relationships for different values N of the axial force. This evaluation was per-
31 formed using a home-made computer code able to perform sectional analysis of rein-
32 forced concrete sections. The relationships obtained were subsequently simplified into a
33 tri-linear elastic perfectly plastic models and included into the numerical model of the
34 bridge. Figure 5b shows the beam bending moment-curvature curves for different values
35 N of axial force on the arch section.
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56 [FIGURE 5 – HERE]
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5 On the bridge, three loads were considered: g represents the dead load, p the ser-
6 vice load (road traffic) and C the assumed settlement. Using non-linear analyses the col-
7 lapse load multiplier of the service load λ_p was assessed. Briefly, defined the value of
8 the settlement to the base of the arch, the bridge's model was loaded with its dead load
9 (g) and with the settlement load (C). At the end of these steps the service load was in-
10 troduced and increased up to the collapse of the bridge.
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18 Figure 6 shows the static model of the bridge (Fig. 6a) and the outcomes of one
19 of nonlinear analyses made (Fig. 6b). In the case shown in figure, the analysis stops
20 with a $\lambda_p = 1.9831$, the collapse of the bridge due to a load equal to 1.9831 times the
21 normal service load of the bridge. In Figure 6b are even marked the zones in which the
22 sectional behavior went beyond the linear elastic field. Repeating the structural analysis
23 for different settlement values, the influence of the settlement load on the bearing capac-
24 ity of the bridge was obtained. This information is summarized in Figure 6c. If the
25 foundation settlement is not present, λ_p is about 2.1 times the service load with a settle-
26 ment of about 0.33 m the bridge is not able to sustain the service traffic load. Since the
27 collapse multiplier is evaluated on the service loads, the authors assume a $\lambda_p = 1.5$ as a
28 safety threshold, that correspond to a settlement of 0.24 m.
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45 [FIGURE 6 – HERE]
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47 Assuming the value of the settlement C is known by monitoring, the abovementioned
48 methodology is applied to the index Δ evaluation for predicting the credibility of
49 the collapse load multiplier λ_p of the bridge over time as consequence of the time-
50 dependent foundation settlement.
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First results

To test the procedure for the settlement of the bridge foundations in Figure 3 it was supposed that five measurements were available, and that they were made between the fifth and tenth year of its life (see also Figure 7). Starting from this monitoring campaign, the evolution of the settlement C follows the discrete trend shown in Figure 4a. This information may be ambiguous: the law evolution of C can be stable or unstable. Basing on pure statistical fitting of experimental data, an error could affect C prediction at a given time. Extending the monitoring time and supporting the few available experimental data with a thorough knowledge of the physical phenomenon reduces the uncertainty and enables to quantify the error. The knowledge on foundation settlement suggests different evolution laws for C , and here two of them have been investigated as possible behavior of the bridge foundation settlement (Figure 4b). Since two possible behaviors are admitted, the credibility index Δ_{rs} can be very useful for the decision-making process.

Hypothesis: the evolution law of C is stable (Figure 4a)

The procedure introduced in the previous sections is here applied on a soil with stable behavior.

Firstly considering path r (Figure 4b) as the *true* evolution law of C (see table in Figure 4) and using a Monte Carlo simulation, combined with a random drawing procedure, 1000 samples of size $v = 5$ were drawn (each sample consists in 5 values of \hat{C}_r , as the size of the monitoring dataset). In this first application, the distribution function used in the random drawing procedure was a uniform distribution function. The samples are drawn over 10 years and they can be considered a *conjectural reality*. Assuming

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3 $h = [0.05 \cdot C^\circ]$, Eq. (1) evaluates index Δ_r° for each year between the tenth and the twen-
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6 tieth.

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8 Afterwards considering path s as the *true* evolution law of C , the same procedure
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10 was applied and each value \hat{C}_s between the tenth and the twentieth year was estimated
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12 for each sample drawn, so as the index Δ_s° (with $h = [0.05 \cdot C^\circ]$).

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16 Eq. (4) provided the value and the sign of Δ_{rs}° . The results obtained are shown
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18 in Table 2.

