

1 **Title:** Influence of repairable bolted dissipative beam splices (structural
2 fuses) on reducing the seismic vulnerability of steel-concrete composite
3 frames

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8 **ABSTRACT**

9 After a strong earthquake, repair work of conventional steel-concrete composite buildings
10 can be very expensive, and very often, impossible due to practical problems. Within the EU-funded
11 research project FUSEIS, a new steel-concrete composite frame type has been developed, as a
12 cost-effective and robust alternative to conventional earthquake resistant structures. In this new
13 frame type, damage concentrates mainly in the bolted dissipative beam splices acting as
14 “structural fuses”, which can be easily and inexpensively replaced after strong seismic events.
15 After the replacement, the building can be restored to its original form. This paper studies a
16 benchmark building frame with and without bolted dissipative beam splices. The performance of
17 both innovative and conventional structures has been quantified in terms of energy dissipation,
18 floor displacements and inter-story drifts, as a result of nonlinear transient dynamic analysis.
19 Different than similar studies in the literature, the numerical models explicitly consider the presence
20 of reinforced concrete slab by means of fiber-based distributed plasticity approach. They have
21 been calibrated according to the experiments, both provided in the literature and performed in the
22 FUSEIS research project. The models allowed the quantification of the energy dissipated by each
23 component of a steel-concrete composite frame (structural fuses, steel elements, concrete slab
24 and steel reinforcement), which gave an insight on redistribution of dissipated energy in the case of
25 adopting the structural fuses with respect to the traditional steel-concrete composite buildings.
26 Based on the results of the numerical analysis, the reparability subject has been discussed.

27 **Keywords:** Composite steel-concrete frames, dissipative bolted beam splices, structural
28 fuses, reparability, distributed plasticity

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31 carried out with the financial grant of the Research Program of the Research Fund for Coal and
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33 1 INTRODUCTION

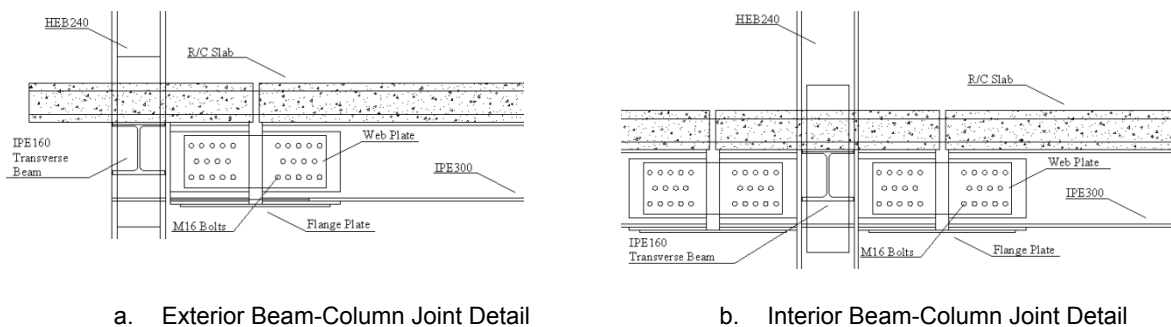
34 Steel-concrete composite structural systems combine the two most common construction
35 materials – steel and concrete – exploiting at best their mechanical properties. During the last
36 decades, these structures have frequently been employed in the earthquake-prone regions. The
37 earthquake events, such as US 1994 Northridge, 1995 Kobe, 2010 Chile and 2011 Christchurch
38 gave important insights about their seismic behaviour. Even though not many global failures were
39 apparent in case of steel-concrete composite buildings, the consequences were severe due to the
40 widespread damage and local brittle failure of a large number of welded beam-to-column
41 connections, and were associated with high repair costs (Engelhardt et al. 1997 [1]). An extensive
42 number of laboratory investigation on connection and weldments (Engelhardt et al. 1995 [2]; Popov
43 et al. 1996 [3]; Whittaker et al. 1996 [4]), and studies on fractured connections (Kaufman et al.
44 1995 [5]; Krawinkler, 1995 [6]) were conducted allowing to capture the leading causes of the
45 connection damages related to both welding and design issues. These failures pushed the
46 research community toward new design strategies to improve the seismic behavior of steel-
47 concrete composite moment resisting frame connections. In the past, mainly two solutions were
48 proposed to improve the seismic behaviour of steel-concrete composite frames: i) strengthening
49 the joint (Krawinkler, 1995 [6]) ii) weakening the beam framing into the column, by reducing its
50 section at a distance from the connections (Plumier A., 1990 [7], Yu et al. 2001 [8], Pachoumis et
51 al, 2010 [9], Avgerinou [10]). Both solutions aim at “forcing” the formation of a plastic hinge in the
52 beams away from the (welded) connection to achieve a better control of damages and to
53 guarantee a ductile global behaviour, by also preventing a fragile collapse mechanism. This means
54 that conventional systems, after a strong seismic event, are actually allowed to suffer significant
55 inelastic deformations (permanent damages) in their main structural elements (steel beams and
56 concrete slabs) and residual inter-storey drifts to a certain extent. Nevertheless, repair work in these
57 cases causes a long interruption of functionality of the building, leading to extra costs and discomfort
58 for building owners and occupants.

59 Several innovative dissipative technologies have been proposed for steel and composite
60 steel-concrete structures (Engelhardt et al. 1995 [2]; Plumier A., 1997 [11]; Dubina et al. 2008 [12];
61 Chan et al. 2008 [13]; Gowda et al. 2013 [14]; Braconi et al. 2012 [15]; Piluso et. al 2014 [25];
62 Morelli et al. 2016 (a) [16]; Morelli et al. 2016 (b) [17]; Karavasilis T.L., 2016 [18]; Dall'Asta et al.
63 2017 [21]; Hwang et.al. 2017 [19]; Morelli et al. 2017 [22]; Vamvatsikos et al. 2017 [23], Latour et
64 al. 2018 [24], Kamperidis et.al. 2018 [20]), which combine some of the most effective mechanisms
65 for the dissipation of seismic energy input, obtained through the inelastic deformation of steel
66 material. A comprehensive review of innovative dissipative systems and devices is presented by
67 Vayas I. (2017 [26]), summarizing the results of a number of EU-RFCS projects carried out in the
68 recent past, and rationalized within the EU-RFCS dissemination project INNOSEIS

69 (<http://innoseis.ntua.gr/> [27]). In the existing literature, mainly two aspects require further study
 70 regarding the structures with dissipative components. First, existing studies address most of the
 71 time the bare steel frame, ignoring the existence of the reinforced concrete slab. Therefore,
 72 experimental and numerical analysis to evaluate the performance of more realistic steel buildings
 73 with dissipative components are missing. Second, the researchers have so far mostly designed the
 74 dissipative systems to absorb as much energy as possible. However, although the damage
 75 reduction in the structural and non-structural elements after a disaster is a fundamental aspect for
 76 improving the long-term sustainability and resource conservation, the reparability aspect is
 77 generally ignored.

78 The need to restore damaged structural elements in post-seismic process has an increasing
 79 interest, as it concerns the reparability and the consequent costs that must be sustained for the
 80 repair works. Hence, while maintaining the benefits of high ductility necessary to perform the
 81 required deformations due to inelasticity, several studies have recently moved towards the
 82 research of new easily replaceable dissipative components.. In this perspective, the RFCS-funded
 83 project FUSEIS (Vayas et al. 2013 [28]; Calado et al. 2013 [29]; Castiglioni et al. 2012 [30];
 84 Dimakoyianni et al. 2015 [31]; Dougka et al. 2014 [32]) introduced an innovative dissipative system
 85 for steel-concrete composite frames. This new connection type is achieved by introducing a
 86 discontinuity in the composite beams of a moment resisting frame and splicing the two parts of the
 87 beam through steel plates bolted to the web and flange of the beam. In what follows, the
 88 expression “structural fuse” will be often used as synonymous of “bolted dissipative beam splice”.

89 The configuration of the structural fuse inside a typical beam-to-column connection is shown
 90 in Figure 1. In this configuration, the plasticization is expected to take place only in the replaceable
 91 parts of the connection. The part of the column near to the connection is reinforced in order to
 92 obtain an adequate over-strength. With this connection configuration, the center of rotation of the
 93 fuse is placed between the two reinforcement layers, which promotes the buckling of the web and
 94 flange steel plates of the splice. This becomes the source of the energy dissipation of the
 95 replaceable beam splice without damaging the rest of the main steel elements of the structure.



96 **Figure 1 Details of structural fuses (Castiglioni et al. 2012)**

97 In the fuse section, a gap of 50 mm is left without interrupting the steel reinforcement bars, to
 98 avoid the damage to the concrete slab due to crushing under flexural deformation. This gap also

99 aims to avoid damage to the floor finishes such as tiles, hydraulic piping or electric wiring. In
100 everyday practice, the gap could be filled with low stiffness foams made of polymers which would
101 not affect the structural performance, while in the other hand would guarantee covering/finishing
102 continuity. These components in practice, may be designed referring to the existing EN1993-1-1
103 and EN1998-1-1, since all the elements included in the structure are made of classical steel
104 construction components, unlike more technological devices (for example the seismic isolation
105 devices) that need to be certified according to EN15129 to be used in practice (Vayas I., 2017
106 [26]).

107 In FUSEIS research project, beam-to-column joint components (Figure 2.a) and full scale
108 specimens (Figure 2.b) have been tested respectively at Instituto Superior Tècnico of Lisbon and
109 at Politecnico di Milano. The tested systems showed very good performance in terms of stiffness,
110 ductility, energy dissipation and resistance, and the structural fuses proved to be very easily
111 replaceable (Castiglioni et al. 2012 [30]). The main structural elements being the non-replaceable
112 parts remained generally in the elastic range or with non-significant damages as intended. The
113 inelastic deformation was mainly concentrated on the structural fuses that were the only
114 component to be replaced after each test. The detailed findings obtained were presented in two
115 articles (Castiglioni et al. 2012 [30]; Calado et al. 2013 [29]).



a. Component tests – IST



b. Full scale tests - POLIMI

116 **Figure 2 Experimental Set-up**

117 This paper quantifies the performance of a benchmark multi-storey building with a steel-
118 concrete composite frame designed by (Zona et al. 2008 [33]) with and without structural fuses by
119 means of nonlinear transient dynamic analysis. Numerical models have been developed using
120 distributed plasticity approach (Uriz et al. 2008 [34]; Sabelli R., 2001 [35]). The models have been
121 calibrated with reference to the experimental results available in the literature (Nie et al. 2003 [36];
122 Bursi et al. 2000 [37]; Nie et al. 2011 [38]) and experimental investigations from the FUSEIS

123 research project (Vayas et al. 2013 [28]). Global response parameters have been quantified such
124 as energy dissipation, base shear and inter-storey drifts.

125 **2 SIMPLIFIED STEEL-CONCRETE COMPOSITE FRAME MODEL**

126 Parametric analysis of the structural fuses was performed with refined finite element
127 numerical models in previous studies (Valente et al. 2016 [39]; Valente et al. 2017a [40]; Valente et
128 al. 2017b [41]), which can be used for specific research applications. However, to study the
129 performance of whole building structures, a simplified model has been proposed hereafter and
130 validated against experimental results from previous studies. The finite element model has been
131 developed using fiber-based beam elements with distributed plasticity implemented in Strand7
132 environment (Strand7 2004 [42]). This modelling approach distributes plasticity by numerical
133 integrations using mainly the displacement-based finite elements: each element is divided into
134 several cross sections along the member length, which are further subdivided into fibers with
135 specific stress/strain relations (Nguyen et al. 2014 [43]). The fibers are considered as mono-
136 dimensional elements with nonlinear elastic constitutive law. Assuming that plane sections remain
137 plane, the strain in each fiber is calculated from centroidal section strain and curvature, then the
138 stresses are calculated from the previous strain values. By integrating the response of the fibers,
139 the constitutive relation of the cross section is obtained, which is then integrated along the member
140 length and allow monitoring the axial force and moments, incremental moment-curvature and axial
141 force-strain relations. Finally, nonlinear transient dynamic analysis has been performed,
142 considering material and geometrical nonlinearities, for the beam and column elements, and plastic
143 links for fuse elements.

