

1 **Title:** Evaluation of 4D Flow MRI-based non-invasive pressure assessment in aortic coarctations

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24

25 **Abstract**

26 Severity of aortic coarctation (CoA) is currently assessed by estimating trans-coarctation pressure drops
27 through cardiac catheterization or echocardiography. In principle, more detailed information could be
28 obtained non-invasively based on space- and time-resolved magnetic resonance imaging (4D flow) data.
29 Yet the limitations of this imaging technique require testing the accuracy of 4D flow-derived hemodynamic
30 quantities against other methodologies.

31 With the objective of assessing the feasibility and accuracy of this non-invasive method to support the
32 clinical diagnosis of CoA, we developed an algorithm (4DF-FEPPE) to obtain relative pressure distributions
33 from 4D flow data by solving the Poisson pressure equation. 4DF-FEPPE was tested against results from a
34 patient-specific fluid-structure interaction (FSI) simulation, whose patient-specific boundary conditions
35 were prescribed based on 4D flow data. Since numerical simulations provide noise-free pressure fields on
36 fine spatial and temporal scales, our analysis allowed to assess the uncertainties related to 4D flow noise
37 and limited resolution.

38 4DF-FEPPE and FSI results were compared on a series of cross-sections along the aorta. Bland-Altman
39 analysis revealed very good agreement between the two methodologies in terms of instantaneous data
40 at peak systole, end-diastole and time-averaged values: biases (means of differences) were +0.4 mmHg, -
41 1.1 mmHg and +0.6 mmHg, respectively. Limits of agreement (2 SD) were ± 0.978 mmHg, ± 1.06 mmHg and
42 ± 1.97 mmHg, respectively. Peak-to-peak and maximum trans-coarctation pressure drops obtained with
43 4DF-FEPPE differed from FSI results by 0.75 mmHg and -1.34 mmHg respectively. The present study
44 considers important validation aspects of non-invasive pressure difference estimation based on 4D flow
45 MRI, showing the potential of this technology to be more broadly applied to the clinical practice.

46 **Keywords:** Aortic coarctation, 4D flow MRI, Pressure Poisson equation, Non-invasive pressure difference
47 estimation, Fluid dynamics.

48 1. Introduction

49 In aortic coarctation (CoA), the narrowed aortic lumen represents an abnormal impedance to flow which
50 increases the afterload on the left ventricle, resulting in high blood pressure in the upper part of the body
51 and often ventricular hypertrophy, degenerative alterations in the proximal aorta and systemic
52 hypertension (LaDisa et al., 2011; Lantz et al., 2013). CoA severity is assessed based on the trans-
53 coarctation pressure difference: the American College of Cardiology guidelines (Warnes et al., 2008)
54 recommend intervention for CoA repair if the peak-to-peak coarctation pressure difference measured by
55 cardiac catheterization exceeds 20 mmHg. Despite being considered a clinical gold standard,
56 catheterization is an invasive procedure and European ESC guidelines recommend the non-invasive
57 evaluation of CoA severity using imaging techniques (Baumgartner et al., 2010). Among these, the most
58 commonly used is Doppler echocardiography, which enables to estimate pressure drops using the
59 simplified Bernoulli equation (Donati et al., 2017). More recently, 4D phase-contrast magnetic resonance
60 imaging (4D PC-MRI or 4D flow) was proposed as an alternative to catheterization and Doppler. 4D flow
61 allows for measurement of *in vivo* blood flow, providing three-directional velocity fields in a volume of
62 interest throughout the cardiac cycle (Markl et al., 2016). An increasing number of studies have assessed
63 the reliability of various 4D flow-derived hemodynamic markers that could support the diagnosis and
64 prognosis of cardiovascular diseases and the timing of intervention (Ha et al., 2016, 2017; Piatti et al.,
65 2017). For instance, flow distribution quantification has been shown to yield predictive information on
66 cerebral ischemia (Bagan et al., 2006), and vortices assessment in pulmonary arteries has been applied to
67 pulmonary hypertension diagnosis (Reiter et al., 2014). Intravascular pressure fields can be derived from
68 4D flow-based velocity fields through numerical methods that yield the approximate solution of the
69 Navier-Stokes equations. Among the main proposed numerical formulations (Bertoglio et al., 2018), the
70 solution of the pressure Poisson equation (PPE) has shown robustness and ease of implementation
71 (Krittian et al., 2012). Nonetheless, 4D flow measurements are affected by noise-like phase errors arising

72 from tissue motion, and are limited by low spatial and temporal resolutions and partial volume effects,
73 which hamper the quantification of parameters, including pressure drops, that require computing velocity
74 space- or time-derivatives (Ha et al., 2016; Ong et al., 2015). These sources of uncertainty question the
75 reliability of such estimations in the real clinical setting and make it necessary to validate 4D flow-derived
76 results against pressures obtained through other well-controlled methodologies. Bock et al. (2011) used
77 *in vitro* experiments on stenosis phantoms to compare MR-derived pressure drops with the established
78 Doppler-based method. *In vitro* phantoms provide highly reproducible experimental conditions, but the
79 Bernoulli formula often leads to pressure drop overestimation (Itu et al., 2013) and Doppler ultrasound is
80 operator-dependent; hence, it represents a suboptimal term of comparison. Important work was
81 conducted by Riesenkampff et al. (2014) and Goubergrits et al. (2019) who compared *in vivo* trans-
82 coarctation pressure drops computed from 4D flow data by solving the PPE vs. direct cardiac
83 catheterization measurements, obtaining an overall good agreement. However, in Riesenkampff et al.
84 (2014) spatial uncertainties in pressure catheter locations or biases related to catheter-induced flow
85 alterations were present but not investigated. In Goubergrits et al. (2019), potential errors due to catheter
86 location were accounted for. Additionally, the authors provided new important evidence of how limited
87 4D flow spatial resolution affects pressure mapping. Still, catheter measurements can only give pressure
88 values at predefined locations along the aorta, hence preventing an exhaustive validation of the whole
89 distribution of 4D flow-based pressure drop data.

90 In order to overcome the aforementioned limitations, in the present study we compared the relative
91 pressure distribution obtained from 4D flow data acquired *in vivo* on a CoA patient to the highly space-
92 and time-resolved results of the corresponding patient-specific fluid-structure interaction (FSI) model.
93 This approach allowed to evaluate the accuracy of the method in terms of pressure distributions over
94 time, since for every 4D flow-derived datum an FSI datum at the same location was available. Moreover,

95 and in contrast with invasive measurements, pressures obtained through FSI were not affected by flow
96 disturbances potentially introduced by catheters.