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22 [TABLE 2 – HERE]
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28 The positive sign of Δ_{rs}° shown in Table 2 suggests that the r – model is the
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30 most reliable in the modeling of a *true* stable behavior. The last three columns of the ta-
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32 ble show the assessed values λ° , λ_r and λ_s of collapse multipliers for the “true” model
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34 r – model and s – model respectively. Note that for the next decade after the monitoring,
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36 both models (r and s) give a good answer: the prediction model based on law r is just a
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38 10% better than the prediction model based on law s . Fifty years after the monitoring
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40 activity, comparing the behavior predicted by s –law with the actual behavior of the soil,
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42 the s – model becomes unreliable. While the r – model can predict the collapse multipli-
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44 er with an error of about 5%, the forecast based on s – model is completely wrong (s –
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46 model predicts a collapse of the bridge, while the actual collapse load multiplier remains
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48 1.83).
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3 ***Hypothesis: the evolution law of C is unstable (Figure 4b)***
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5 For a soil with unstable behavior, the above described procedure is repeated and the re-
6 sults are shown in Table 3.
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11 [TABLE 3 – HERE]
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16 The negative sign of Δ_{rs}° points out the unreliability of the prediction law r
17 which models the soil behavior. Over the next decade after the monitoring, the predic-
18 tion laws r and s provide the same results. After fifty years, the unstable behavior of the
19 soil causes the collapse of the bridge (the service loads multiplier at collapse results to
20 be equal or less than zero). An analysis based on the prediction law r wrongly shows
21 that the bridge is still safe, while the winning in credibility prediction s – model rightly
22 predicts the non-safety of the structure. The index Δ_{rs}° shows a great effectiveness in
23 catching the true behavior of the parameter investigated.
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37 ***Real situation: the evolution law of C is unknown***
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40 In common practice, the evolution law F_C° of C° is unknown; therefore, F_C^* , \hat{C}^* and Δ_{rs}^*
41 must be experimentally *evaluated* through a given procedure, $\Delta_{rs}^* = E_{rs}(F_C^*)$ (E_{rs} is the
42 procedure chosen). Figures 7a-b points out the difficulty in choosing the most reliable
43 interpretation model of the foundation settlement in the portion analyzed.
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50 Selecting a discrete polyline law F_C^* , the small data set can be modeled (Fig. 7a).
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52 Since the monitoring is time-limited, sometimes a simple linear regression may be suf-
53 ficient to fit the experimental data. If no other information is available, this tendency
54 could describe the evolution of parameter C , even if it's a strong simplification. Howev-
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er, here the linear regression is assumed and the tendency of the law has been investigated both over a 20-year and a 50-year period (Fig. 7b).

[FIGURE 7 – HERE]

If the simple regression law is assumed as evolution law, the regression branch at 50 year should lead to the value $\hat{C}^*(50)=0.249$ m. Using both the r – model and s – model the small monitoring dataset has been modeled and indexes Δ_r^* and Δ_s^* have been evaluated. The results obtained are shown in Table 4.

These results show the difficulty in interpreting the phenomenon investigated when a short term monitoring has been carried out.

The index Δ_{rs}^* at 10th year is close to zero therefore the models reliability is quite the same. The index Δ_{rs}^* at 20th year results positive; therefore, over a 50 years period, the r – model is the most reliable and it results in $\hat{C}_r^*(50)=0.144517$ m (Tab. 4). Nevertheless, considering 50th year the tendency changes: an index value $\Delta_{rs}^* < 0$ means that actually the s – model is the most reliable model over a 50 years period and it results in $\hat{C}_s^*(50)=0.339625$ m (Tab 4).

Thus a wrong choice can lead up to underestimation or overestimation of \hat{C}^* value (50) with significant consequences for maintenance and rehabilitation.

[TABLE 4 – HERE]

Figure 7a-b point out the mutual reliance between monitoring and reliability of the choice: longer the monitoring, higher the reliability of the choice. Therefore, a rea-

sonably regular monitoring distributed over a time range between 10th and 30th year of the structural service life could suggest the behavior law of foundation settlement when it's uncertain.

Some remarks

By the first results here obtained it's noticeable that:

- (1) When only a limited amount of monitoring data is available, there is a high risk of a wrong prediction of the evolution law of a given quantity that could influence the erroneous prediction of safety and or collapse of our structural systems.
- (2) When the law describing a certain phenomenon is unknown, the credibility index provides valuable information on the correctness of the modeling process applied on data collected.
- (3) The positive or negative value of Δ concurs in defining the process correctness. Furthermore it is necessary to consider the time Δ takes to reach 0: faster it reaches 0, smaller the reliability of both the processes is. Table 2 and 3 explain it.
- (4) In both the cases studied, the index Δ enabled support the decision concerning the most reliable model to use in the prediction on the possible evolution law over time for the arch bridge investigated.