144 The modelling of the concrete nonlinear behaviour is characterized by the complexity of the
145 material features, such as mechanical parameters degradation, energy dissipation for hysteresis,
146 progressive cracking caused by tensile stresses and strains. Moreover, the presence of
147 reinforcement requires more complex modelling considerations such as: bond between concrete
148 and steel, aggregation interlocks and dowel action. Since the aim of this study is the investigation
149 of the global response of a building structure where the presence of concrete material is limited to
150 the slab of the composite beam, and to achieve a high calculating efficiency, a simplified stress-
151 strain relationship for plain concrete in the uncrushed and un-cracked condition has been
152 considered. In this regard, a conservative set of rules are applied for the definition of stress-strain
153 relationship on post-peak phase, by omitting the decreasing stress value for the definition of the
154 softening branch. It is worth emphasizing that the softening and localisation problems, which could
155 be regarded as material instabilities that are caused by micro-cracks, are considered not to affect
156 the macrostructure behaviour at a significant level. Up to the peak, the parabolic curve equation
157 from (UNI EN 1992 2004 [44]) Eqs. (1-4) has been used, and a constant branch has been
158 considered after reaching the peak compressive strength (Figure 3.a).

159
$$\frac{\sigma_c}{f_{cm}} = \frac{k \cdot \eta - \eta^2}{1 + (k - 2) \cdot \eta} \quad (\text{eq.1})$$

160 where:

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$$- \eta = \frac{\varepsilon_c}{\varepsilon_{c1}} \quad (\text{eq.2})$$

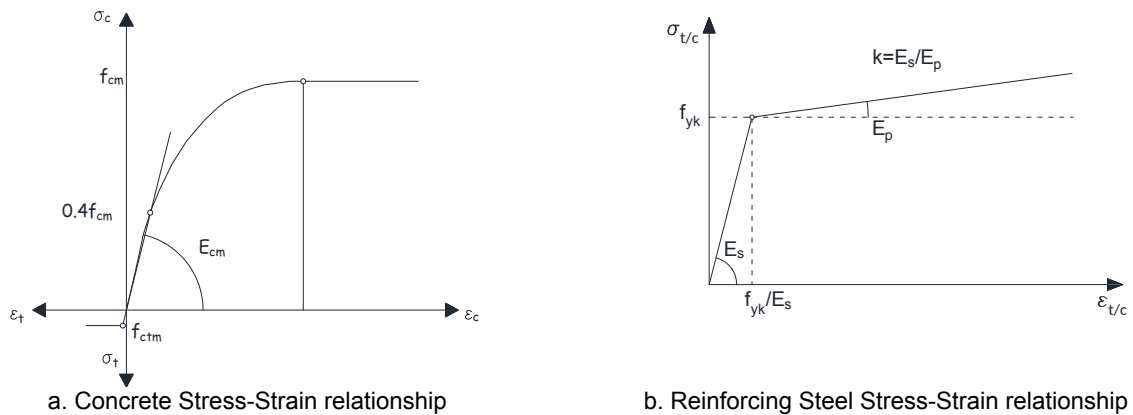
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$$- k = 1,05 \cdot \frac{E_{cm} \cdot |\varepsilon_{c1}|}{f_{cm}} \quad (\text{eq.3})$$

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$$E_{cm} = \left(\frac{f_{cm}}{10}\right)^{0.3} \quad (\text{eq.4})$$

164 For concrete in tension, the adopted constitutive relation consists in two parts: the first one is
 165 linear elastic up to the tensile strength f_{ctm} Eq. (5) and a strain equal to 0.0015%; then a pure
 166 plastic behaviour with a constant branch has been considered.

167
$$f_{ctm} = 0.4f_{ck}^{2/3} \quad (\text{eq.5})$$

168 The steel constitutive relationship is idealized as a bilinear curve, representing elastic-plastic
 169 behaviour with linear strain hardening (Figure 3.b), symmetric both in tension and compression. In
 170 order to verify the proposed numerical models and investigate the nonlinear behaviour of the
 171 composite frame structure, some examples from the literature, including simply supported beams
 172 and plane frames, were analysed and compared with the respective experimental results.



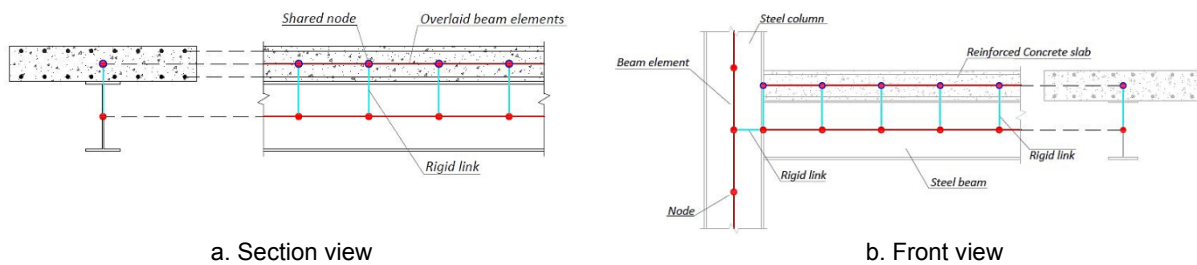
173 **Figure 3 Steel constitutive relation**

174 **2.1 Steel-concrete composite slab**

175 To achieve a good balance between the numerical accuracy and feasible computational
 176 time, a simplified model has been developed for the steel-concrete composite connections used in
 177 this study. The numerical model is schematically represented in Figure 4. Steel beams and
 178 columns reinforced concrete slab and structural fuse are modelled with two-node fiber beam
 179 elements. Slip effect between the steel beam and concrete slab is not considered since its
 180 influence on the global response of the building is assumed to be not significant in this case.
 181 Therefore, the overlaid beams sharing the same nodes have the same translation and rotation

182 degree of freedoms. This full composite action has been represented by rigid link elements
 183 connecting the steel and concrete beam elements (simulating the shear connectors). An additional
 184 beam element has been used to simulate the two rows of steel reinforcement, placed at the
 185 centroid of the concrete slab. The distance between the centroids of the concrete and the steel
 186 beam is taken into account applying an offset to the concrete slab element.

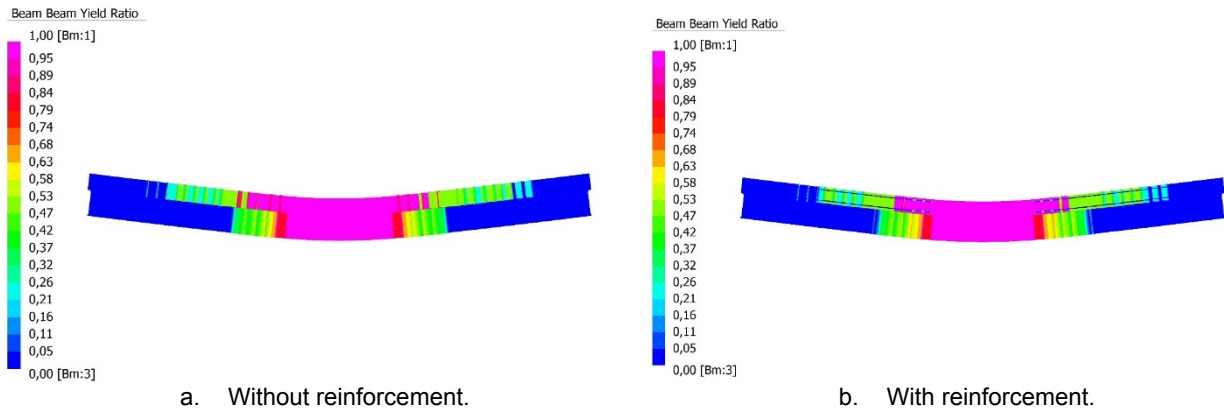
187 In the performance of the buildings with steel-concrete composite frames and structural
 188 fuses, since most of the plasticity concentrates in the fuses. the impact of the phenomena such as
 189 strength deterioration of the concrete and the contact between concrete slab and steel column
 190 should be minimal. Therefore, during modelling, these two phenomena are not considered,
 191 resulting in a more robust steel-concrete composite connection with slightly underestimated energy
 192 dissipation capacity. For the comparison purposes of this paper (performance of the buildings with
 193 and without fuses), these simplifications can be acceptable since in both cases the same
 194 imperfections will be present. Finally, the accuracy of the models are rated using the experimental
 195 results of the tests in the literature, performed with simply supported beams (i) (Nie et al. 2003 [36])
 196 continuous beams (ii) (Bursi et al. 2000 [37]), and plane frames (iii) (Nie et al. 2011 [38]).



197 **Figure 4: Numerical model scheme of composite steel-concrete beam.**

198 **2.1.1 Simply-supported composite beam tested by (Nie et al. 2003 [36])**

199 In order to verify the rationality of the adopted numerical model, the nonlinear behaviour of a
 200 simply-supported composite beam has been simulated under monotonic loading. The specimen
 201 was subjected to hogging moment (Nie et al. 2003 [36]). Two models are developed, namely with
 202 and without slab reinforcement. The cubic compressive strength $f_{ck,cube}$, reinforcing steel yield
 203 strength f_{yr} and structural steel yield strength f_{ys} are adopted from experimental results reported as
 204 27.7 N/mm², 290 N/mm² and 310 N/mm², respectively. The deformed shape under sagging
 205 visualized together with yield ratio shows that the concrete slab is mainly under compression; thus,
 206 the results are insensitive whether, in the model, the slab reinforcement is considered or not
 207 (Figure 5).



208 **Figure 5 Deformed shape with yield ratio of simply-supported composite beam tested by (Nie et al. 2003**
 209 **[36])**

210 The results show that the simplified numerical model captures tolerably the test specimen
 211 behaviour as concerns the initial stiffness and moment capacity; the presence of slab
 212 reinforcement does not affect the result in terms of stiffness, but slightly influence the ultimate
 213 flexural capacity, as shown in Figure 5 and presented in Table 1.

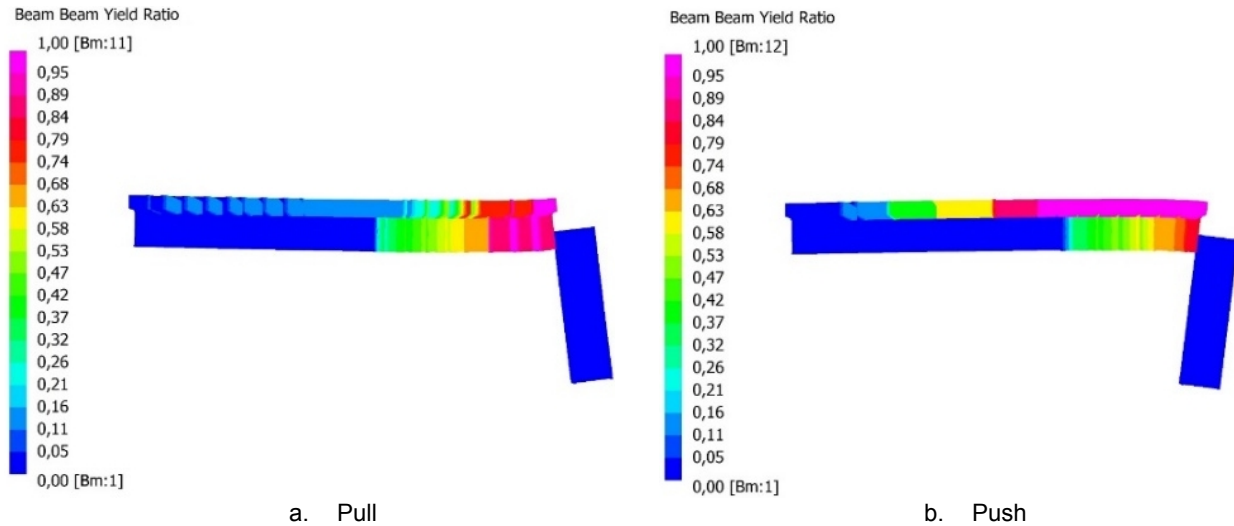
	Numerical	Experimental	Ratio Num/Exp
Stiffness (kNm/m)	14433	12998	1,11
M_{yield} w/o reinforcement (kNm)	147	125	1,18
M_{yield} with reinforcement (kNm)	147	125	1,18
M_{max} w/o reinforcement (kNm)	202	199	1,02
M_{max} with reinforcement (kNm)	207	199	1,04

214 **Table 1 Quantitative comparison with (Nie et al. 2003 [36])**

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227 **2.1.2 Composite frame joint tested by (Bursi et al. 2000 [37])**

228 The nonlinear behaviour of the composite frame tested by (Bursi et al. 2000 [37]) has been
 229 simulated under cyclic loading. The cylindrical compressive strength f_{ck} , reinforcing steel yield
 230 strength f_{yr} and structural steel yield strength f_{ys} are adopted from experimental results reported as
 231 39 N/mm², 482 N/mm² and 291 N/mm², respectively. The deformed shape under monotonic
 232 loading together with yield ratio are shown in Figure 6.