97 Hence, the aim of this study was to assess the feasibility and accuracy of a non-invasive method based on
98 a finite element solution of the PPE (FE-PPE), through a comprehensive validation against a detailed
99 computational model, in the specific context of CoA.

100 2. Methods

101 2.1. Mathematical and Numerical Formulations

102 For a given velocity field, the corresponding pressure field (p) can be derived from the Navier-Stokes
103 equation, whose weak form can be obtained following the procedure described in (Krittian et al., 2012);
104 find $p \in H^1(\Omega)$ such that:

$$105 \quad \int_{\Omega} \nabla p \cdot \nabla q \, d\Omega = \int_{\Omega} \vec{b} \cdot \nabla q \, d\Omega, \quad \forall q \in H^1(\Omega). \quad (1)$$

106 Where q is a test function and Ω is the computational domain. The term \vec{b} is defined as:

$$107 \quad \vec{b} = -\rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} - g \right) + \mu \Delta \vec{v}, \quad (2)$$

108 where \vec{v} is velocity, ρ is density, g describes a distribution of external forces, and μ is dynamic viscosity.

109 Adopting a standard Galerkin finite element approximation, equation (1) can be expressed as a linear
110 system (Meier et al., 2010):

$$111 \quad Kp = \sum_{l=1,2,3} L^{x_l} b^{x_l}, \quad (3)$$

112 where K is the stiffness matrix and L^{x_l} is a non-symmetric matrix defined as:

$$113 \quad L_{i,j}^{x_l} := \int_{\Omega} N_i \frac{\partial N_j}{\partial x_l}, \quad l=1,2,3 \quad (4)$$

114 where N_i are the finite element shape functions (Meier et al., 2010). In contrast with (Krittian et al., 2012),
115 linear, instead of tricubic, Lagrangian shape functions were used to limit computational expense. Velocity

116 derivatives in equation (2) were calculated using finite difference schemes and the numerical framework
117 for the solution of the PPE was implemented in MATLAB (Mathworks, Natick, MA, USA). For a unique
118 solution of p a reference pressure must be defined at a certain (arbitrary) point: in the present study $p=0$
119 was imposed at the most distal point of the aorta for all time steps; therefore all pressure results obtained
120 from the algorithm (referred to as 4DF-FEPPE) are pressure differences with respect to this reference
121 point.

122 *2.2. Workflow*

123 4D flow MRI data acquired for a CoA patient were used to calculate pressures through the numerical
124 framework of 4DF-FEPPE and to prescribe boundary conditions for the FSI simulation (Figure 1). Upon
125 testing velocity field yielded by the FSI simulation vs. the raw 4D flow data, pressure data obtained through
126 4DF-FEPPE were evaluated against FSI pressure results.

127 *2.3. Data Acquisition and Geometry Reconstruction*

128 4D flow MRI and contrast-enhanced magnetic resonance angiographic (MRA) acquisitions for a 57-year-
129 old male patient with CoA were provided by the Multimodality Cardiac Imaging Section, IRCCS Policlinico
130 San Donato (San Donato Milanese, Milan, Italy). Using a Magnetom Aera 1.5T scanner (Siemens
131 Healthcare, Erlangen, Germany), *VENC* values were set to 150 cm/s for all directions and 21 time frames
132 were obtained over the cardiac cycle. Maximum velocity magnitude was observed to be equal to 253
133 cm/s. 4D flow isotropic in-plane resolution and slice thickness were set to 2.08 mm and 2.4 mm,
134 respectively. Temporal resolution was equal to 40 ms and echo time to 2.4 ms. MRA isotropic in-plane
135 resolution and slice thickness were set to 1.56 mm and 1.60 mm, respectively.

136 Using in-house MATLAB code, velocity fields were converted from the corresponding phase-contrast
137 images and 4D flow datasets were corrected for aliasing. The gold standard manual segmentation was
138 performed by an expert operator to extract the patient's 3D geometry. Segmentation was carried out in

139 itkSNAP from the MRA images using the brush tool. The segmented volume was exported as a *.stl* file and
140 smoothed in Meshmixer (Autodesk, San Rafael, CA, USA) using the software embedded shape-preserving
141 smoothing filter. In the smoothed model, coarctation cross-sectional area was equal to 0.84 cm², while
142 aortic inlet and outlet cross-sections were 10.6 cm² and 2.5 cm² wide, respectively. This volume (shown
143 in red in Figure 2a) was used for the FSI simulation (Figure 2b). The same *.stl* model was registered onto
144 the 4D flow volume and used as computational domain for 4DF-FEPPE. For this purpose, to avoid the
145 errors due to 4D flow measurements near the vessel boundaries, boundary voxels were excluded from
146 the 4DF-FEPPE computational domain by an inward extrusion of the *.stl* model equal to the voxel size.
147 This operation was done using Meshmixer 'Extrude' filter followed by the shape-preserving smoothing
148 filter.

149 *2.4. Patient-Specific FSI Simulation*

150 The patient's aortic geometry, previously segmented in itkSNAP from the MRA images (Figure 2a), was
151 imported in CRIMSON (Figuroa et al., 2006; www.crimson.software) and discretized into a mesh
152 consisting of ~4M tetrahedral elements using the software embedded meshing tools. Maximum element
153 size was set to 0.9 mm and an exponential growth ratio between adjacent layers close to the boundary
154 was chosen, with a minimum element size of 0.2 mm and a total thickness of 2 mm. Flow rate through a
155 cross-section in the ascending aorta was extracted from 4D flow data and imposed at the model inlet
156 using a parabolic velocity profile. A three-element Windkessel model (3E-WKM) was coupled to each
157 outlet, i.e., brachiocephalic trunk (BCT), left carotid artery (LCA), left subclavian artery (LSA) and
158 descending aorta (DAo), to account for the downstream hydraulic impedances (Figure 2b). 3E-WKM
159 parameters (Table 1) were calculated following the procedure described in (Pirola et al., 2017). Mean flow
160 rate values for each outlet were obtained from 4D flow data analysis, while mean pressures were assumed
161 equal to 80 mmHg for all outlets. Two consecutive cardiac cycles were simulated. A 5% or less change in
162 maximum velocity magnitude and outlet pressures was considered for assuming periodicity and the

163 second cycle was used for result analysis. Maximum convergence residuals and time step were set to 10^{-5}
 164 and 0.002 s, respectively. Blood was modelled as a Newtonian fluid with viscosity $\mu=4$ cP and density
 165 $\rho=1060$ kg/m³. The aortic wall was assumed 1 mm thick (Kim et al., 2009) and with a homogeneous, elastic
 166 and isotropic stress-strain behaviour (Young modulus $E=878$ kPa, Poisson ratio $\nu=0.5$). According to
 167 Moens-Korteweg equation (Cavalcante et al., 2011), these parameters correspond to a pulse wave
 168 velocity of approximately 5.25 m/s, which is in agreement with previous studies on CoA stiffness (Xu et
 169 al., 1997) and with the value used to tune the 3E-WKM parameters. Computations were performed on 24
 170 cores (Intel® Xeon® CPU E5-2640 v3 2.60 GHz).