Conclusions

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3 The structural behavior of a civil structure may differ from the expected one due to un-
4 foreseen environmental attacks; therefore an effective structural monitoring is neces-
5 sary. The use of monitoring can help to enable the control of structural behavior and the
6 residual life prediction of the structure. Thus, effective maintenance can be scheduled.
7 Since monitoring data are usually affected by uncertainty and sometime, for different
8 reasons, they are gathered over a short period of time, the knowledge of the physical
9 phenomenon modeled must be deepened in a statistical or probabilistic way. Further-
10 more, the small size of available monitoring datasets could become a critical issue be-
11 cause of it can compromise the modeling of structural quantities over time and the pre-
12 diction of its development over time.
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25 In this paper an index has been introduced in order to identify between two plau-
26 sible models, which is the most reliable to describe the evolution of phenomenon or
27 quantity investigated. Basing on the credibility index, Δ , introduced by Grandori et al.
28 (1998, 2003) for representing a probabilistic model in evaluating a static hazard quanti-
29 ty, the same index has been proposed as a possible credibility index to define the most
30 suitable model in the modeling of the evolution law of a given structural quantity.
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38 Following Grandori's approach the method is applied to a real case-study. This
39 procedure has good effectiveness in identifying the most reliable evolution law for the
40 settlement C of an arch bridge. Considering few monitoring dataset describing the phys-
41 ical phenomenon, the methodology developed appears to be suitable.
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47 The procedure proposed, through the evaluation of the evolution of the founda-
48 tion settlement C has shown how a wrong modeling of a given quantity can lead to a
49 wrong estimation of the structural response with dangerous consequence. In fact, a
50 wrong modeling of C can lead to a wrong estimation of the λ loads multiplier with a
51 possible overestimation of the bridge bearing capability. It has shown like the procedure
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proposed is able to give information also on the error made in the estimation of a given quantity C in presence of few data and an unknown evolution law.

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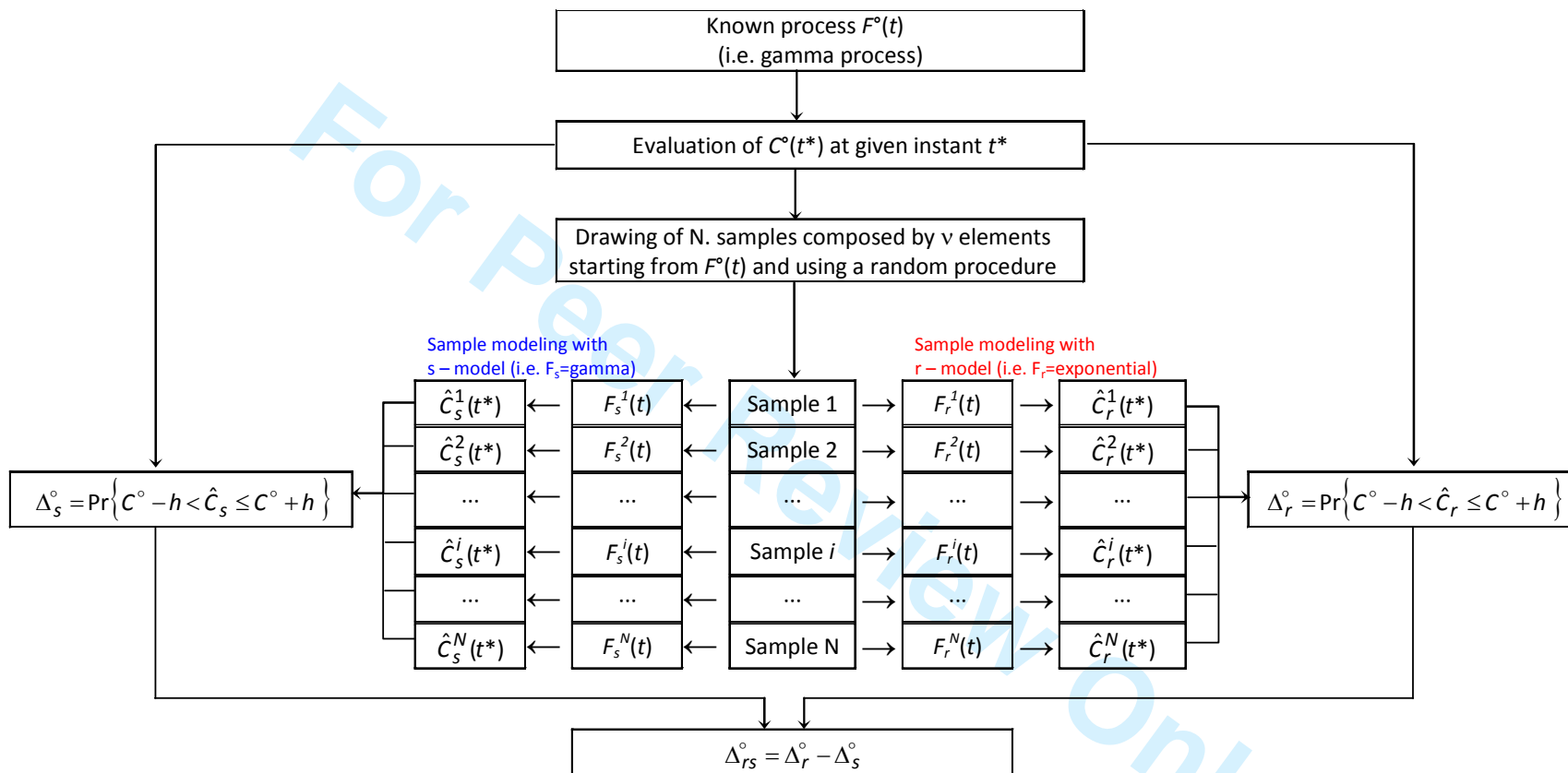


Figure 1. Credibility index: flowchart of the process.