233 **Figure 6 Yield ratios of the numerical model (Pull and Push)**

234 The results of the cyclic loading show that the numerical model correlates adequately with
 235 the test specimen behaviour as concerns the initial stiffness (K_{push} , K_{pull}) and resistance ($F_{pull,max}$,
 236 $F_{push,max}$). The quantitative comparison is given in the following Table 2.

	Numerical	Experimental	Ratio (Num/Exp)
K_{push} (kN/m)	15849	15769	0.99
K_{pull} (kN/m)	17780	17004	1.05
$F_{pull,max}$ (kN)	355	359	0.98
$F_{push,max}$ (kN)	-236	-276	0.86

237 **Table 2 Quantitative comparison (Bursi et al. 2000 [37])**

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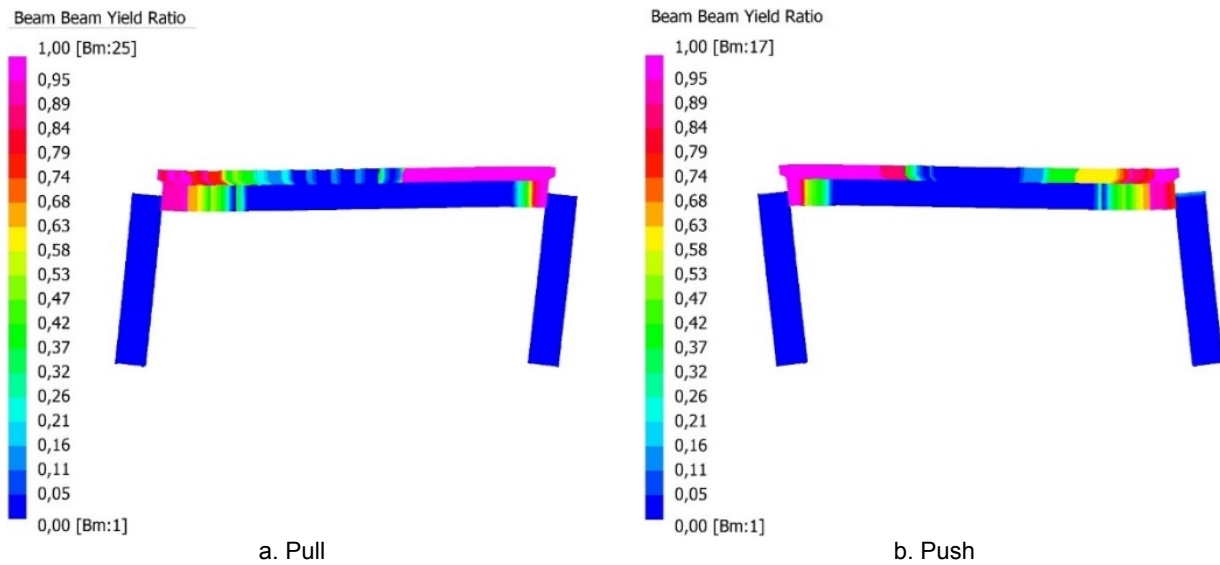
244 **2.1.3 Full scale composite frame tested by (Nie et al. 2011 [38])**

245 The nonlinear behaviour of the composite frame tested by (Udagawa et al. 1991 [45]) has
 246 been simulated under cyclic loading. The cylindrical compressive strength f_{ck} , reinforcing steel yield
 247 strength f_{yr} and structural steel yield strength f_{ys} are adopted from experimental results reported as
 248 22,6 N/mm², 300 N/mm² and 353.3 N/mm², respectively. The deformed shape under pull and push
 249 visualized together with yield ratio are shown in Figure 7.

	Numerical	Experimental	Ratio (Num/Exp)
K _{push} (kN/m)	14010	13500	1.03
K _{pull} (kN/m)	14010	13500	1.03
F _{pull,max} (kN)	208	231	0.90
F _{push,max} (kN)	-224	-236	0.95

250 Table 3 shows the comparison of results, which are in good agreement also in this case.

251



252 **Figure 7 Yield ratio of numerical model (Push and Pull)**

	Numerical	Experimental	Ratio (Num/Exp)
K _{push} (kN/m)	14010	13500	1.03
K _{pull} (kN/m)	14010	13500	1.03
F _{pull,max} (kN)	208	231	0.90
F _{push,max} (kN)	-224	-236	0.95

253 **Table 3 Quantitative comparison (Udagawa et al. 1991 [45])**

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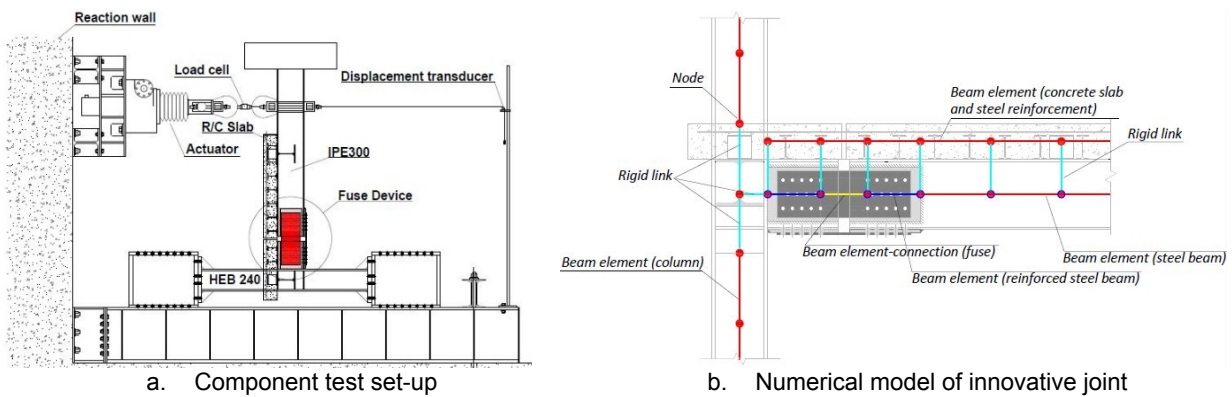
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259 **3 STEEL-CONCRETE COMPOSITE FRAMES WITH STRUCTURAL FUSES**

260 Two numerical models have been developed to simulate the component and the full-scale
261 cyclic tests implemented at Instituto Superior Tecnico (IST) in Lisbon (Calado et al. 2013 [29]) and
262 at Politecnico di Milano (Castiglioni et al. 2012 [30]). The component test model aimed to
263 characterize the fuses in terms of moment rotation curves, and the full-scale model intended to
264 simulate a real scale case which was a portion of a storey of a composite steel frame with
265 structural fuses. In the following, the details of these models are provided.

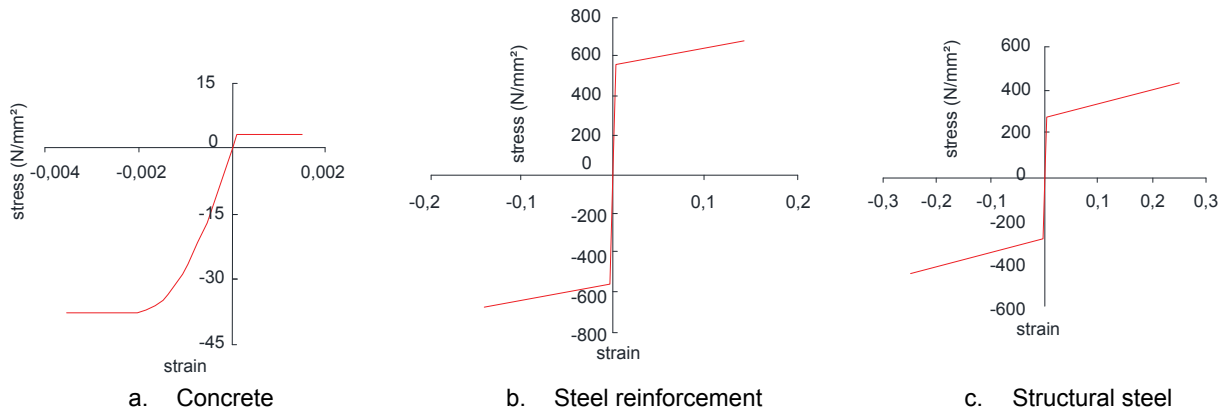
266 **3.1 Numerical simulation of the component tests**

267 The numerical model developed for the bolted structural fuse is shown in Figure 8.b. Steel
268 columns and beams, concrete slab, and reinforcement steel are modelled with fiber-based inelastic
269 beam elements. The structural fuse is modelled as a connection-beam element, positioned within
270 the free length $L_0 = 170\text{ mm}$, and connected to the adjacent beam elements with rigid links. The
271 beam element representing the concrete slab has been introduced with an offset. The model has
272 been developed based on the geometry used in the experimental set-up. To consider the
273 reinforcing contribution of welded steel cover plates, the web dimension of the beam elements next
274 to the connection have been increased by the thickness of the plates. Because of the presence of
275 web stiffeners, the beam-to-column web panel area has been modelled with rigid links.



276 **Figure 8 Experimental test set-up (Calado et al. 2013 [29])**

277 As concerns the boundary conditions, the end nodes of the column are fully restrained while
278 the top of the steel beam is free to move and subjected to an imposed displacement, in order to
279 reproduce the cyclic loading history from the test. All the structural elements are modelled with
280 elasto-plastic material. The uniaxial stress-strain relationships are based on the material properties
281 reported in (Calado et al. 2013 [29]). Both structural and reinforcing steel are defined with a bilinear
282 relation and kinematic hardening type, while the concrete is defined with a parabolic and linear
283 branch in compression and with a linear and straight branch in tension, as described in section 2.
284 The stress-strain curves are depicted in Figure 9.