171 **Table 1.** Windkessel parameter values used in the numerical simulation: proximal resistance (R_p),
 172 compliance (C) and distal resistance (R_d) for the brachiocephalic trunk (BCT), left carotid artery (LCA), left
 173 subclavian artery (LSA) and descending aorta (DAo).

Outlet	R_p [g·mm ⁻⁴ ·s ⁻¹]	C [mm ⁴ ·s ² ·g ⁻¹]	R_d [g·mm ⁻⁴ ·s ⁻¹]
BCT	0.0294	12.1872	0.1281
LCA	0.0872	1.2950	1.3955
LSA	0.0418	3.7653	0.4682
DAo	0.0203	10.0218	0.1583

174 3. Results

175 3.1. Quantification of Results

176 To quantify the agreement between FSI results and 4D flow raw data, outlet flow rates over time and
 177 velocity color maps were analyzed. Correlation coefficients were calculated to quantify similarity between
 178 flow rate curves. Relative root-mean-square errors (RRMSE) and 2D correlation coefficients (2DCC) were
 179 calculated between velocity maps determined by 4D flow and FSI to provide an average quantification of

180 their consistency. Then, to better assess spatial differences in velocity profiles, normalized grayscale
181 differences (NGD) were obtained for three cross-sections along the aorta.

182 To evaluate the agreement between 4DF-FEPPE and FSI pressure results throughout the aortic domain, a
183 Bland-Altman analysis was performed by taking into account a series of cross-sections along the aorta.
184 Finally, as most clinically relevant measures, trans-coarctation pressure drops calculated with 4DF-FEPPE
185 were compared to corresponding FSI data.

186 *3.2. FSI Model Verification vs. 4D Flow Raw Data*

187 Overall, a good match was found between time-dependent outlet flow rates obtained with FSI and 4D
188 flow data (Figure 3): the largest difference in time-averaged flow rate was 0.26 L/min (+20.6%) at the LSA.
189 In the LSA and in the BCT flow rate waveform were fully consistent with 4D flow data, whereas in the DAo
190 the FSI simulation results showed an underestimation of the peak flow rate by 1.43 L/min (-18.25%) and
191 a slower temporal decay, possibly due to an underestimation of the patient's true aortic wall stiffness.
192 Correlation coefficients between the flow rate curves were equal to 0.9746, 0.8786, 0.9846 and 0.9403
193 for the BCT, LCA, LSA and DAo, respectively.

194 Space distribution of velocity magnitude in the descending aorta on one sagittal (Figure 4a) and three
195 cross-sectional planes (P1, P2 and P3; Figure 4b, c) was compared at several time-points during systole
196 (T1, ..., T9). The high velocity jet created by the coarctation narrowing could be observed clearly at the
197 longitudinal plane (Figure 4a), but the flow jet in the simulation results lasted longer in time, covered a
198 larger volume of the descending aorta and showed a sharper high-velocity propagation front (time points
199 T6 and T8), which might be due to the Newtonian fluid modelling assumption. RRMSE (Sarrami-Foroushani
200 et al., 2015) and 2DCC (Table 2) confirmed the good agreement between simulation and 4D flow, with
201 values ranging from 0.168 to 0.364 and from 0.628 to 0.911 respectively. On P1 (Figure 4c), FSI results
202 showed a peak velocity region near the left side wall, in agreement with 4D flow data; at T5 and T9, the
203 FSI simulation captured secondary flow features that were not observed in 4D flow measurements.

204 Additionally, the high velocity profile obtained from the simulation appeared more flattened against the
 205 wall: phenomenon which could be better appreciated at T3 in the NGD images (Figure 4c). Similarly, on
 206 P2, complex secondary flows and more irregular high velocity profiles were resolved by the finer FSI grid,
 207 while they seemed to be averaged out by 4D flow lower resolution; differences in high velocity regions
 208 could possibly be due to small discrepancies in coarctation orifice shape. On P3, at T5 4D velocity contours
 209 showed a high velocity region that was not observed in the simulation results due to the aforementioned
 210 peak flow rate underestimation through the DAo. At T9, good agreement was found in terms of velocity
 211 profile.

212 **Table 2.** Normalized root mean square errors (RMSE) and 2D correlation coefficients (CC) between FSI
 213 and 4D flow velocity magnitude contours on the selected planes for the specified time points.

		Time-Points					
		T3		T5		T9	
		RMSE	2DCC	RMSE	2DCC	RMSE	2DCC
Cross-sectional Planes	P1	0.168	0.886	0.239	0.847	0.213	0.833
	P2	0.220	0.681	0.364	0.628	0.319	0.638
	P3	0.222	0.911	0.333	0.883	0.252	0.829

214 **3.3. Comparison between 4DF-FEPPE and FSI Pressure Fields**

215 On 19 different cross-sections along the aorta (Figure 5a), plane-averaged values of the pressure
 216 difference with respect to the DAo outlet were compared through a Bland-Altman analysis. Instantaneous
 217 values at peak systole and at end diastole, as well as time-averaged values, obtained with the two
 218 approaches were considered (Figure 5b, c, d). Biases (means of differences) were +0.4, +1.1 and +0.6
 219 mmHg for peak systolic, end-diastolic and time-averaged values, respectively. The corresponding limits of
 220 agreement (2 standard deviation of differences) were ± 0.978 mmHg, ± 1.97 mmHg and ± 1.06 mmHg,

221 respectively. For peak systole and time average pressures almost all data points lie in the 95% limit band,
222 which shows good agreement between the two methodologies along the whole aorta.

223 Trans-coarctation pressure difference curves over time obtained with 4DF-FEPPE were consistent with
224 simulation results (Figure 6a) throughout the cardiac cycle. Peak-to-peak (Δp_{pp}) and maximum (Δp_m)
225 pressure drops between two cross-sectional planes located immediately proximally and distally to the
226 coarctation were compared between the two approaches (Figure 6b, Table 3). Δp_{pp} corresponds to the
227 difference between pressure peaks over time, Δp_m is the maximum instantaneous pressure difference
228 over time.

229 **Table 3.** Maximum and peak-to-peak pressure drops (in mmHg) obtained from the FSI simulation and 4DF-
230 FEPPE.