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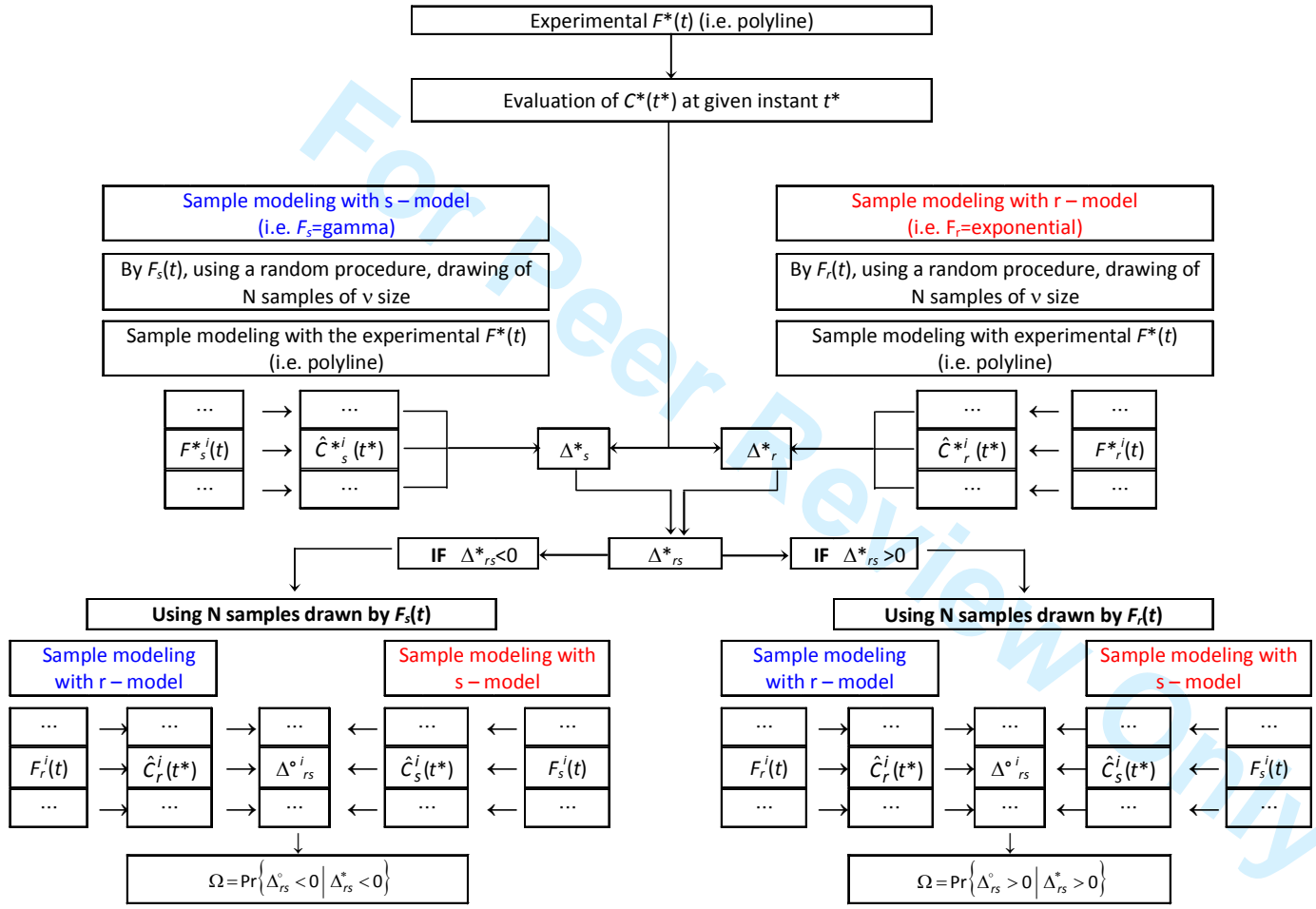


Figure 2. Flow chart showing the evaluation process of the posterior probability of hypothesis.