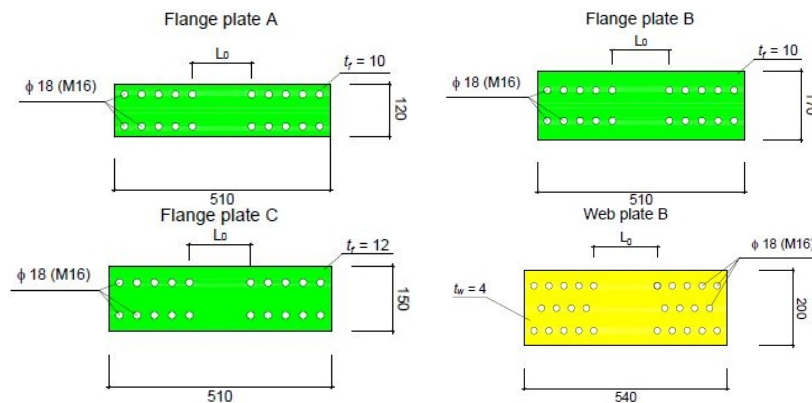


285 **Figure 9 Material uniaxial stress-strain curve**

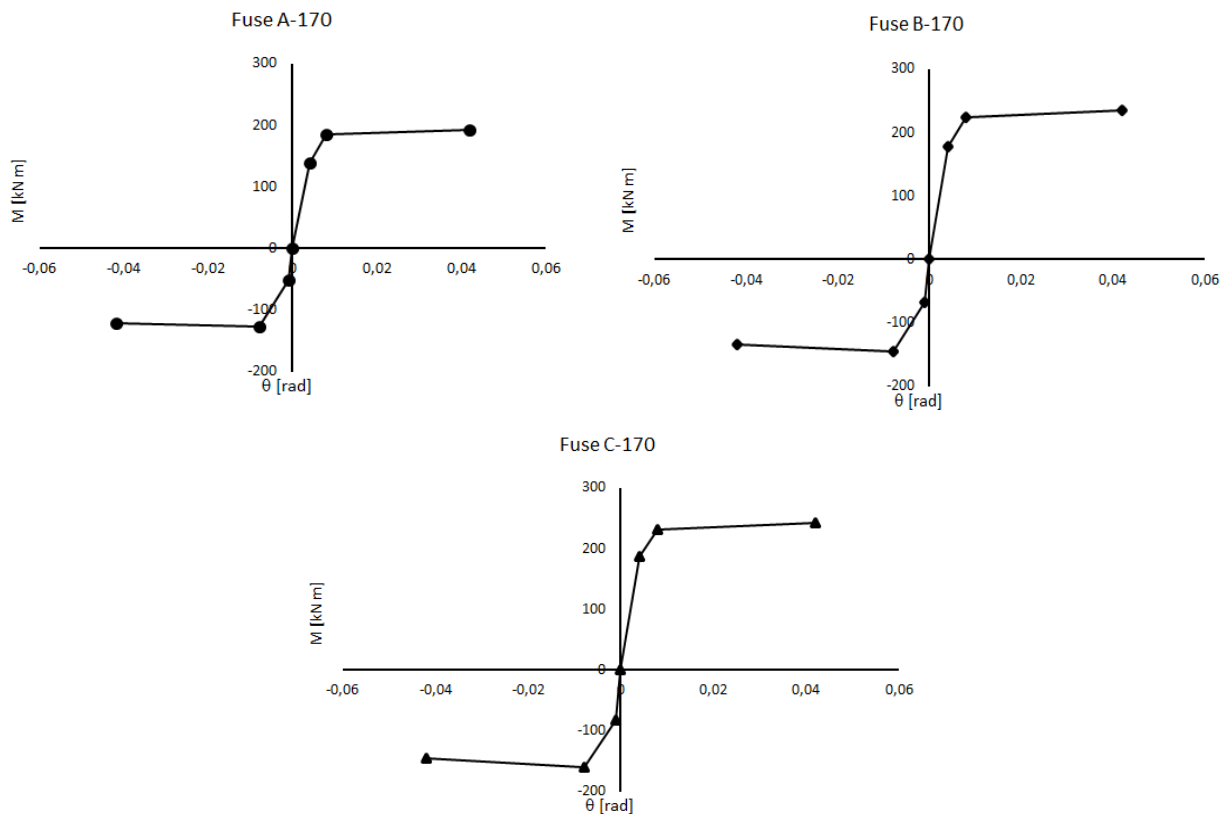
286 The nonlinear behaviour of the connection element, representing the structural fuse, is
 287 defined by a moment-rotation diagram, which is calculated analytically, and calibrated according to
 288 the results of the component tests performed during FUSEIS research project (Vayas et al. 2012
 289 [46]). In order to capture the nonlinear response, the hysteresis type is assumed to be the one
 290 described by the Takeda Model (Takeda T., 1970 [47]), which represent the most suitable
 291 hardening type among those provided by the numerical analysis software (Straus7 2004 [42]).
 292 Three models have been created, one per each fuse type considered (A, B and C in Table 4),
 293 which differ in terms of the flange height and thickness, while the web plate has the same
 294 dimension in all the tests. The moment-rotation input diagrams are reported in Figure 11.

Flange plate	A	B	C
t_f [mm]	10	10	12
b_f [mm]	120	170	150

295 **Table 4 Dimensions of the flange plates**



296 **Figure 10 Dimensions of the fuse flange and web plates**

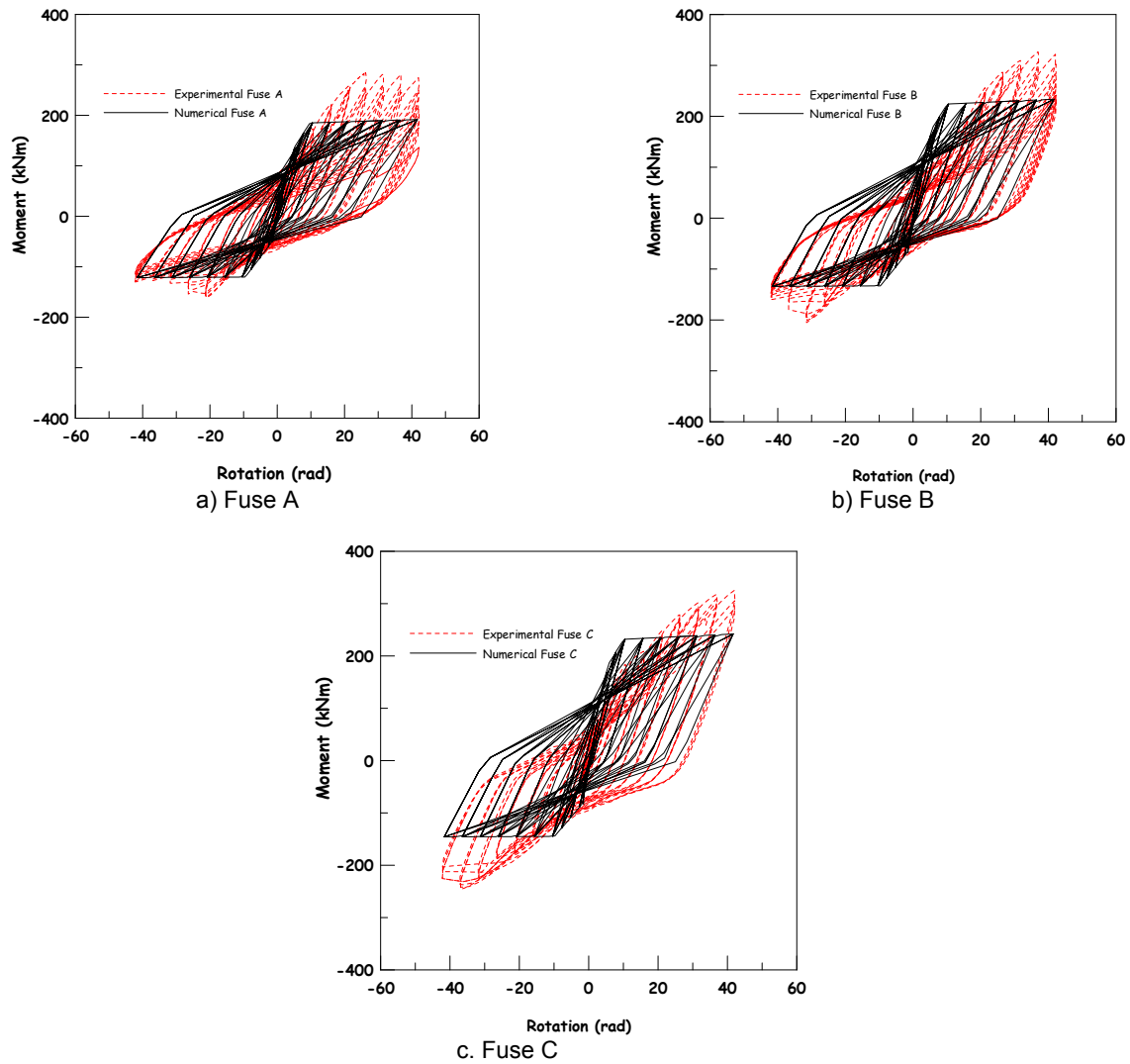


297 **Figure 11 Moment-rotation input diagram for structural fuses**

298 Figure 12 shows the comparison between the numerical and experimental results. While the
 299 steel beam and column remain within their elastic range, the overall joint behavior is characterized
 300 by the inelastic deformation taking place mainly in the structural fuses.. The asymmetry of the
 301 moment-rotation diaphragms is due to the configuration of the structural fuse composed of steel
 302 plates and composite steel-concrete slab. The maximum rotation observed in the structural fuse
 303 was 40 mrad. It can be observed that the amplitude of the hysteresis cycles obtained numerically
 304 are smaller, and this can be associated to the simplifications introduced in the definition of stress-
 305 strain tables and modelling assumptions. [In all the cases, numerical results remain on the](#)
 306 [conservative side showing less energy dissipation with respect to the experiments Table 5.](#) The
 307 best fit is achieved in the case of Fuse B.

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309



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Figure 12 Experimental vs. numerical result of test specimen (Calado et al. 2013 [29])

Fuse	Experiments (kNmrad)	Numerical (kNmrad)	Ratio num/exp
A	13852	11525	0.83
B	14506	13700	0.94
C	15908	14456	0.91

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Table 5 Total Energy Dissipation (Calado et al. 2013 [29])

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The specimen after testing is shown in Figure 13. During sagging, flange and web plates were under tension, while under hogging, both plates buckled under compression. The composite beam and the column remained almost elastic with no evidence of plastic deformations in steel elements, and almost no tensile cracks in the concrete slab.

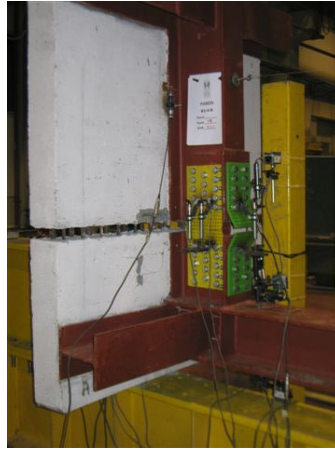


Figure 13 Inelastic deformation obtained during tests

3.2 Numerical modelling of the full-scale test specimens

The experimental set up (Figure 14) for the full scale test performed at Politecnico di Milano represents a portion of a multi-story frame, with three structural fuses namely Fuse 1, Fuse 2 and Fuse 3. The structure is composed of four HEB240 steel columns, two IPE300 steel beams and a 150-mm thick reinforced concrete slab supported by IPE160 transverse beam placed every 1.4 m, in addition to a pair of transverse beams, placed at each beam-to-column connection. Full shear connection is provided between the slab and the steel beam by means of IPE100 sections welded on top of the beam flange, acting as shear studs. The numerical model of the full-scale test specimens is developed assuming the same choices done for the component test specimen (Figure 8.b) as concerns the materials and geometry of the members and the moment-rotation input diagram of the fuses devices. The boundary conditions reproduce the experimental configuration: at the bottom, the columns are pinned while at the top, the rigid beam is modelled by enforcing the same displacement at both columns. The end node of the steel beam connected to the Fuse 3 is restrained only against vertical displacement with a roller. Three models have been created, one per each fuse type considered (A, B and C, see Table 4).