	Δp_m	Δp_{pp}
FSI	22.43	16.85
4DF-FEPPE	21.09	17.6

231 Pressure difference contours were compared at three different time points in the cardiac cycle are
232 reported in Figure 6c, where simulation results are shown as pressure differences relative to the DAo.
233 Both 4D flow-derived pressure and FSI simulation results showed pressure distributions typically
234 observed in CoA patients, with a clear difference between regions proximal and distal to the narrowing.

235 4. Discussion

236 The present study represents an evaluation of pressure mapping from 4D flow MRI using a numerical
237 framework for the FE-PPE referred to as 4DF-FEPPE. Our methodology was applied to a specific case of
238 CoA, where pressure assessment is of diagnostic importance. Relatively low $VENC$ values of the 4D flow
239 acquisition were set pursuing an optimal trade-off between the need for capturing high velocity jets in
240 the coarctation region and improving the signal-to-noise ratio in 4D flow measurements at lower velocity

241 regions, including the post-coarctation region. Minor aliasing effects were associated to this setting and
242 were filtered out.

243 Given the limitations of 4D flow, and the uncertainties related to this technology, which must be carefully
244 addressed before its clinical application, we assessed the feasibility of our non-invasive pressure
245 estimation method by comparison with the pressures obtained with a specifically designed FSI simulation.
246 Unlike 4D flow, FSI simulations provide noise-free velocity and pressure fields on arbitrarily fine spatial
247 and temporal scales. Therefore, our analysis allowed to investigate the uncertainties related to 4D flow
248 noise and limited spatial and temporal resolutions.

249 Our approach differs from Riesenkampff et al. (2014) and Goubergrits et al. (2019) one, where the
250 reliability of MR-derived trans-coarctation pressure drops was investigated by a comparison with catheter
251 measurements. In both studies, the authors performed a Bland-Altman analysis on a cohort of patients,
252 whereas only one patient was included in our work. However, the nature of our comparison allowed to
253 perform a similar analysis by comparing pressures at different locations within the aorta. Riesenkampff et
254 al. reported limits of agreement of ± 9.6 mmHg and ± 9.7 mmHg for peak-systolic and end-diastolic
255 pressure differences respectively, around ten times greater than the ones obtained in our study (± 0.978
256 and ± 1.97 mmHg, respectively). Considering peak-to-peak trans-coarctation differences (Δp_{pp}),
257 Riesenkampff et al. (2014) found good agreement between 4D flow-based and direct measurements, with
258 discrepancies ranging from 0 to 5 mmHg, while Goubergrits et al. (2019) reported differences between 0
259 and 6.5 mmHg. In our study, a discrepancy in Δp_{pp} of 0.75 mmHg was obtained.

260 Goubergrits et al. (2019), Riesenkampff et al. (2014) and Bock et al. (2011) all mentioned the tendency of
261 the MR-based method to underestimate pressure with respect to catheters or echocardiography
262 respectively. Bock et al. (2011) reported MR-based peak pressure differences that underestimated
263 echocardiography by $60.1 \pm 17.8\%$. Nevertheless, the authors themselves argued that echocardiography
264 could have overestimated pressure differences. In our comparison with FSI results we did not observe this

265 bias, further suggesting an overestimation of Doppler-based methods and, possibly, of catheter
266 measurements as well (De Vecchi et al., 2014; Olesen et al., 2018). On the contrary, in our Bland-Altman
267 analysis 4D flow-based results had biases (mean of differences) of +0.4 mmHg and -1.1 mmHg at peak-
268 systole and end-diastole, respectively, consistently with the -0.6 mmHg and -0.3 mmHg values found by
269 Riesenkampff et al. (2014).

270 The validity of our approach relied on the accuracy of the FSI model, which was supported by the good
271 consistency between the flow field computed by FSI modelling and the raw 4D flow velocity data.

272 The flow rates for the three supra-aortic branches and DAo obtained *in silico* were in agreement with 4D
273 flow, with errors between time-averaged values of 3.94%, 11.6%, 20.6% and 0.838% for the BCT, LCA, LSA
274 and DAo respectively. In a recent validation study of CFD results with 4D flow, Biglino et al. (2015) reported
275 similar errors in mean flow rates, equal to 3.53%, 1.69%, 4.35% and 14.2%, respectively.

276 A potential limitation of our FSI model consisted in having imposed a non-patient-specific velocity profile,
277 which might also affect pressure drop results (Goubergrits et al., 2013). Nonetheless, recent studies
278 (Madhavan and Kemmerling, 2018; Pirola et al., 2018) have shown how, albeit modelling 3D inlet velocity
279 profiles is important for evaluating hemodynamics in the ascending aorta, differences in flow solutions
280 are negligible beyond two diameters distal to the inlet. For the patient analysed in the present study, the
281 distance along the centreline from the inlet to the site of the coarctation was found equal to 16.8 cm;
282 enough for the velocity profile to develop, given the inlet diameter of 3.7 cm. The comparison between
283 velocity color maps along the descending aorta further confirmed the accuracy of the FSI model, which
284 also captured late systolic secondary flow features that were not detected by 4D flow owing to its lower
285 spatial resolution. Also, RMSE between velocity magnitude color maps ranged from 16% to 36%; despite
286 the higher complexity of our fluid domain, these results are in agreement with a previous study focused
287 on the CFD vs. 4D flow comparison in a carotid artery (Sarrami-Foroushani et al., 2015), which reported
288 RRMSE values ranging from 10% to 20%.

289 No information about the patient's pressure at any location was available and a mean value of 80 mmHg
290 was used to set 3E-WKM parameters for all outlets. Albeit this was an inevitable modeling limitation, the
291 good agreement between FSI flow fields and 4D flow data confirmed the goodness of this assumption.
292 Finally, the worse matching of flow rate curves in the DAo could be due to an underestimation of the true
293 ascending aorta stiffness. A higher aortic compliance could have resulted in increased energy stored
294 proximal to the coarctation, leading to higher diastolic flow rate through the post-coarctation region
295 (DeGroff et al., 2003). Although it is in principle possible to estimate patient-specific vessel wall
296 mechanical properties from PC-MRI (Ou et al., 2008), a variety of methodologies have been proposed
297 (Wentland et al., 2014) and recent evidence suggests that different methods can give significantly
298 different results (Dyverfeldt et al., 2014). Given this uncertainty in estimating mechanical properties from
299 MRI, we used parameters taken from recent literature. Despite many researchers developed constitutive
300 models for the healthy aortic wall (Prendergast et al., 2003), there is great scarcity of studies reporting
301 parameters for vascular tissue in unrepaired CoA. The Young's modulus and thickness values used in the
302 present study were taken from (Kim et al. 2009), where they were obtained for an untreated case of CoA
303 with similar geometry. The chosen mechanical properties yielded a good match between FSI results and
304 raw 4D flow data in terms of flow distributions and velocity magnitude contours.