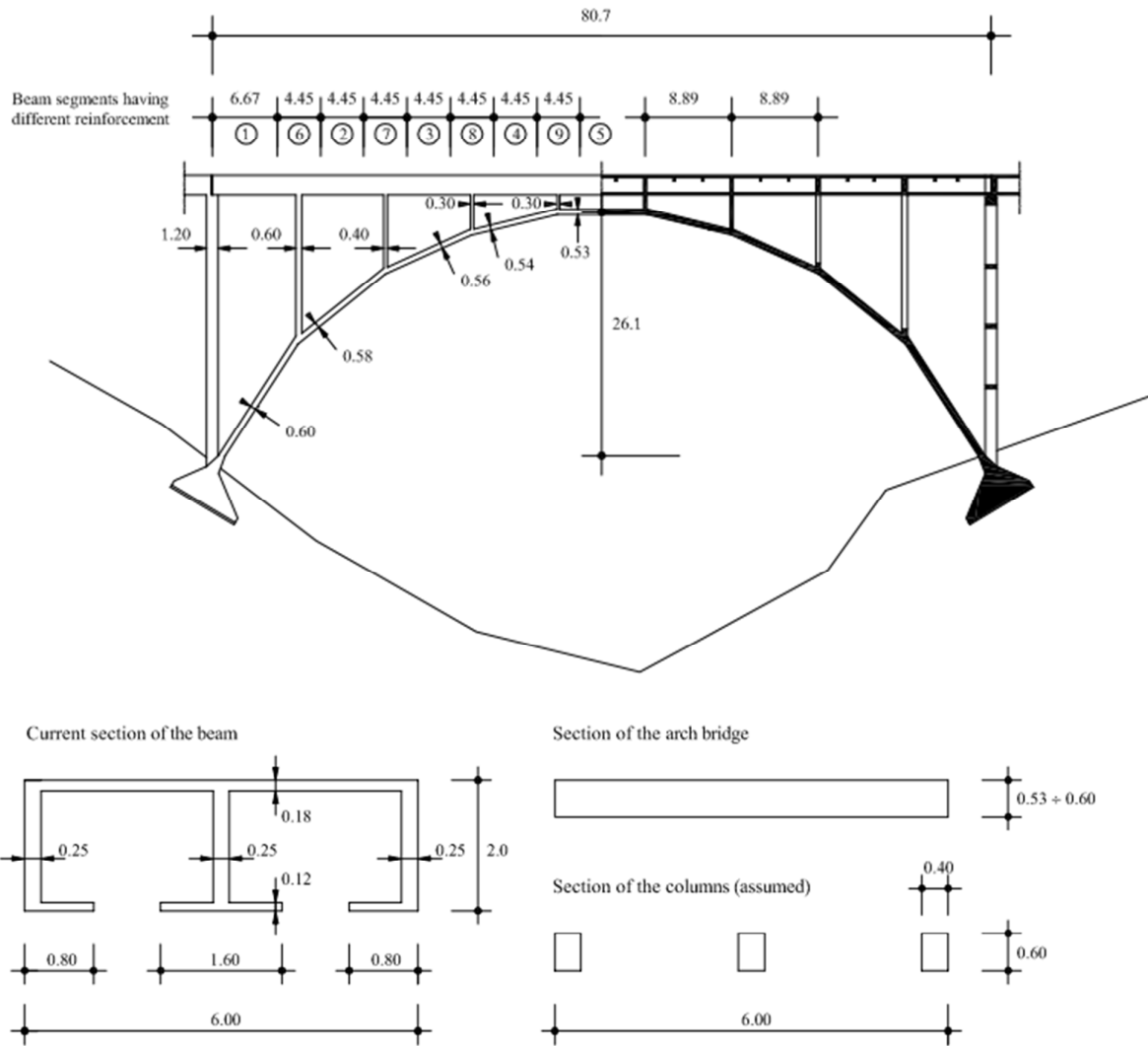
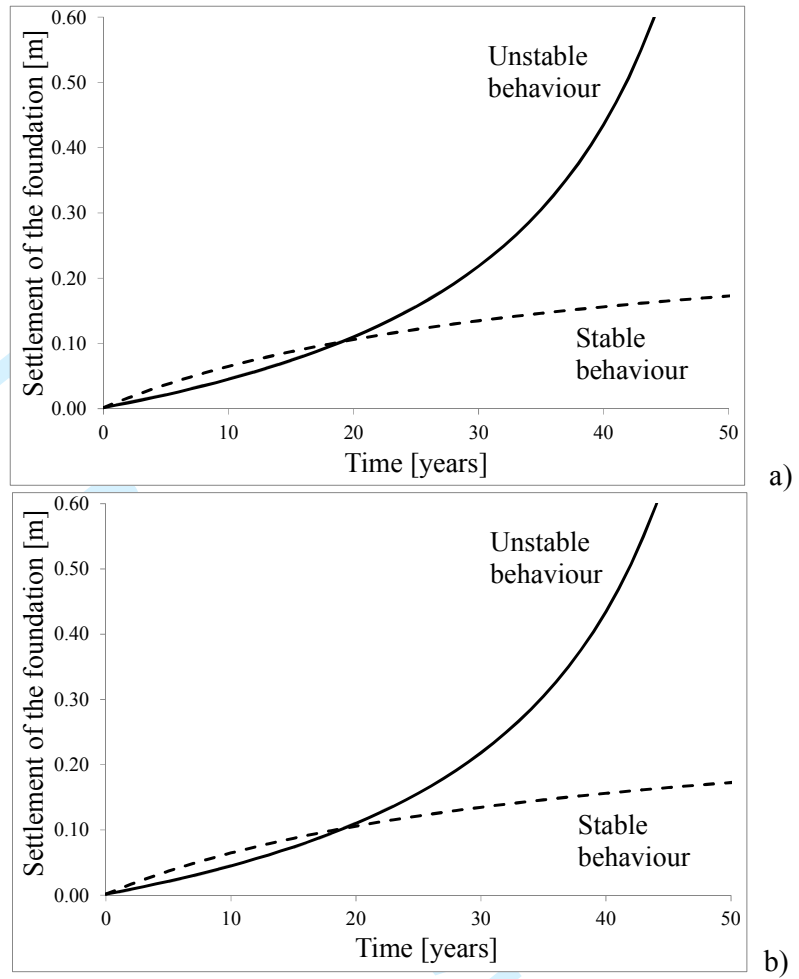