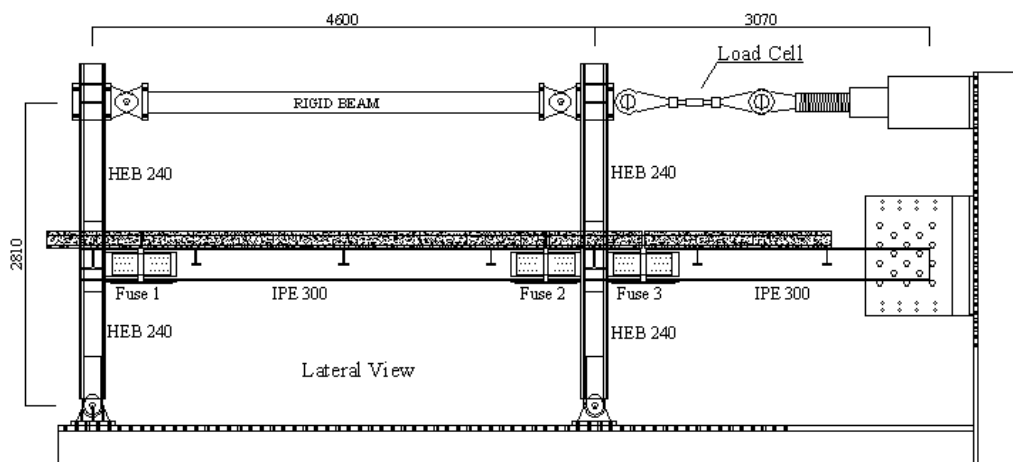
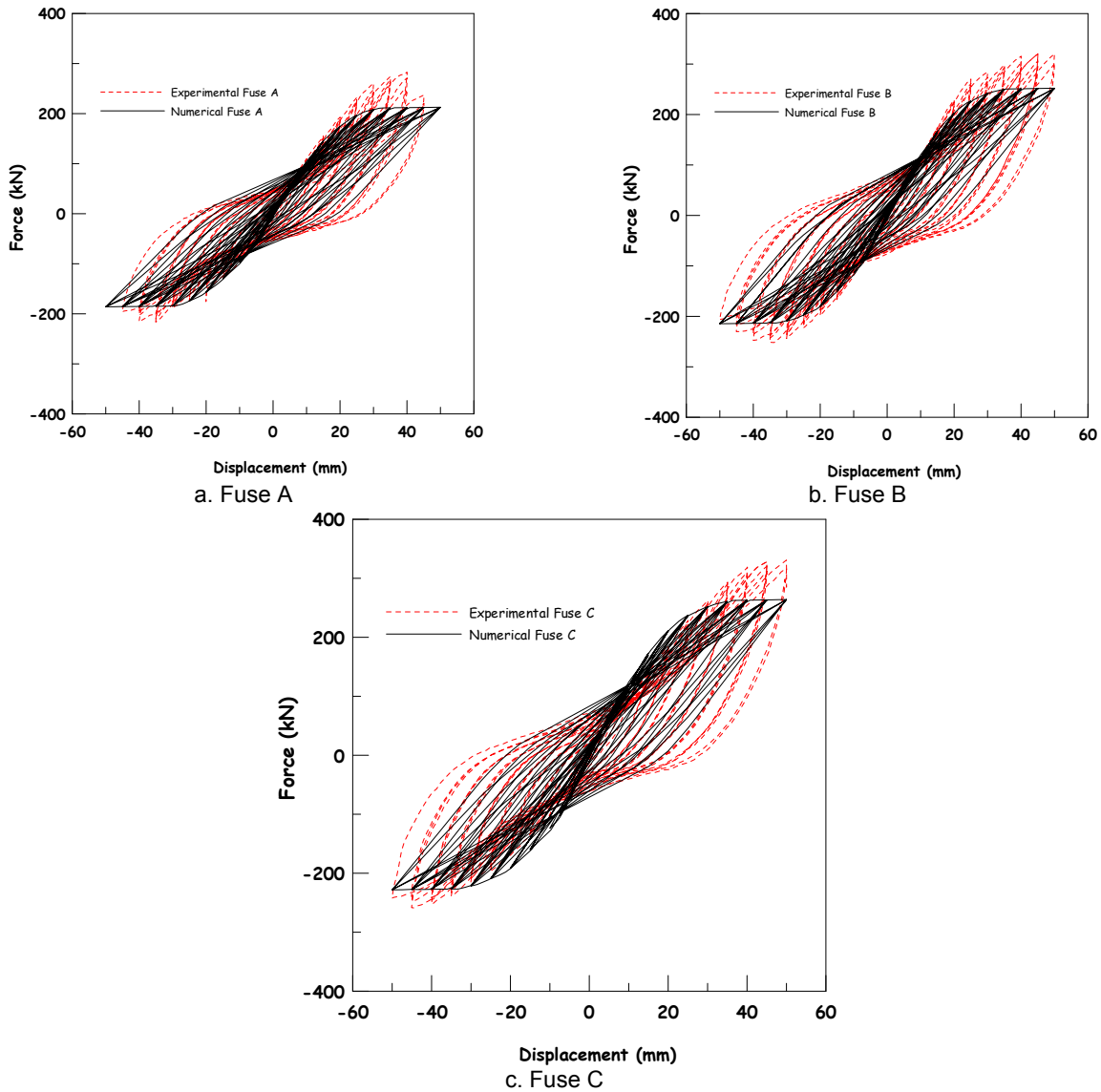


Figure 14 Experimental set-up (Castiglioni et al. 2012 [30])

336 Also, in this case, the inelastic deformation took place mainly in the structural fuses, the steel
 337 beams and columns remaining elastic. The maximum rotation observed in the structural fuse was
 338 42 mrad. The comparisons between numerical and experimental results in terms of global force-
 339 displacement behaviour are shown in Figure 15. As in the case of component models, the
 340 amplitude of hysteresis cycles of the numerical models is smaller because of the simplifications
 341 introduced in the modelling. Numerical results remain on the safe side showing less energy
 342 dissipation with respect to the experiments Table 6.



343 **Figure 15 Experimental vs. numerical result for the test specimen (Castiglioni et al. 2012 [30])**

Fuse	Experiments (kNmm)	Numerical (kNmm)	Ratio num/exp
A	13742	11523	0.84
B	19376	13238	0.68
C	17601	13973	0.79

344 **Table 6 Total Energy Dissipation (Castiglioni et al. 2013 [30])**

345 The inelastic deformation that provided the hysteresis behaviour can be seen in Figure 16 in
346 case of an exterior (a) and an interior joint (b).



347 **Figure 16 Inelastic deformation of the structural fuses**

348 In general, the numerical models provide reasonable results. However, in some cases they
349 result in lower energy dissipation with respect to the experimental ones. This is because of the
350 simplifications introduced in the models to be able to achieve a feasible computational time for the
351 nonlinear transient analysis of the multi-storey building example that is presented in the next
352 chapter. Indeed, the objective of this study is not to simulate perfectly the steel-concrete composite
353 structures which was already done in the previous studies (Nie et al. 2003 [36]; Bursi et al. 2000
354 [37], Valente et al. 2016 [39]), but to quantify the improvements obtained thanks to the structural
355 fuses in the performance of the whole buildings with steel-concrete composite frames under
356 acceleration-time history input.

357 **4 STRUCTURAL FUSES IN A BENCHMARK BUILDING EXAMPLE**

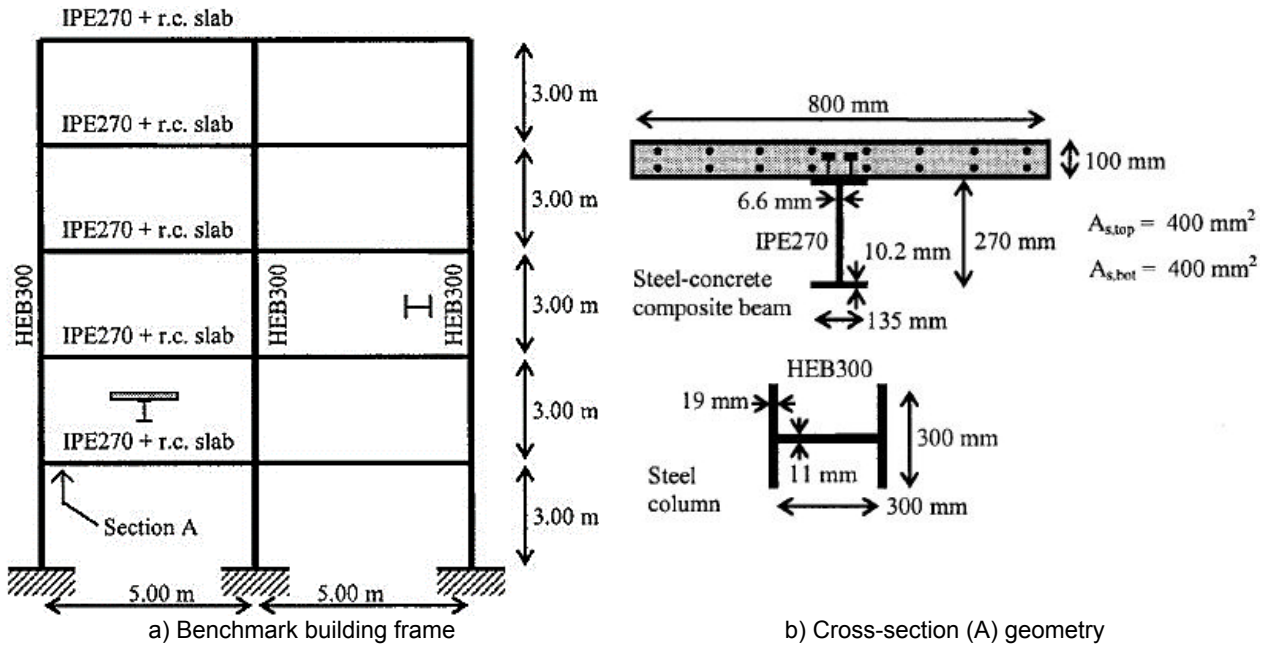
358 To quantify the performance of the structural fuses, two models have been analysed:

- 359 i) A conventional moment resisting steel-concrete composite frame (benchmark);
- 360 ii) A model with the structural fuses, placed close to the ends of composite beams of the
361 benchmark model

362 Nonlinear time-history analyses have been performed. The results have been interpreted in
363 terms of floor displacements, inter-story drifts, base shear and energy dissipated by each
364 component of the steel-concrete composite frame (structural fuses, steel elements, concrete slab
365 and steel reinforcement).

366 The benchmark model ("Model-B") is a five-storey two-bays moment resisting frame made of
367 steel columns and composite beams, which was designed by (Zona et al. 2008 [33]) in a previous
368 study (Figure 17). Each bay and storey has a span of 5 m and a height of 3 m. The steel columns
369 are made of European HEB 300 wide flange S275 steel beams, while the composite beams are
370 made of European IPE 270 S275 steel I-beams connected by means of stud connectors to a 100-
371 mm-thick C25/30 concrete slab with an effective width estimated as 800 mm. The reinforcement of

372 the concrete slabs consists of top and bottom layers of 400 mm² of B450C re-bars with a concrete
 373 cover of 30 mm. The frame was designed according to (UNI EN 1994-1-1 2004 [48]) to resist the
 374 static loads (composite cross section self-weight= 2.36 kN/m, permanent load G= 16 kN/m, and
 375 live load Q= 8 kN/m, uniformly distributed along the composite beams), and seismic forces were
 376 evaluated using response spectrum analysis with peak ground acceleration=0.35 g, Type 1
 377 spectrum of (UNI EN 1998-1-1 2005 [49]), modal damping ratio=5%, and soil class B.