305 Calculating pressure from 4D flow using 4DF-FEPPE took approximately 4 minutes for a 21-frame dataset.
306 Future work will focus on 4D flow MRI pre-processing, including advanced noise reduction and clever
307 spatiotemporal upsampling techniques to improve extraction of *in vivo* hemodynamic features. Current
308 efforts are aimed at the application of the developed method on a larger patient cohort, in order to test
309 its robustness as a non-invasive diagnostic tool.

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314 **Conflict of interest statement**

315 The authors declare that there is no conflict of interest regarding the content of this article.

316 **Appendix A – Mesh Sensitivity Analysis**

317 A mesh sensitivity analysis was performed by running steady flow simulations in CRIMSON using meshes
318 consisting of ~1.4, ~2.4 and ~4 million tetrahedral elements. A steady flow rate corresponding to systolic
319 peak was imposed at the inlet, while zero pressure was set for all outlets. Similar velocity patterns were
320 captured by all three meshes, but different maximum values of velocity magnitude within the narrowing
321 were computed with the different grids. To choose the best suited mesh, the maximum velocity
322 magnitude value on a cross-section within the coarctation was chosen as parameter of grid convergence.
323 Then, the Grid Convergence Index (GCI) (Roache, 1998) was calculated for the fine-to-medium and
324 medium-to-coarse grid refinements as described in (Craven et al., 2009). The *GCI* is a measure of how
325 much the variable of interest (trans-coarctation maximum velocity magnitude) is different from the
326 asymptotic numerical value; it indicates how much the calculated variable of interest
327 would change with a further grid refinement (Craven et al., 2009; Sakri et al., 2016). Let the subscripts 1,
328 2, 3 indicate the fine, medium and coarse meshes respectively:

$$329 \quad r \approx \left(\frac{N_1}{N_2}\right)^{1/3} \approx \left(\frac{N_2}{N_3}\right)^{1/3}, \quad (\text{A1})$$

$$330 \quad p = \frac{\log\left(\frac{f_3-f_2}{f_2-f_1}\right)}{\log r}, \quad (\text{A2})$$

$$331 \quad E_1 = \frac{f_2-f_1}{r^{p-1}}, \quad E_2 = \frac{f_3-f_2}{r^{p-1}}, \quad (\text{A3, A4})$$

332
$$GCI_{1,2} = F_s \cdot |E_1|, \quad GCI_{2,3} = F_s \cdot |E_2|, \quad (A5, A6)$$

333 where N is the number of elements, f is the parameter of interest and F_s is the “factor of
334 safety” equal to 1.25 (Craven et al., 2009). In particular, $f_1 = 1:871$ m/s, $f_2 = 1:849$ m/s and $f_3 = 1:8209$
335 m/s were found. The mesh sensitivity analysis revealed that the solution computed by
336 the fine was relatively insensitive to further mesh refinement, and the grid
337 chosen herein was the fine one, corresponding to a grid $GCI_{1,2}$ of approximately 3.4%,
338 which is in agreement with GCI s reported in recent studies (Craven et al., 2009; Tedaldi et al., 2018).
339 Additionally, to ensure that grids were in the asymptotic range of convergence the ratio:

340
$$k = \frac{GCI_{2,3}}{r^p \cdot GCI_{1,2}}, \quad (A7)$$

341 was calculated, and the relation $k \approx 1$ was satisfied.

342

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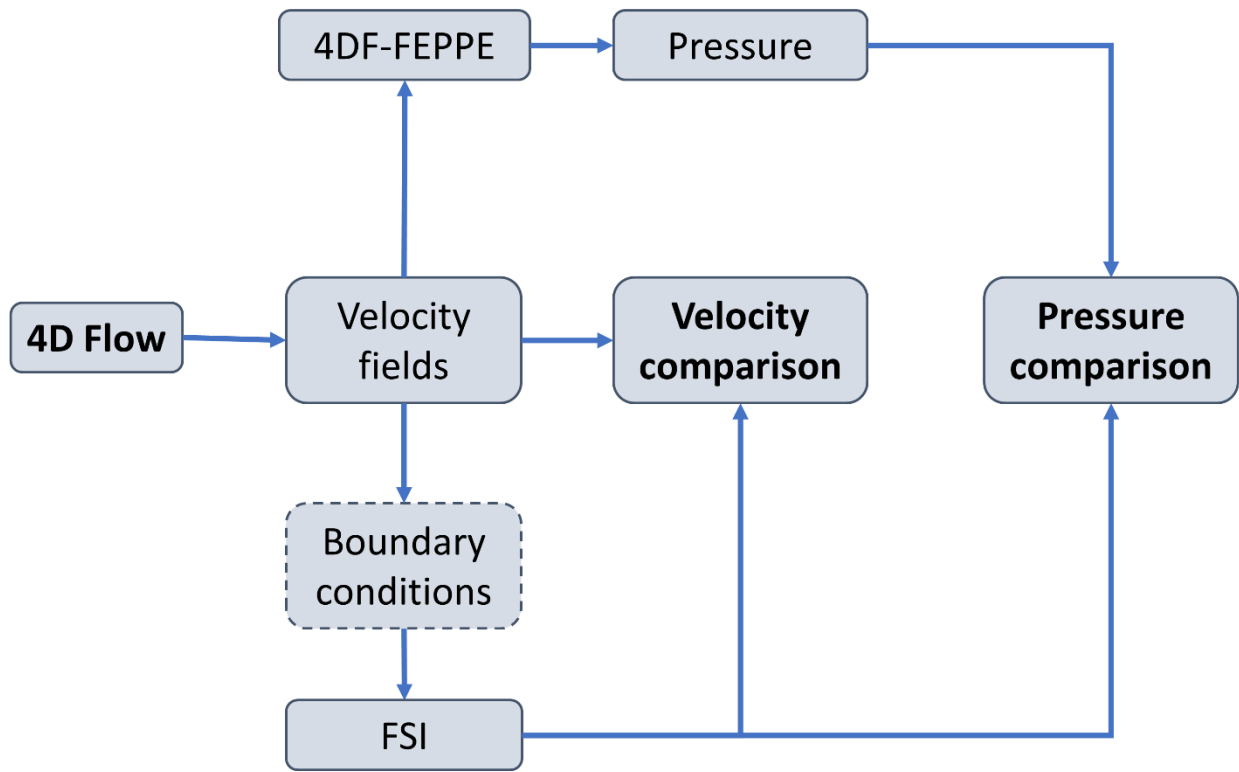
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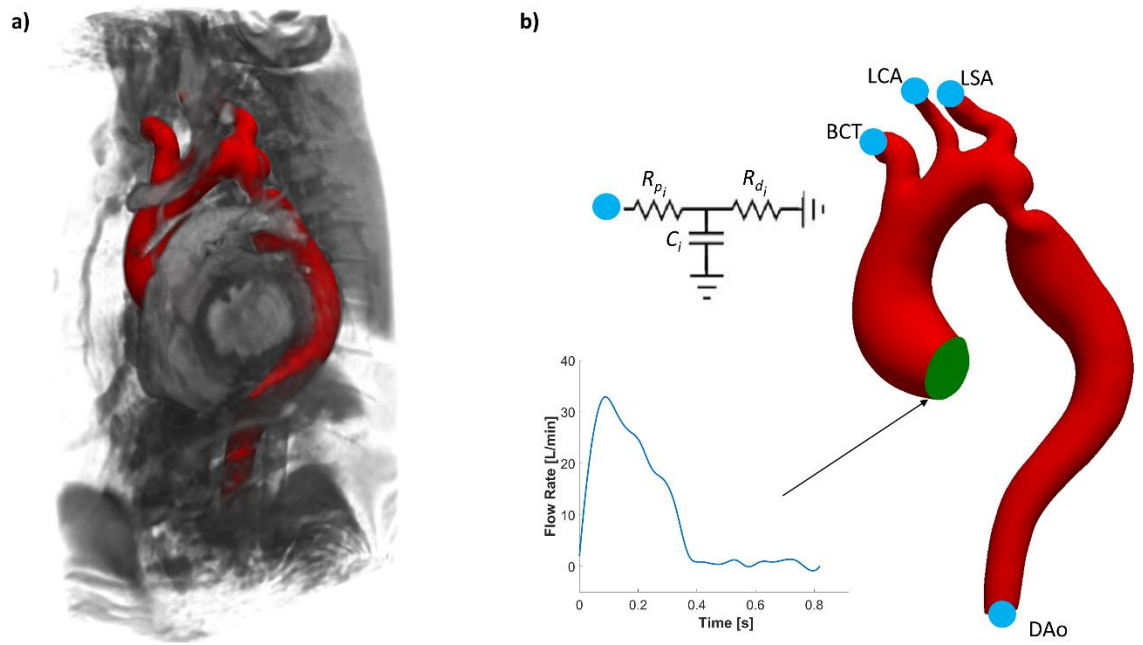