Figure 3. Overall dimensions of the arch bridge and detail of the current section of the beam, of the arch bridge and of the columns (measures expressed in meter).

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Settlement and prediction functions	
Stable behaviour	$C(t) = \frac{1}{3} - \frac{1}{3+t}$
Unstable behaviour	$C(t) = \frac{13}{60-t} - \frac{13}{60}$
Prediction laws	$C(t) = a \cdot t^2 + b \cdot t$

Figure 4. Evolution laws (a) assumed to describe the foundation settlement over time and prediction laws (b). The model parameters (*a* and *b*) are estimated during the prediction phase with a least-squares procedure.

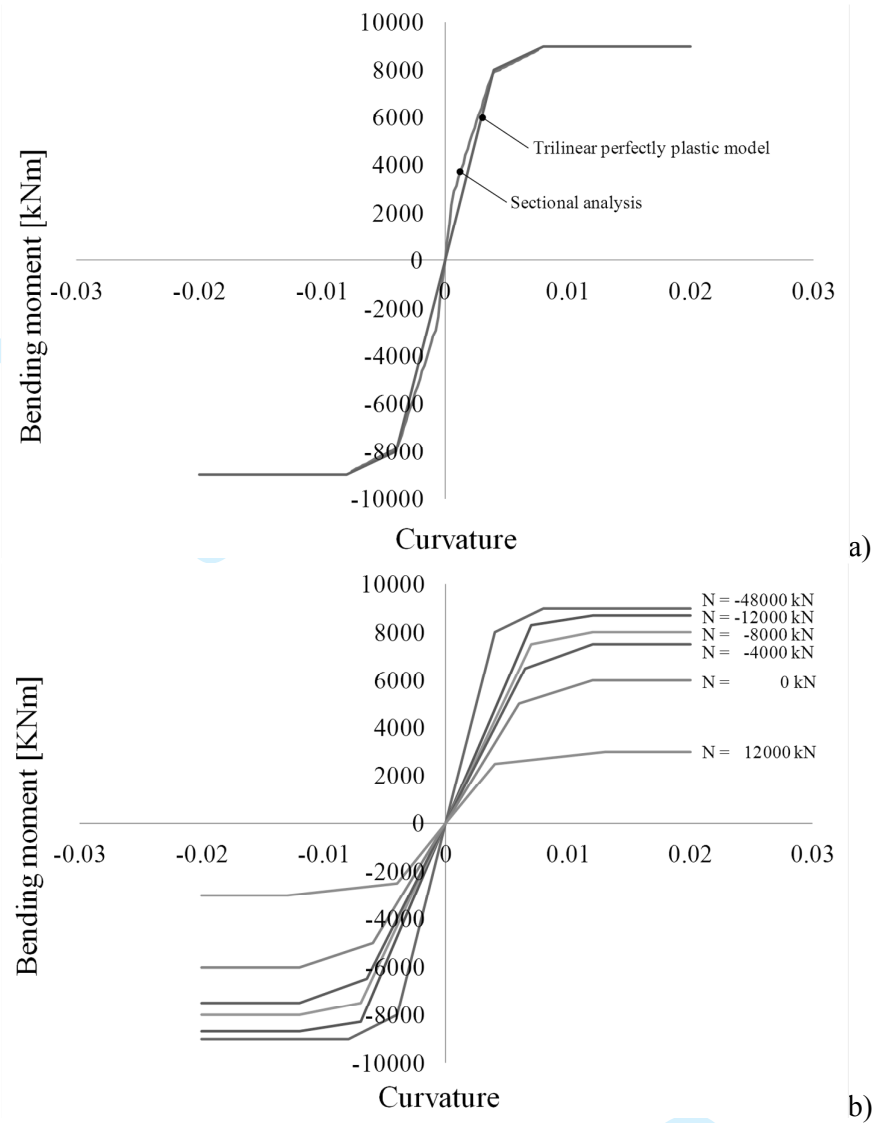
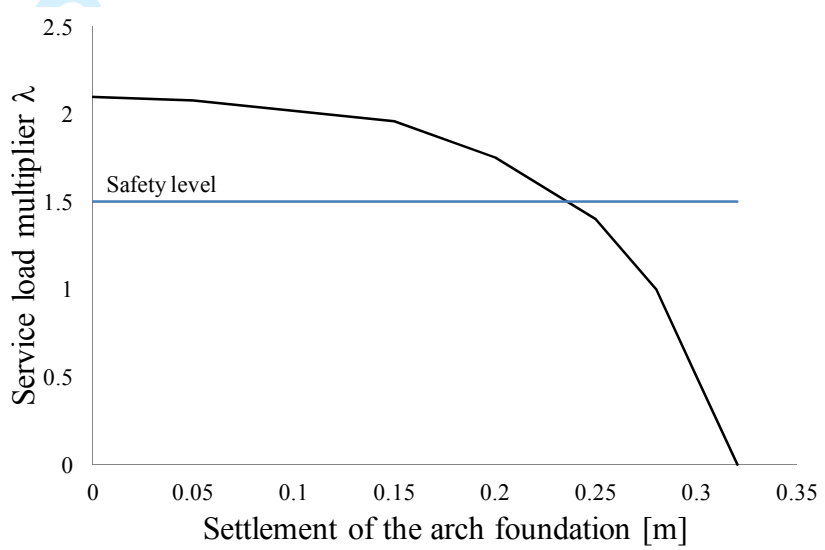
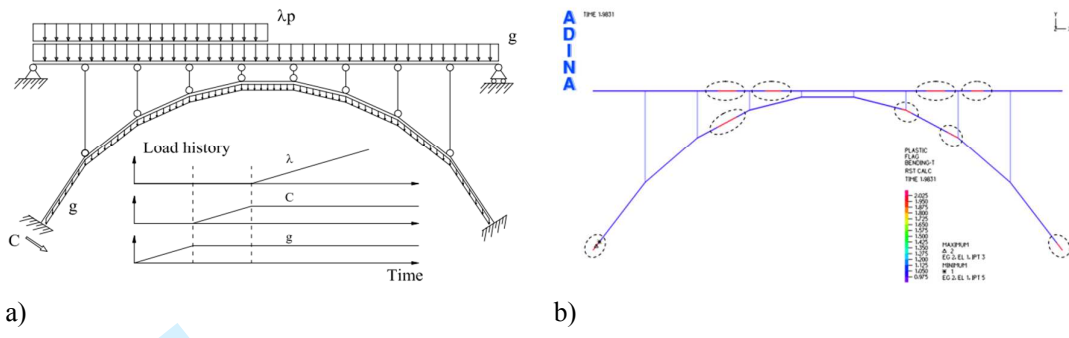
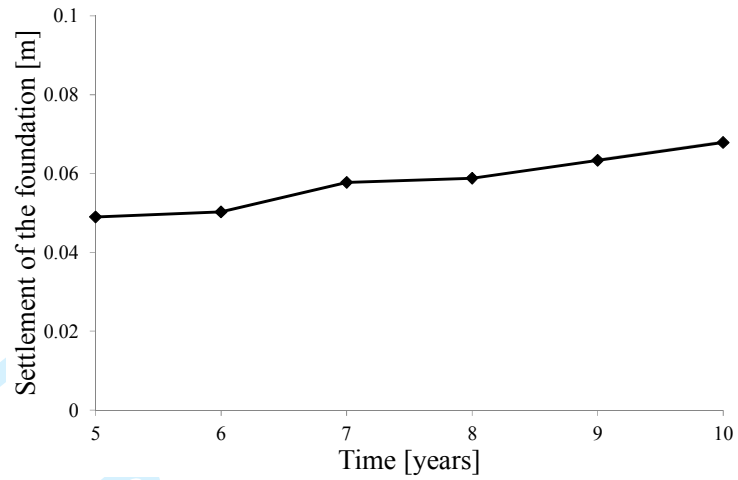


Figure 5. a) Bending moment-curvature for the arch section assessed with sectional analysis and tri-linear perfectly plastic simplification; b) series of bending moment-curvature curves for the arch section with different axial force (N).