378 **Figure 17 Steel-concrete composite frame tested (Zona et al. 2008 [33])**

379 In “Model-F”, the structural fuses have been introduced. The fuses have been designed by
 380 means of a parameter a introduced as a capacity ratio, to achieve their best performance in terms
 381 of capacity and energy dissipation, as suggested by (Castiglioni et al. 2012 [30]). The a value
 382 relates the resistant capacity of the fuse to the plastic resistance of the cross-section of the
 383 composite beam, and can be defined as the capacity ratio of the fuse:

384

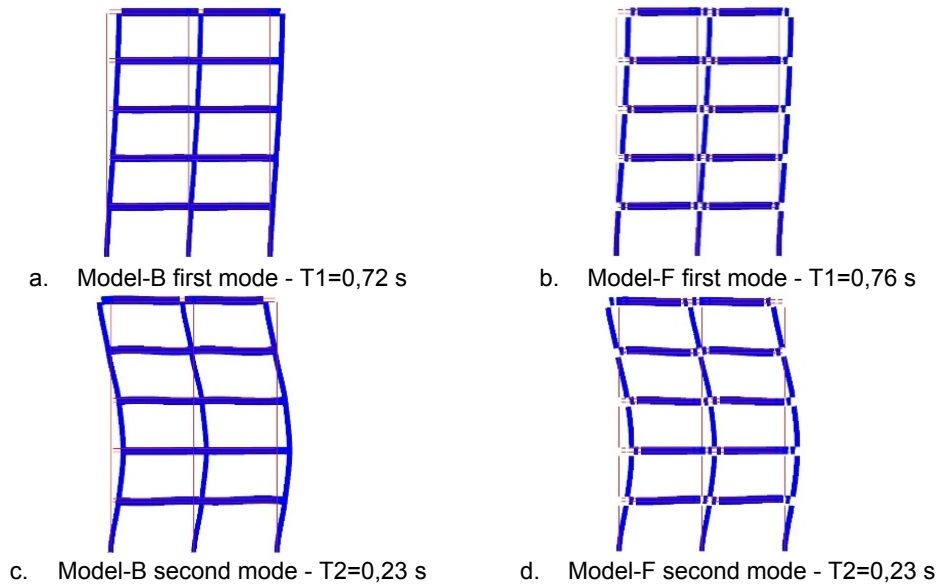
$$a = \frac{M_{max,fuse}}{M_{pl}}$$

385 Where M_{pl} is the plastic moment resistance of the composite beam, and $M_{max,fuse}$ is the
 386 maximum moment that can develop in the fuse section. The a value is set to 0.4, as suggested by
 387 (Castiglioni et al. 2012 [30]) based on the re-analysis of the experimental results. In the Model-F,
 388 the moment-rotation input diagram of device B (Table 4) has been considered. The two numerical
 389 models have been developed with the assumptions previously described in the paper, in terms of
 390 material and geometric modelling. Hence using inelastic beam elements with fiber-based
 391 formulation allowed to highlight the effectiveness of structural fuses for each structural component.
 392 First, a static analysis has been performed to obtain the initial conditions necessary for the
 393 dynamic analysis, together with a natural frequency analysis for the evaluation of modal properties

394 of the structures. The modal properties of the two analysed frames are presented herein (Table 7
 395 and Figure 18).

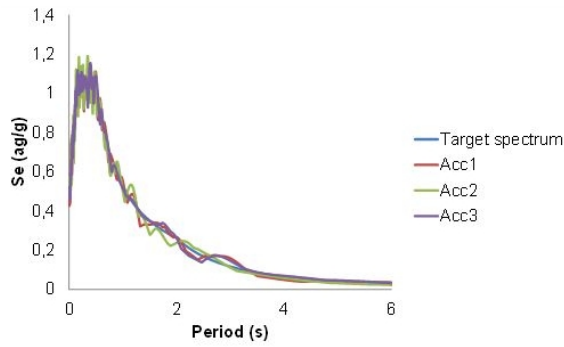
Mode	Period [sec]	PF-X [%]	Sum PF-X [%]
Model-B / First mode	0,72	84,1	84,1
Model-B / Second mode	0,23	10,2	94,3
Model-F / First mode	0,76	83,2	83,2
Model-F / Second mode	0,23	10,6	93,8

396 **Table 7 Modes of free vibration**

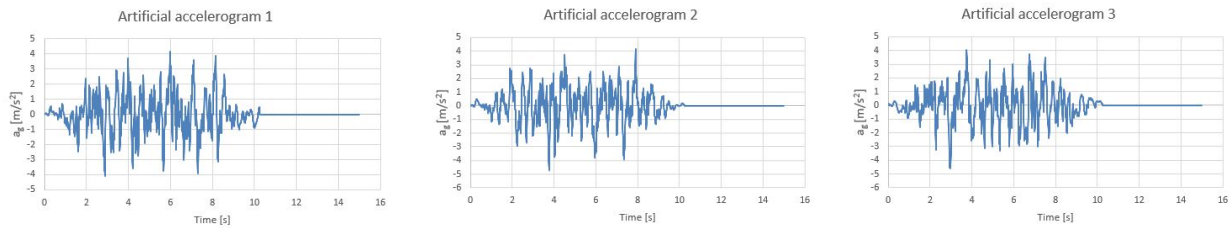


397 **Figure 18 Modes of free vibration - without structural fuses**

398 For the nonlinear dynamic analyses, three artificial accelerograms have been generated with
 399 Gosca software (Denoël V., 2001 [50]), compatible with the design criteria of the structural frame
 400 analysed by (Zona et al. 2008 [33]), by using a peak ground acceleration=0.35 g, Type 1 spectrum
 401 of EN1998-1-1, modal damping ratio=5%, and soil class B. The use of a set of accelerograms
 402 coherent with a Uniform Hazard Spectrum allows to greatly simplify the selection phase, without
 403 losing in terms of precision, as already highlighted in several past researches, such as in (Morelli et
 404 al. 2018 [51]). In order to observe residual displacements and inter-storey drifts in the structure
 405 after the seismic excitation, the accelerograms have the last 5 seconds with acceleration set to
 406 zero (The values at the end of the analysis will be referred in the results). Response spectra and
 407 the artificial accelerograms are shown in Figure 19 and Figure 20 respectively.

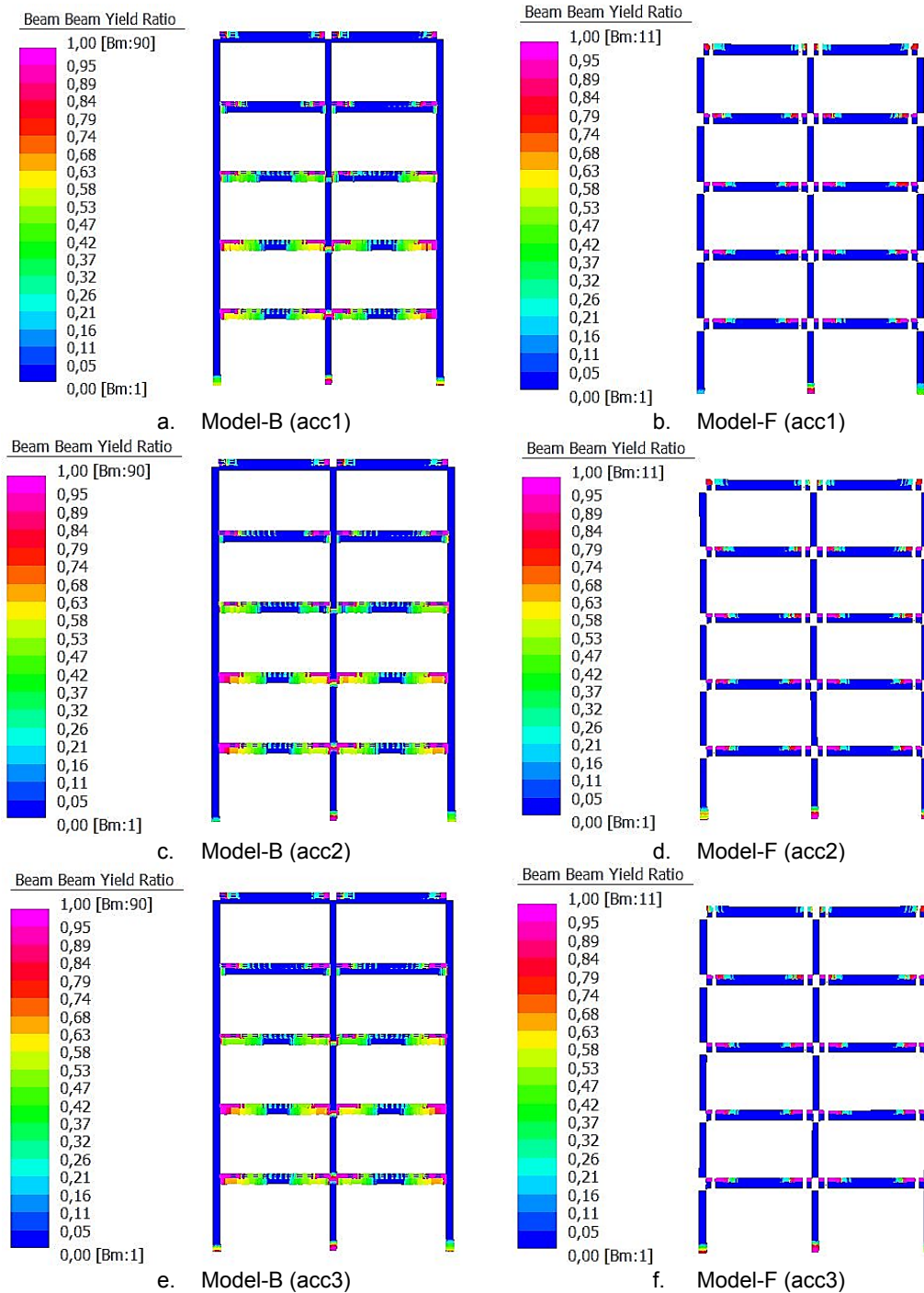


408
409 **Figure 19 Response spectra for 0,35g, Type 1, soil type B, Damping ratio 5%.**
410



411 **Figure 20 Artificial accelerograms used in the analysis.**

412 The results obtained from each three record are presented below. Since only three
413 accelerograms have been used, the performance of the systems should be interpreted considering
414 the maximum or minimum values. Figure 21 shows the nonlinear behaviour of the structural
415 members of Model-B and Model-F. The inelastic deformations observed in the structural elements
416 have been represented by means of a yield index (changing between 0 and 1.00, being 1.00 fully
417 plastic cross section). As concerns Model-B, in all three analyses, inelastic deformation takes place
418 in the columns at the base level, at the upper levels of the central column and in most of the
419 composite beam elements. These results actually confirm the principles of “capacity design”
420 approach, which represents the desired behaviour for conventional earthquake resistant structures.
421 However, the damage in the structural members caused by the inelastic deformations in this case
422 would not be easily reparable, as discussed previously in this paper. On the other hand, in Model-
423 F, inelastic deformations mainly took place in the structural fuses, while steel beams and columns
424 showed almost elastic behaviour with no significant yielding except in the column at the base level
425 and in the concrete slab due to tension cracks.



426

Figure 21 Yield ratio of two models under three accelerograms

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433

The two models have been compared also in terms of floor displacements, inter-storey drift (described as the difference in lateral displacements between two floors normalized by the story height), and base shear, which were the main indicators of the global performance (Figure 22 to Figure 25). It can be observed that Model-B suffers from non-homogeneous distribution of floor displacements and large inter-storey drifts, which indicate the presence of damage to both structural and non-structural components, and potential of a “soft-storey” mechanism. The displacement diagrams show that Model-F reaches higher displacements than those of the Model-

434 B. This is a consequence of the reduced lateral stiffness of the frame with structural fuses, which
 435 can also be observed from the results of model analysis shown in Table 7. On the other hand, after
 436 the seismic event (shown by the last 5 seconds of the time-acceleration history diagram), the
 437 residual inter-storey drifts remain insignificant for Model-F (0.05 %) (Figure 23.b,d,f), while they are
 438 in the order of 1% in case of Model-B (Figure 23.a,c,e). The negligible residual inter-storey drifts
 439 (i.e. permanent deformations), showing the re-centering capacity of Model-F, assumes a primary
 440 importance for the repair works after the earthquake.