517

518 **Figure 1.** Schematic representation of the adopted workflow. 4D flow MRI data were used as input to 4DF-FEPPE

519 and as boundary conditions for the FSI simulation. FSI simulation results were first compared with raw 4D flow data

520 in terms of flow fields and then compared with 4DF-FEPPE pressure results.

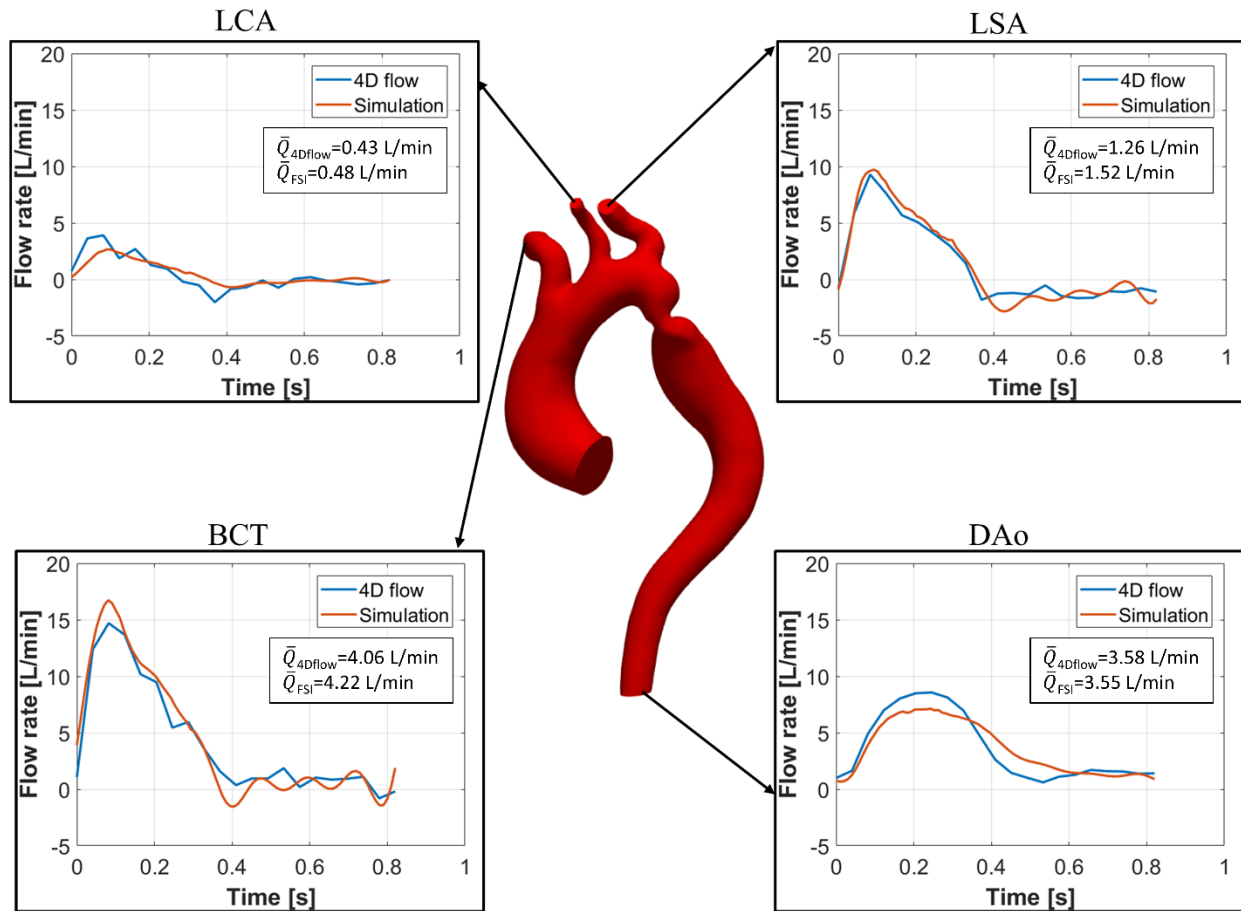


521

522 **Figure 2.** (a) Segmented 3D geometry (red) superimposed on a volumetric representation of MRA images. (b) FSI

523 simulation setup with patient-specific time-dependent flow rate curve imposed at the inlet (in green) and 3E-WKM

524 at the outlets. Different parameters were set for each outlet.