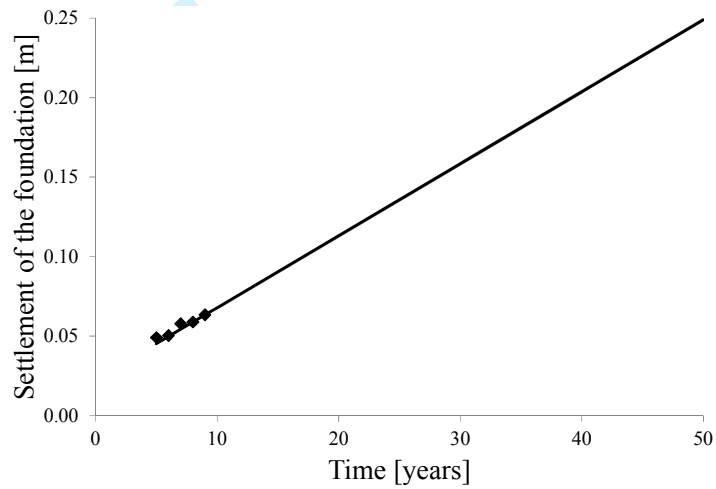
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c) Figure 6. a) Load model of the bridge. The collapse load multiplier λ_p is 1.9831 (on the top-left in the figure). b) Outcomes of the nonlinear analysis performed. The figure shows the plasticized zones of the structure. c) Variation of the collapse load multiplier over settlement.



a)



b)

Figure 7. Case-study: small data set, a) polyline describing the tendency; b) simple linear regression of data describing the tendency over time.

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Distribution at the top A'_s and at the bottom A_s reinforcement along the beam									
Section	1	2	3	4	5	6	7	8	9
A'_s	21Φ28	48Φ28	42Φ28	30Φ28	24Φ28	48Φ28	48Φ28	45Φ28	33Φ28
	130Φ8	130Φ8	130Φ8	130Φ8	130Φ8	130Φ8	130Φ8	130Φ8	130Φ8
A_s	21Φ28	30Φ28	42Φ28	24Φ28	24Φ28	21Φ28	36Φ28	27Φ28	24Φ28
Reinforcement along the arch bridge: 45 (on the top) + 45Φ28 (on the bottom of the section)									
Reinforcement along the columns: 3 x 8Φ18 (assumed, each column in the 2D numerical model represents 3 columns of the bridge).									

Table 1. Distribution of the steel reinforcement in the beam, in the arch and in the columns (the upper, A'_s , and downer, A_s , steel areas are expressed in number of steel bars per diameter).

<i>Time of monitoring</i>	Δ_r°	Δ_s°	Δ_{rs}°	λ°	λ_r	λ_s
11 years	1.00	1.00	0.00	2.05	2.05	2.05
12 years	1.00	0.98	0.02	2.05	2.04	2.02
13 years	0.99	0.89	0.11	2.04	2.04	1.99
14 years	0.97	0.59	0.39	2.04	2.03	1.96
15 years	0.92	0.23	0.69	2.03	2.03	1.93
16 years	0.74	0.03	0.71	2.03	2.02	1.90
17 years	0.66	0.00	0.65	2.02	2.02	1.87
18 years	0.60	0.00	0.60	2.02	2.01	1.84
19 years	0.53	0.00	0.53	2.01	2.01	1.81
20 years	0.49	0.00	0.49	2.01	2.01	1.78
60 years	---	---	---	1.83	1.97	< 0

Table 2. *Credibility evaluation: true law F_C° representative of a stable settlement, prediction model r = stable behavior, prediction model s = unstable behavior.*

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<i>Time of monitoring</i>	Δ_r°	Δ_s°	Δ_{rs}°	λ°	λ_r	λ_s
11 years	0.99	1.00	-0.01	2.03	2.08	2.09
12 years	0.98	1.00	-0.02	2.03	2.07	2.09
13 years	0.96	1.00	-0.03	2.02	2.07	2.09
14 years	0.94	0.99	-0.05	2.02	2.06	2.08
15 years	0.90	0.99	-0.09	2.02	2.06	2.08
16 years	0.81	0.97	-0.16	2.02	2.05	2.08
17 years	0.50	0.84	-0.35	2.01	2.04	2.08
18 years	0.10	0.74	-0.64	2.01	2.04	2.08
19 years	0.00	0.68	-0.68	2.01	2.03	2.07
20 years	0.00	0.63	-0.63	2.00	2.03	2.07
60 years	---	---	---	< 0	1.12	< 0

Table 3. *Credibility evaluation: true law F_C° representative of an unstable settlement, prediction model r = stable behavior, prediction model s = unstable behavior.*

<i>Time of monitoring</i>	Δ_r^*	Δ_s^*	Δ_{rs}^*	$\hat{C}^*(t)$	$\hat{C}_r^*(t)$	$\hat{C}_s^*(t)$
10 years	0.998	0.999	-0.002	0.068	0.065	0.067
20 years	0.998	0.977	0.021	0.113	0.112	0.136
30 years	0.979	0.955	0.024	0.158	0.137	0.204
50 years	0.896	0.909	-0.014	0.249	0.144	0.339

Table 4. Real situation: the evolution law F_C^* is unknown and assumed to be a linear regression of the monitoring data *prediction model* $r =$ stable behavior, *prediction model* $s =$ unstable behavior.