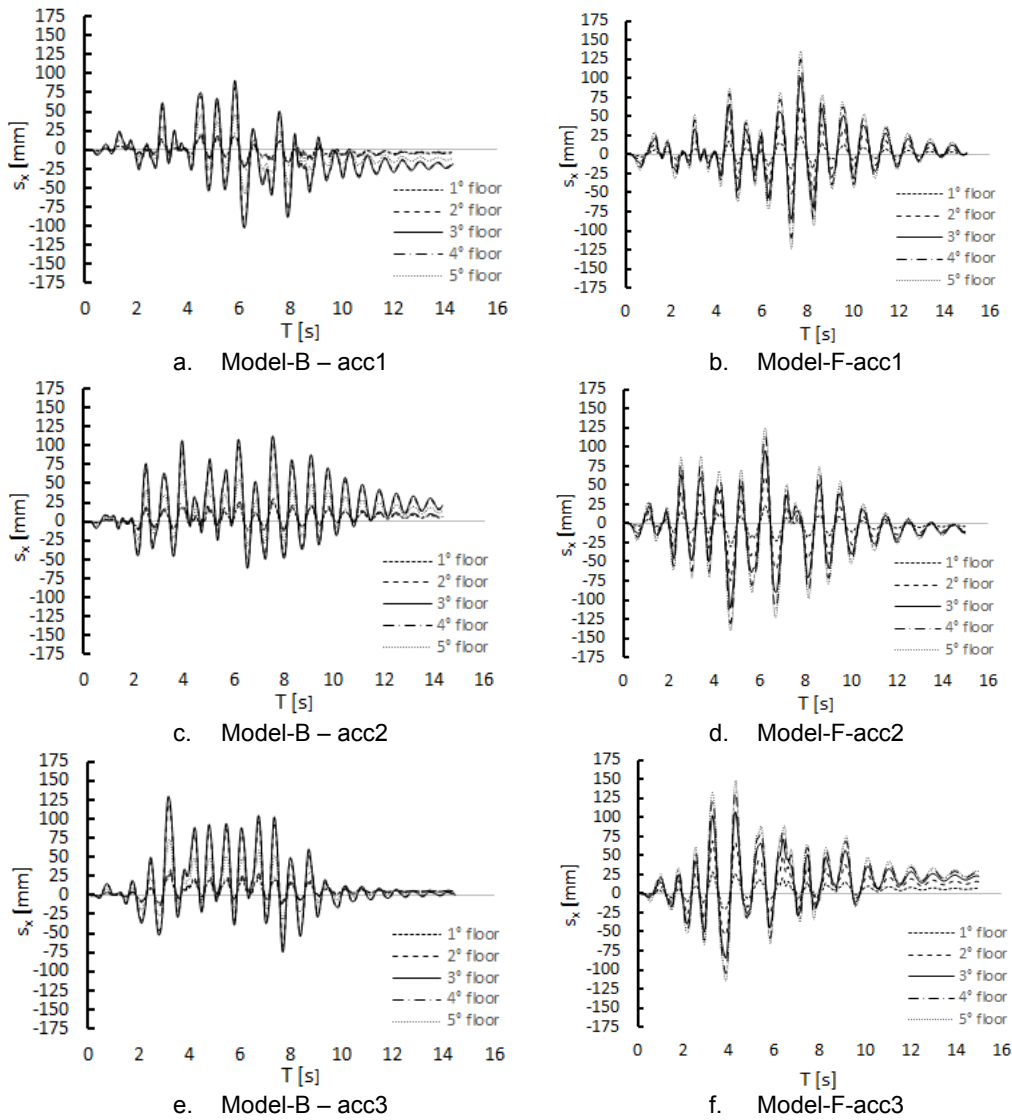
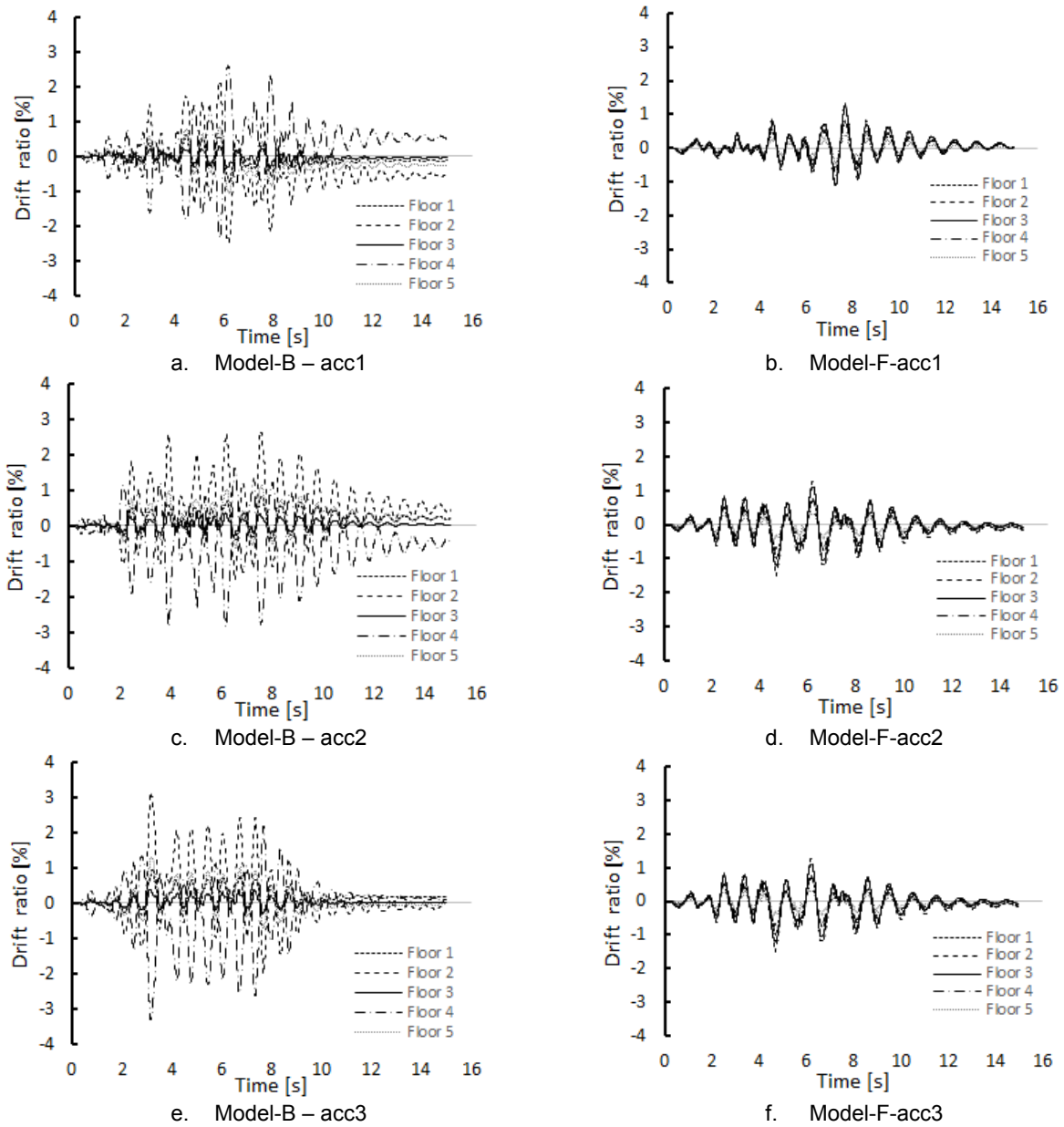


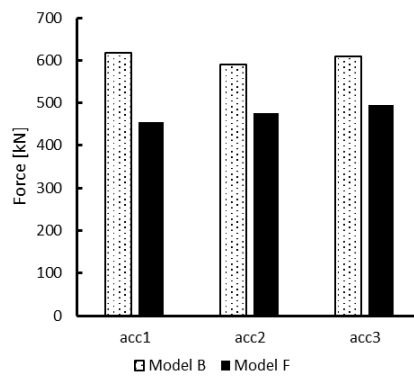
Figure 22 Floor displacements of two models under three accelerograms

441



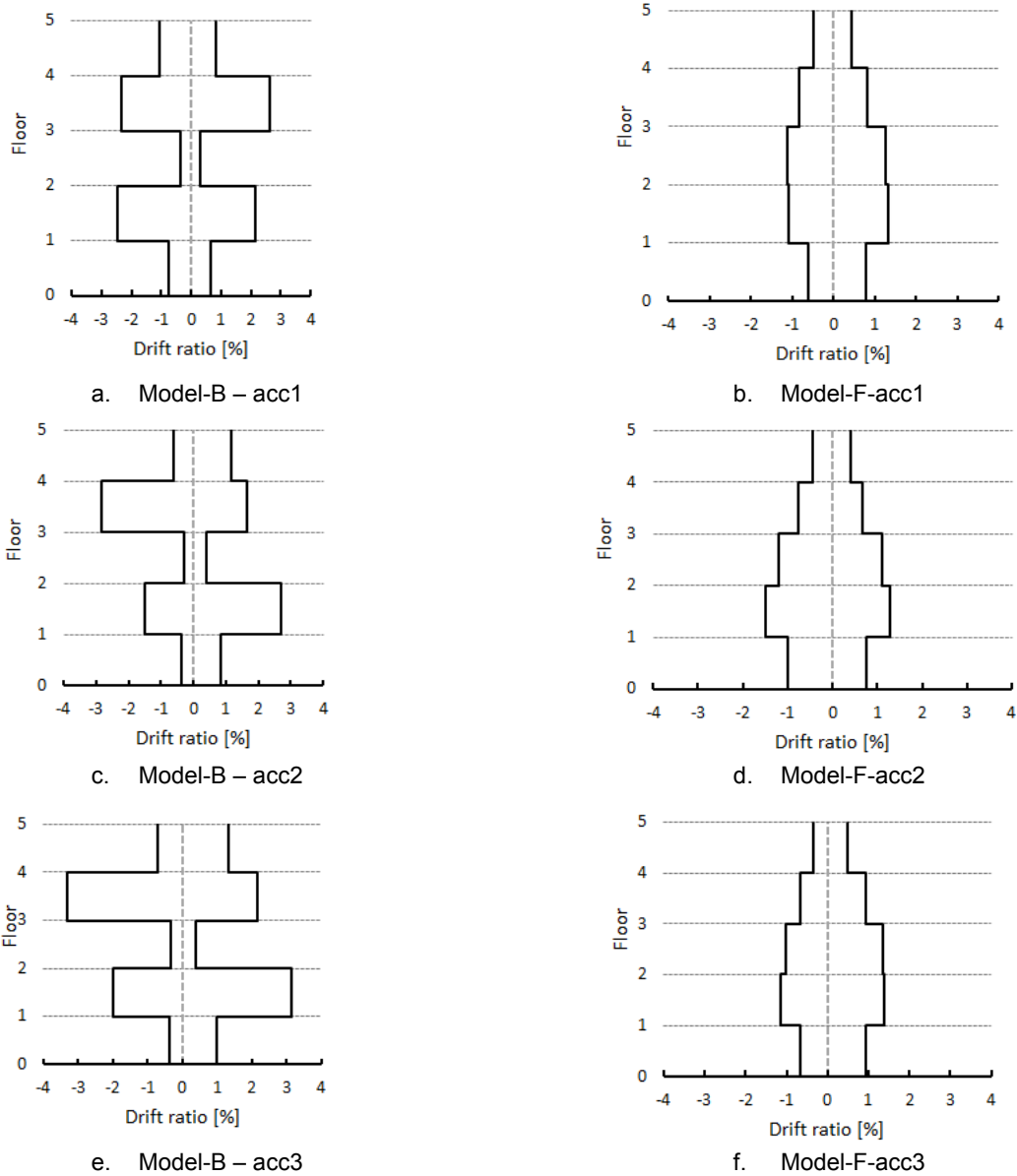
442 **Figure 23 Inter-storey drift ratio of two models under three accelerograms**

443 Figure 24 shows the reduction of maximum base shear forces that takes place in the building
 444 with structural fuses.