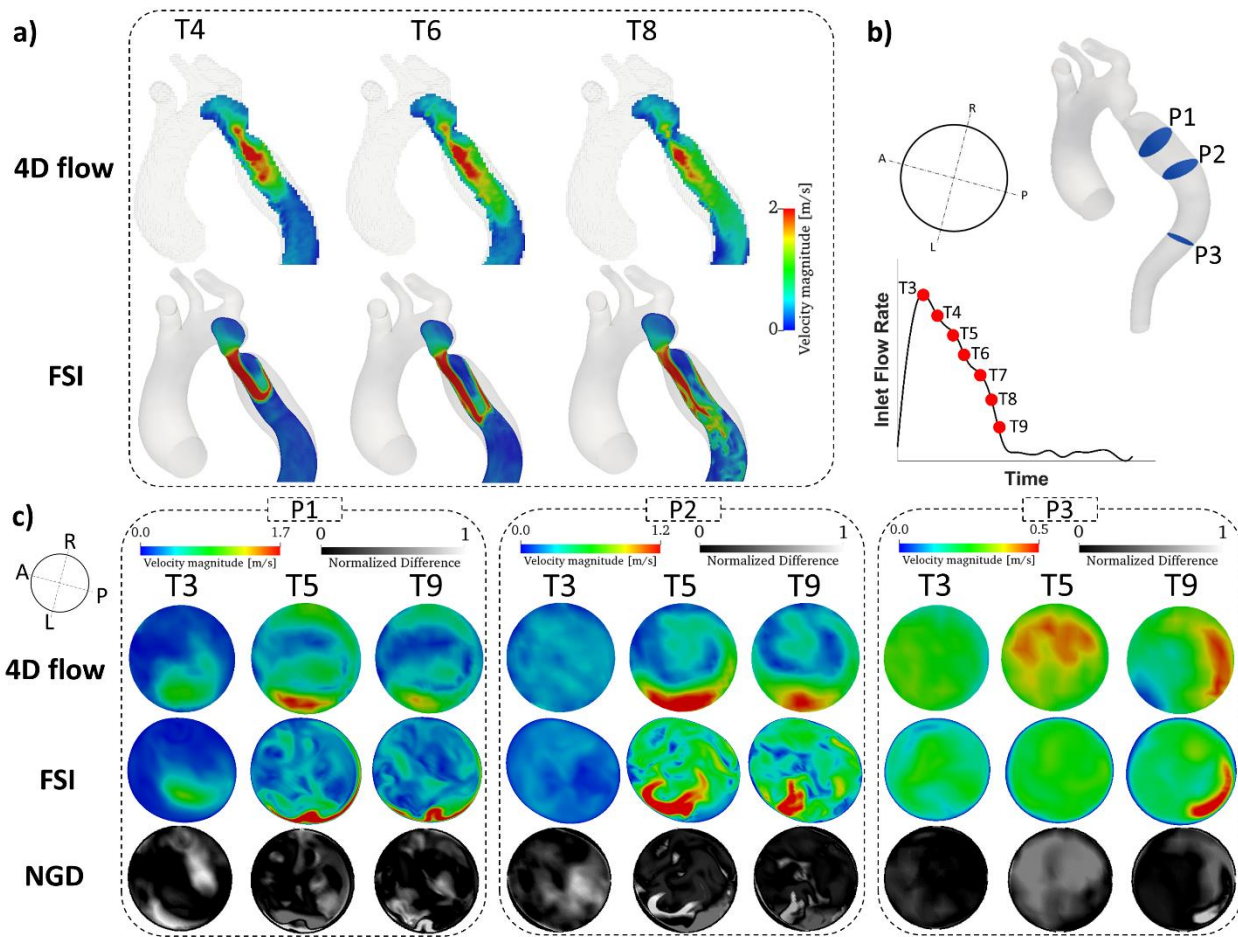


525

526 **Figure 3.** Outlet flow rates over time from FSI simulation results (red lines) compared to 4D flow data (blue lines).

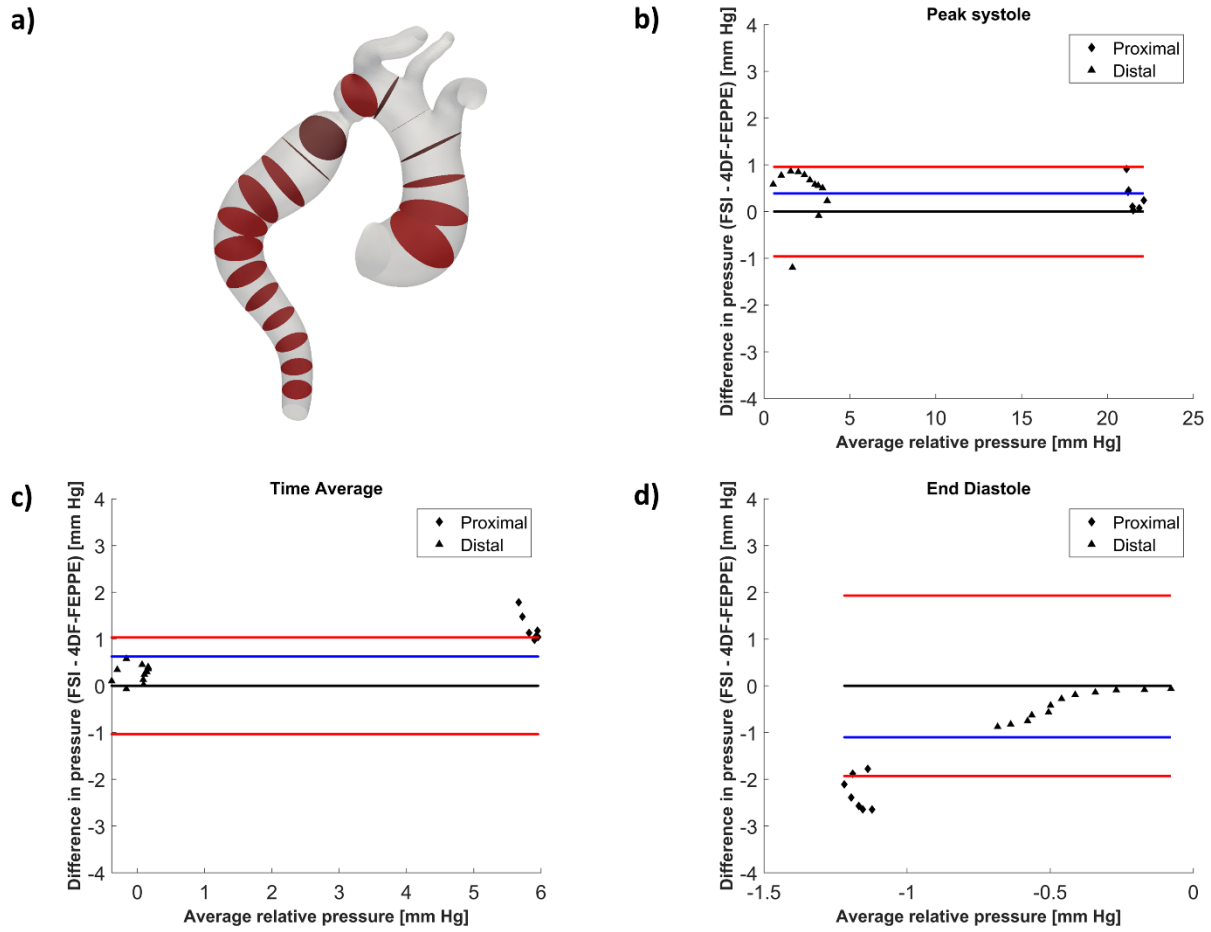
527 \bar{Q} =time-averaged flow rate. LCA=left carotid artery; LSA= left subclavian artery; BCT=brachiocephalic trunk; DAo=