445

Figure 24 Maximum base shear forces comparison



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Figure 25 Peak inter-storey drift ratio of MODEL-B and FUSE under three accelerograms

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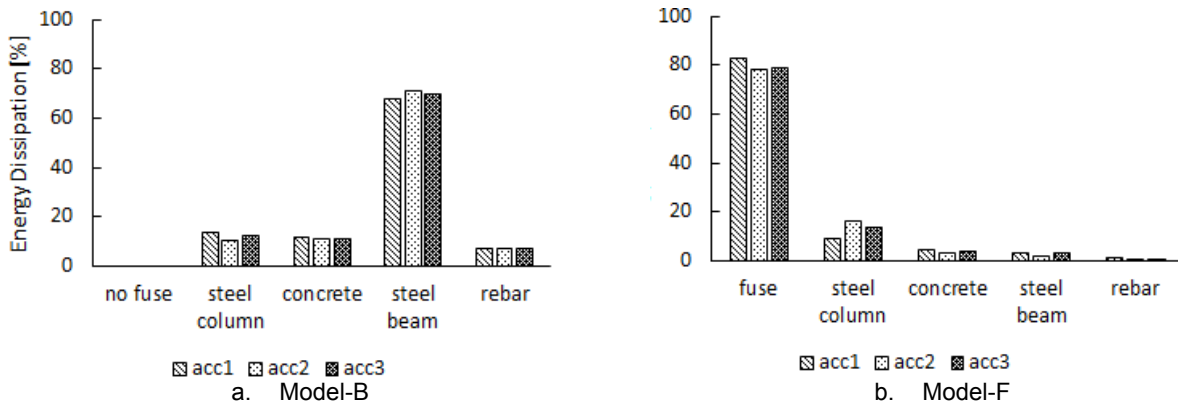
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457

Benefiting from the distributed plasticity numerical approach, it was possible to measure the energy dissipation for each component of the structural system, namely: structural fuses, steel columns and beams, concrete slab, and steel reinforcement bars. This allowed to get more insight on the redistribution of energy in the case of employing structural fuses with respect to the conventional building. The dissipated energy has been calculated based on the areas of the hysteresis diagrams of each plasticized element. Figure 26 classifies the dissipated energy in terms of their sources in the structural frame. In the case of Model-F, the majority of damage takes place in the fuses that can be easily replaced, whereas in the other elements the energy dissipation is drastically reduced. Composite slab dissipates very little energy, which is mainly due to the tension cracks. Steel reinforcement bars remain entirely elastic. In general, comparison

458 between Model-B and Model-F indicate that the latter minimizes the inelastic deformation in the
 459 main structural components. The beneficial effect of the fuse device is shown in Figure 26 as
 460 comparison of energy dissipation. Figure 26.a indicates maximum energy dissipation is mainly
 461 concentrated in the steel beam whereas, the Figure 26.b suggests that the energy dissipation
 462 predominantly takes place in the fuse device.
 463

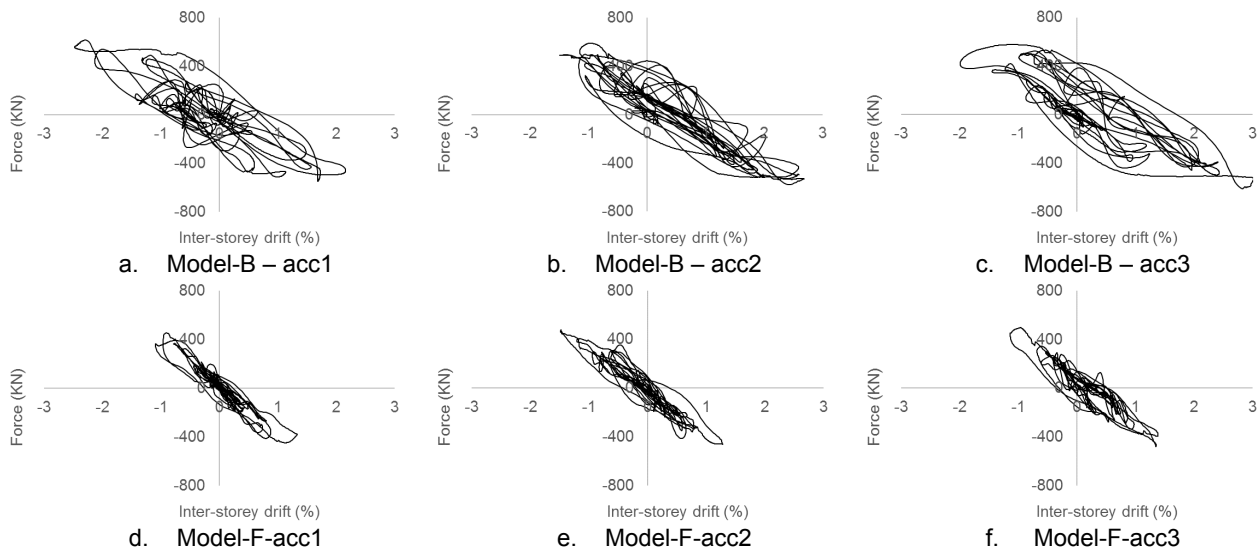


464 **Figure 26 Comparison of % energy dissipation of building components**

465

466 5 DISCUSSIONS ON THE REPARABILITY ASPECT

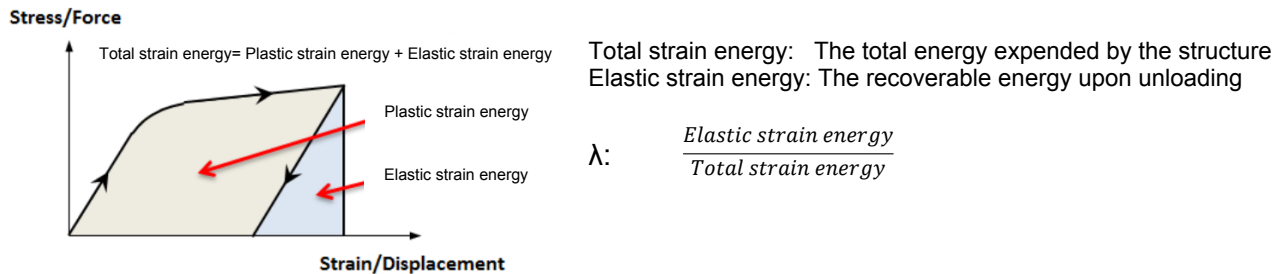
467 The results of the numerical analysis can be interpreted to show that the structural fuses
 468 would enable long-term use of the structural elements of the steel-concrete composite buildings.
 469 This improves the sustainability of these types of structures, eliminating the demolition risk after
 470 strong earthquake events. This aspect was indeed one of the long-term objectives of European
 471 Union in the steel construction sector (European Commission, 2017 [51]). From the benchmark
 472 numerical analysis, it is seen that the main objective has been achieved concentrating the seismic
 473 damage in the fuses, the rest of the structure remaining essentially elastic. This can be observed
 474 from Figure 27, where a comparison is shown between Model-B and Model-F hysteresis curves
 475 regarding the base-shear vs 2nd inter-storey drift relation under the three time-history acceleration
 476 data. While in Model-B, a large energy dissipation occurred in the 2nd storey structural elements, in
 477 Model-F, a smaller energy dissipation occurred, which is also mainly concentrated in the structural
 478 fuses present inside the frame. This evidences that the model with structural fuses is much less
 479 prone to the “soft-storey” behaviour. Furthermore, the improved re-centering capability of model F
 480 can be seen in these graphs, from the accumulation of inter-storey drifts around the origin (in
 481 contrary to the Model-B, where a shift is evident in the inter-storey drift axis).



482 **Figure 27 Force vs 2nd inter-storey drift hysteresis curves of FUSE and MODEL-B frames**

482

483 The capability of the structural fuses to absorb the seismic energy can be quantified with
 484 reference to a λ parameter which is the ratio between stored and spent energy according to the
 485 sketch shown in Figure 28 and to the total strain energy definition of (Ellyin, F. 1989 [53]). Table 8
 486 compares the percentage of the energy stored in the structural elements excluding the fuses, for
 487 the two cases. The percentage of the recoverable energy was 17% and 46%, respectively for the
 488 Model-B and Model-F. This shows the larger capability of the Model-F to restore the seismic
 489 energy resulting in a higher degree of re-centering.



490 **Figure 28 Stored vs total energy**

490

	Acc1	Acc2	Acc3	Average
λ – Model-F	0.59	0.34	0.44	0.46
λ – Model-B	0.19	0.16	0.16	0.17

491 **Table 8 λ values for two cases**

491

492 Thanks to this smart redistribution of damage, repair work of such a frame could be achieved
 493 easily and efficiently, as was proven during the experimental tests (Figure 29). Replacement of the
 494 fuses after testing up to failure was easily performed by two workmen in approximately 30
 495 min/fuse. This tested replacement approach can be also applied in multi-storey buildings. Since the
 496 structural elements are not significantly damaged after severe loading conditions, an extension of
 497 their lifetime is a direct consequence as well as an increased resilience of the building.



Figure 29 Repair operation after the full-scale tests

498
499

500 These observations have been obtained in a laboratory environment, with ideal working
501 conditions that may not reflect the construction practice. In order to prove the efficacy of the
502 system in the real environment, two authors of this paper (Kanyilmaz and Castiglioni) have been
503 coordinating an EU-RFCS pilot-demonstration project “DISSIPABLE”, which started in June 2018.
504 In this project, shake table testing of half scaled 3D buildings under real three-dimensional seismic
505 excitations will be performed at the Laboratory for Earthquake Engineering (LEE) of National
506 University of Athens (NTUA). The following objectives of this project will be complementary to the
507 conclusions of this paper:

- 508 • The adequacy of repair measures of the pilot buildings will be demonstrated.
- 509 • The ability of the repaired pilot buildings to continue withstanding other strong earthquakes
510 events will be demonstrated.
- 511 • Several non-symmetric arrangements of the resisting elements (stiffness eccentricity) or non-
512 symmetric distribution of masses which produce a torsional response on the global system will
513 be investigated on the pilot buildings.
- 514 • Design guidelines will be established based on the results of the experiments and the
515 numerical analyses. The proposed design methodology will be suitable for use in everyday
516 practice.
- 517 • A systematic “assembly, removal, repair and reassembly” operative procedure for the
518 dissipative devices will be developed in order to facilitate their adoption and application in
519 current practice.
- 520 • Worked examples will be drafted for practical use.
- 521 • Case studies will be investigated in order to quantify recyclability and economic aspects.
- 522 • A clear comparison will be made between conventional and innovative building costs.

- 523 • Environmental and economic life cycle impacts of the fuses will be calculated and compared
524 with existing functional equivalent solutions.
- 525 • A comparative life cycle balance will also be performed for the whole building, including non-
526 structural elements, in order to quantify environmental and economic savings of an entire real
527 building due to absence of damage in both structural and non-structural elements. These
528 comparative studies will serve to assess the effectiveness of various loss-reduction measures
529 and determine why and how the proposed system is more resilient than others.
- 530

531 **6 CONCLUSIONS**

532 The popularity of dissipative building components has greatly increased within the last two
533 decades. The introduction of these components aims to dissipate the seismic energy through their
534 plastic deformation, leaving main structural elements damaged at a low level. The focus has been
535 given so far to maximize the dissipation capacities of these components, and reparability aspect is
536 mostly neglected. Since it is crucial to restore buildings and its functions as quickly as possible
537 after an earthquake, it is strongly advisable to develop structural systems that are simple to repair.
538 Besides this, most of the existing studies regarding the dissipative components in steel buildings
539 ignore the presence of the reinforced concrete slab.

540 This paper presented a numerical study on “bolted dissipative beam splices”, also called as
541 “structural fuses” developed in the European Research Project “FUSEIS”. When they are
542 introduced in steel-concrete composite moment resisting frame buildings, the earthquake damage
543 concentrates mainly in the fuses, which can be easily and inexpensively replaced after strong
544 seismic events. The seismic performance of a benchmark steel-concrete composite frame model
545 (Zona, et al., 2008) has been studied with and without structural fuses, taking explicitly into account
546 the reinforced concrete slab in the numerical models. These models have been developed using
547 fiber-based distributed plasticity approach and calibrated based on the experiments provided in the
548 literature and performed in the FUSEIS research project.

549 The energy dissipated by each component of a steel-concrete composite frame has been
550 quantified, showing its redistribution for both conventional and innovative cases. Results showed
551 that the structural fuses improved the seismic performance in terms of inter-storey drift, energy
552 dissipation and re-centering features. The damage has been concentrated mainly on these
553 connection components, whereas the other frame members suffered very low damage.
554 Conventional frame suffered from large inter-storey drifts and non-homogenous distribution of floor
555 displacements, indicating damage to both structural and non-structural elements, furthermore a
556 high risk of soft-storey mechanism. In case of the building with the structural fuses, these were not
557 present. The residual inter-storey drifts were minimized down to 0.05 % thanks to the structural

558 fuses, from 1% developed in the case of conventional frame, which is an indicator of the possibility
559 of limited repair works after a seismic event.

560

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