528 descending aorta.



529

530 **Figure 4.** (a) Velocity magnitude contours on a sagittal plane in the descending aorta: comparison between 4D flow
 531 data and FSI results. (b) Representation of the 3D geometry used to analyze simulation results, cross-sectional planes
 532 are represented with their orientation together with time points in the cardiac cycle. (c) Velocity magnitude contours
 533 obtained from 4D flow data and FSI together with their normalized grayscale difference (NGD) images for the three
 534 cross-sections along the descending aorta.



535

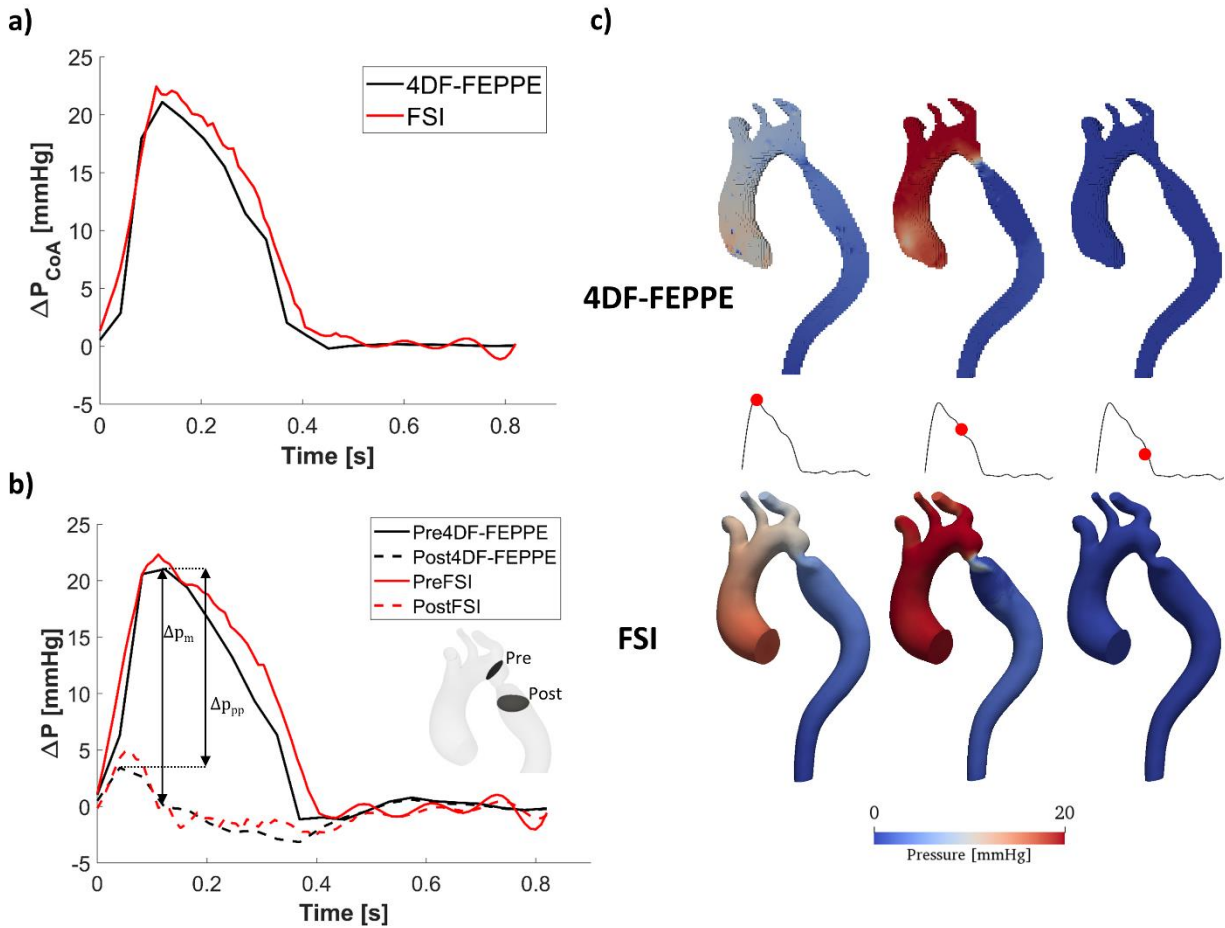
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Figure 5. Pressure comparison: (a) cross-sections along the aorta where pressure was analysed. Bland-Altman plots for (b) peak systolic, (c) time-averaged and (d) end-diastolic pressures differences obtained with FSI and 4DF-FEPPE for the selected locations. Values corresponding to regions proximal and distal to the coarctation are represented with diamonds and triangles respectively.



540
 541 **Figure 6.** Trans-coarctation pressure drop comparison: (a) instantaneous trans-coarctation pressure drop: 4D flow-
 542 based curve calculated with 4DF-FEPPE (black line) vs. simulation results (red line). (b) Pressure differences between
 543 a section proximal (Pre) to the CoA and the DAo (continuous lines), together with pressure differences between a
 544 section distal (Post) to the CoA and the DAo (dashed lines) calculated from 4DF-FEPPE (black) and FSI results (red);
 545 cross-section-averaged values over time are shown. The different definitions for peak-to-peak (Δp_{pp}) and maximum
 546 (Δp_m) pressure drops are shown for the 4D flow-derived curves. (c) Pressure difference contours calculated with
 547 4DF-FEPPE (top row) and with the FSI simulation (bottom row). Pressure differences are calculated with respect to
 548 the DAo.

549